

COMPUTATIONAL
GEOMECHANICS

To see and compute as never before in granular materials: the avatar concept

José E. Andrade

Mechanical & Civil Engineering

Keynote IS-Cambridge, UK, September 2014



GRAIN SCALE

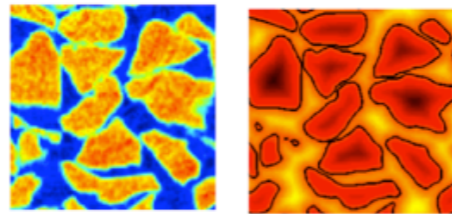
MULTISCALE

CONTINUUM SCALE

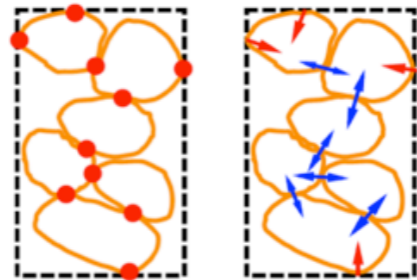
TOMOGRAPHY



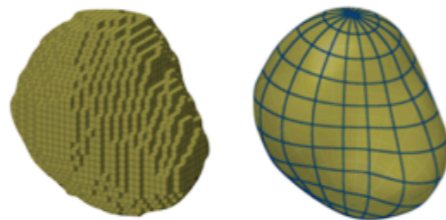
LEVEL-SET



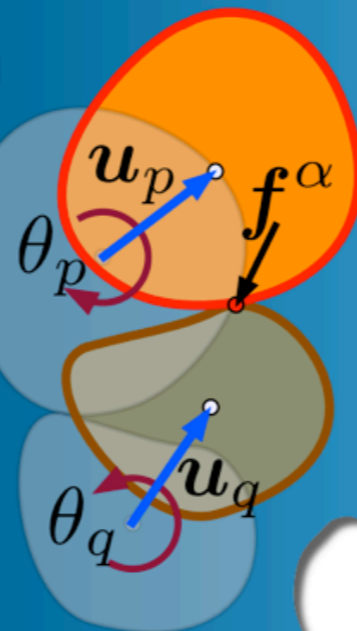
GEM



NURBS



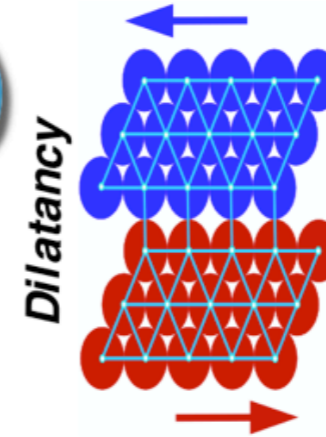
KINEMATICS



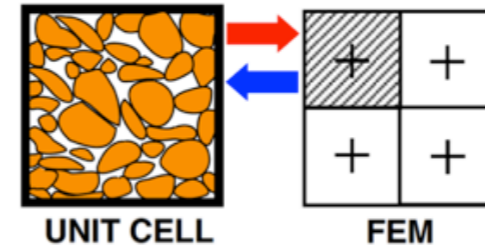
FORCES

THEORY

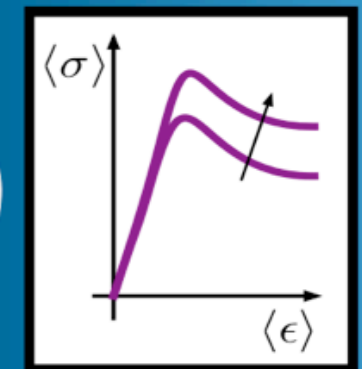
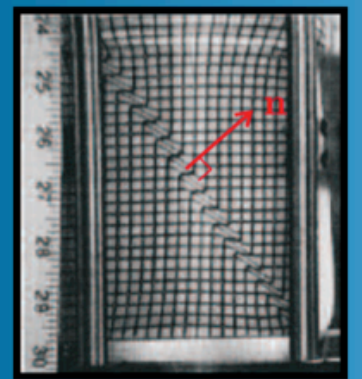
Friction



COMPUTATION



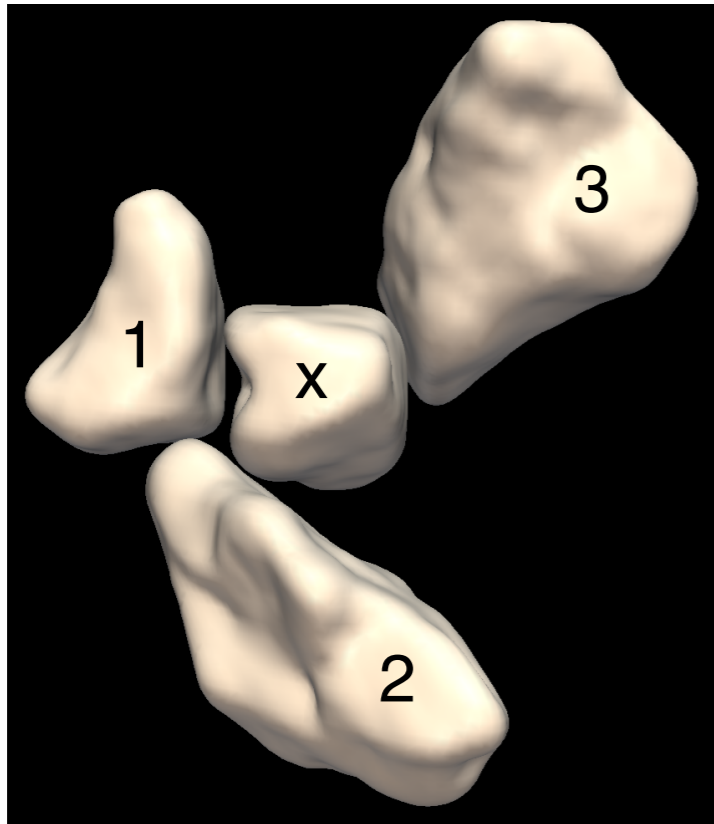
EXPERIMENTS



SIMULATION

PLASTICITY

FOCUS AREAS



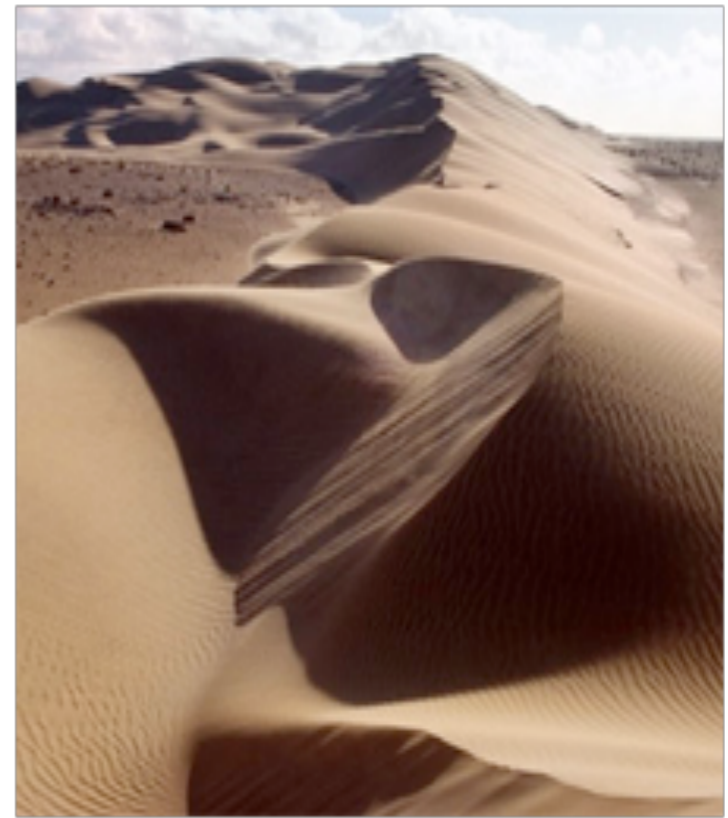
Grain Scale (~mm)
Newtonian Mechanics

$$F = ma$$

discrete

concept: force F

Multiscale



Continuum Scale (>m)
Continuum Mechanics

$$\nabla \cdot \sigma = \rho a$$

average, bulk

concept: stress σ

Concept of Force

Isaac Newton: 1643-1727

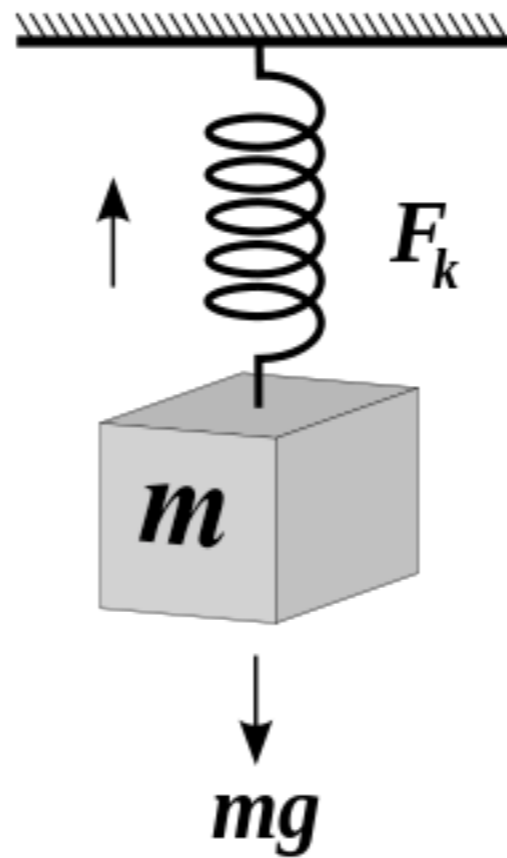


$$F = ma$$

Robert Hooke: 1635-1703



$$F = k\delta$$



Concept of Force

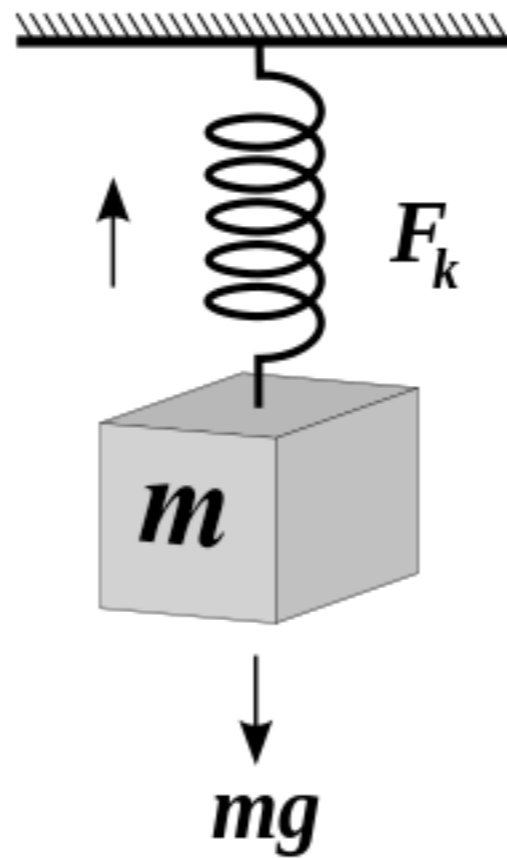
Isaac Newton: 1643-1727

Robert Hooke: 1635-1703



$$F = ma$$

force relates to momentum



$$F = k\delta$$

Concept of Force

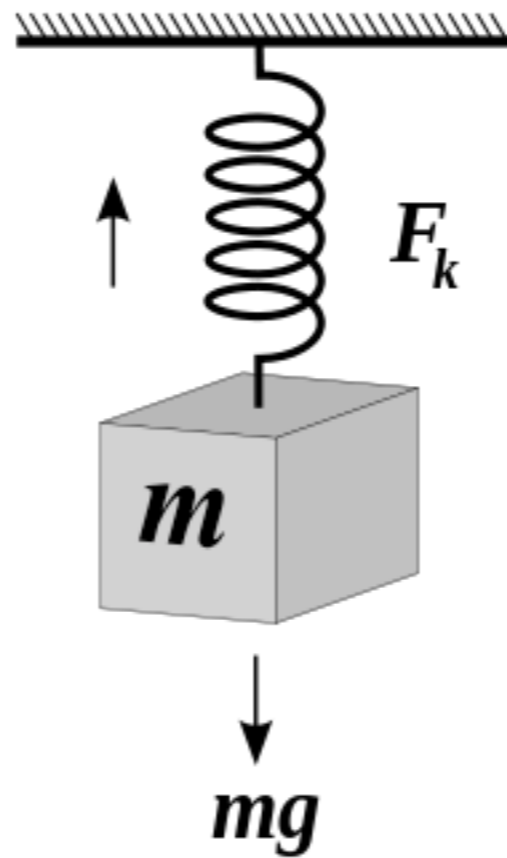
Isaac Newton: 1643-1727

Robert Hooke: 1635-1703



$$F = ma$$

force relates to momentum



$$F = k\delta$$

ceiinossstuv

Concept of Force

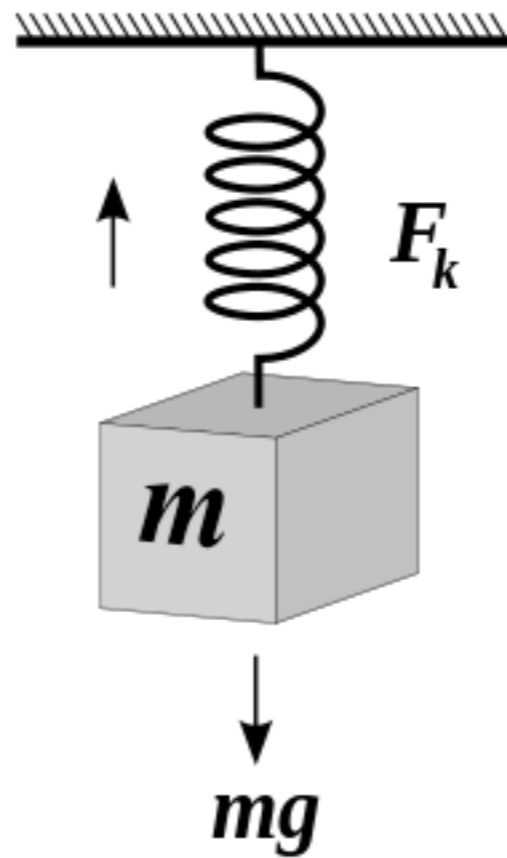
Isaac Newton: 1643-1727

Robert Hooke: 1635-1703



$$F = ma$$

force relates to momentum



$$F = k\delta$$

Concept of Force

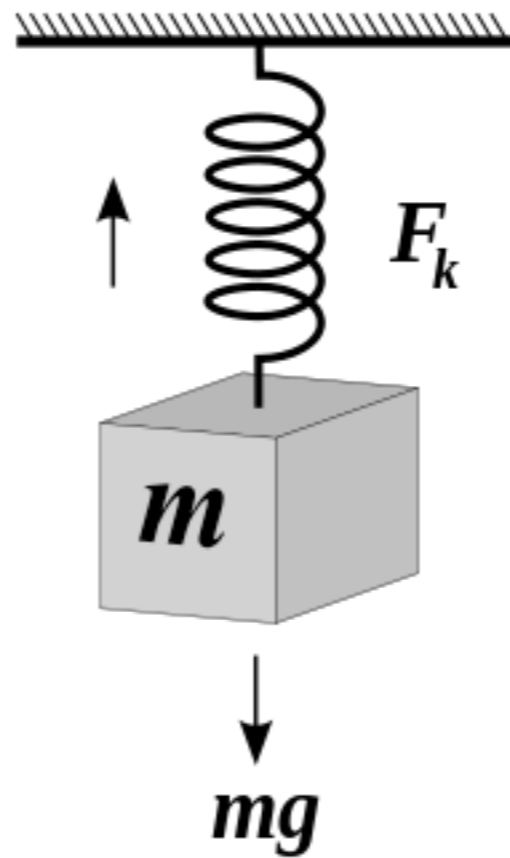
Isaac Newton: 1643-1727



$$F = ma$$

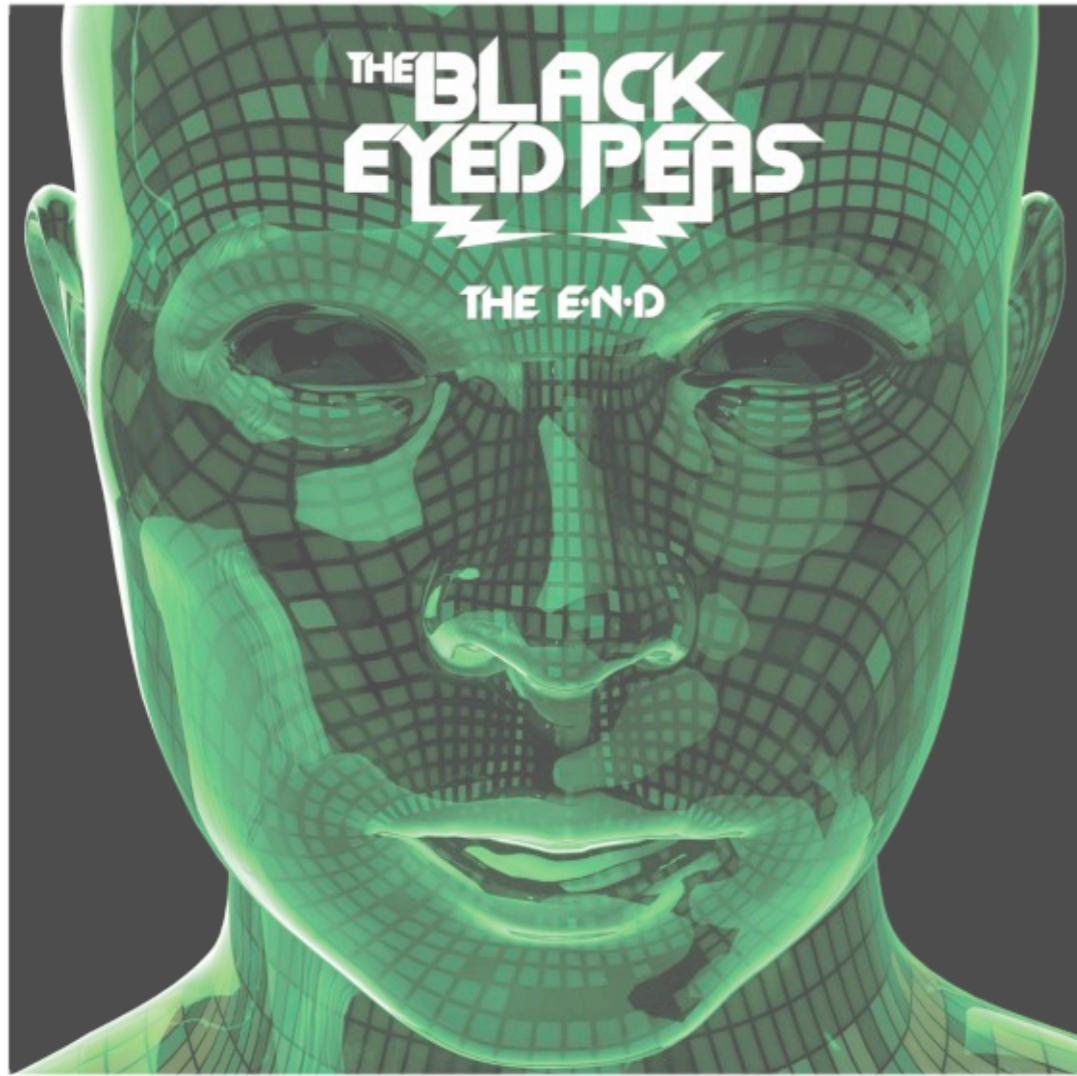
force relates to momentum

Robert Hooke: 1635-1703

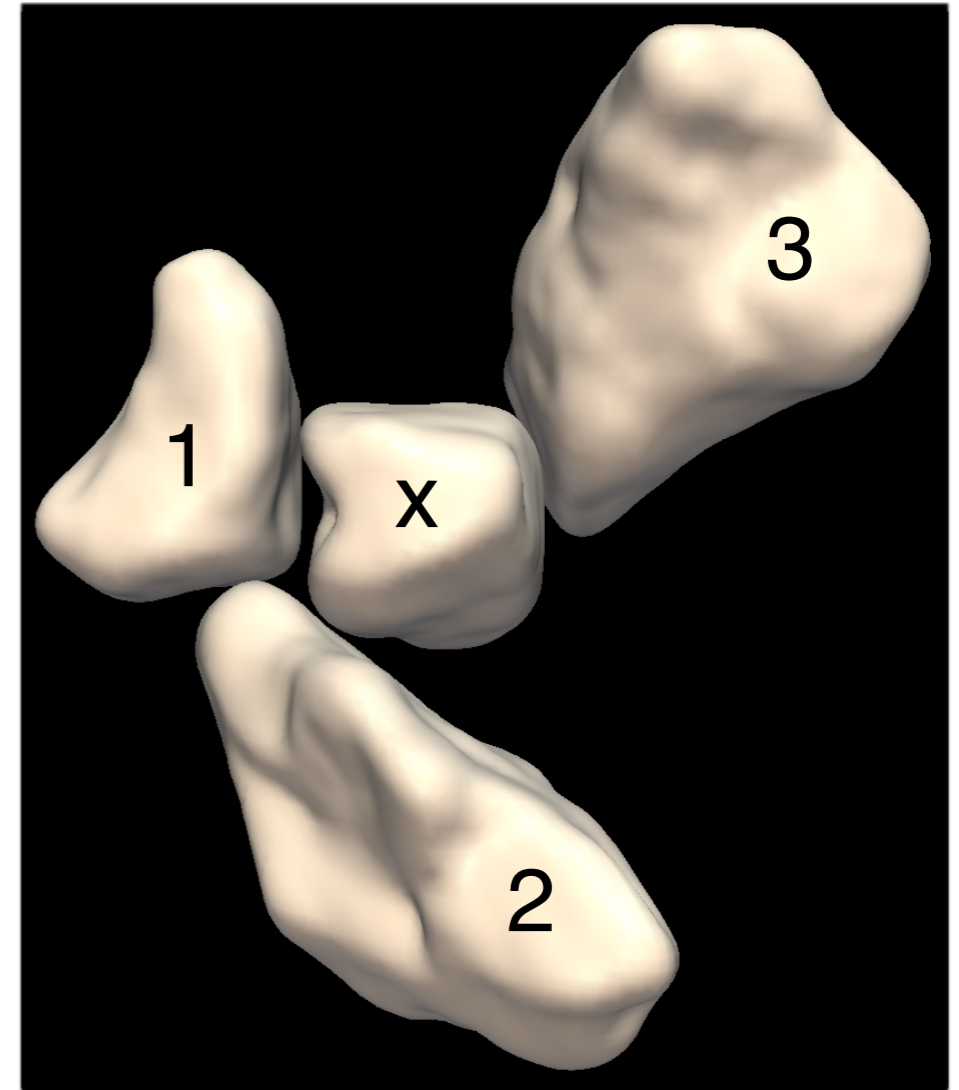


$$F = k\delta$$

ut tensio sic vis



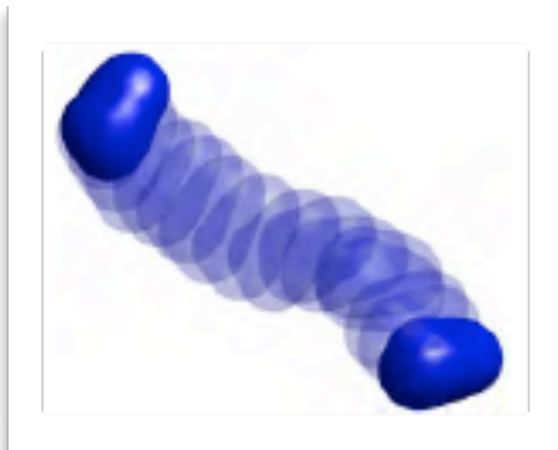
physical features
behavior



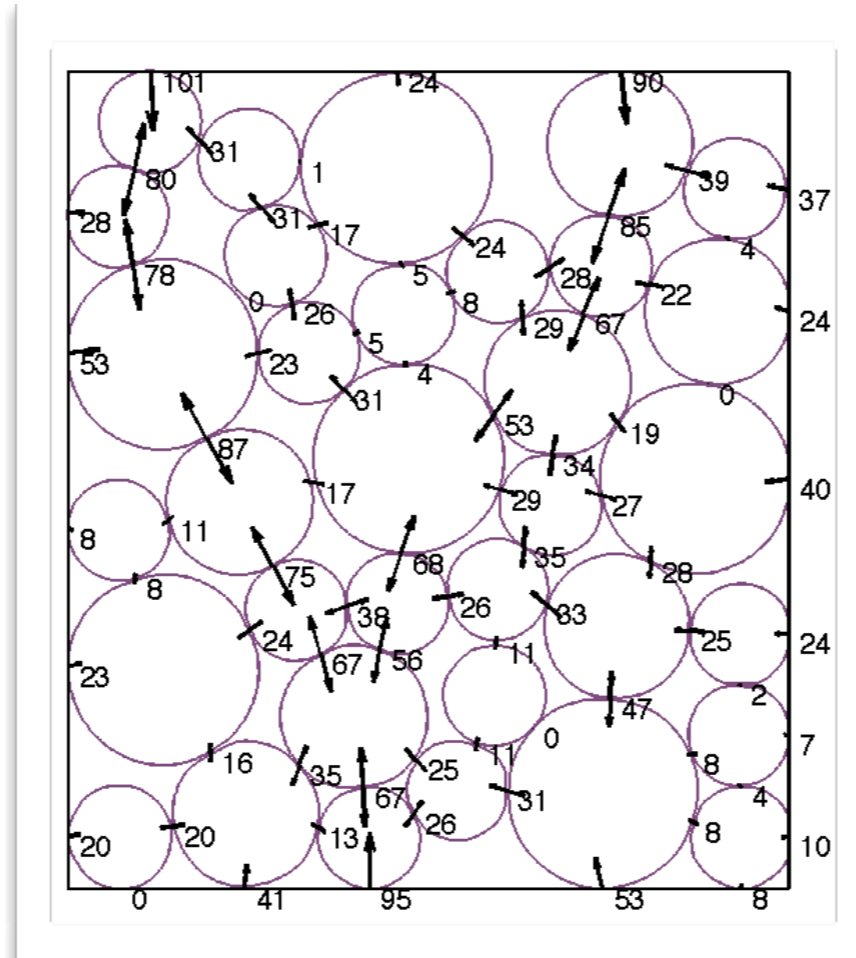
morphology = shape
behavior = **kinematics**
& **forces**

The avatar concept

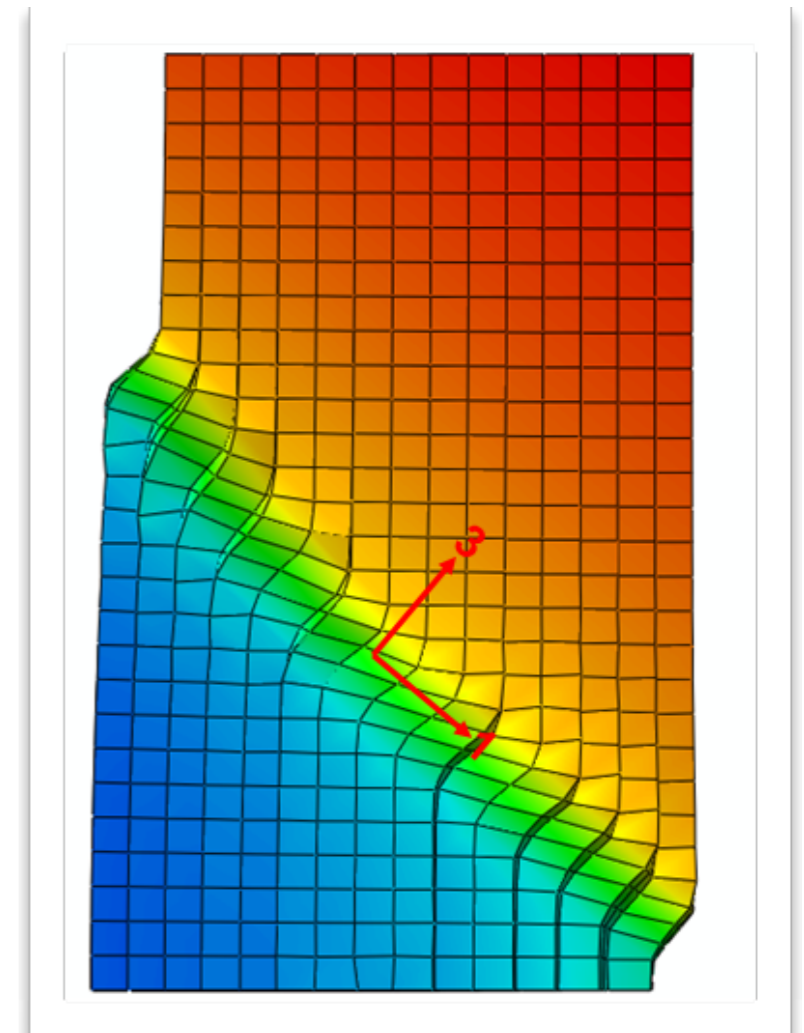
Today's menu: Avatar



measuring
kinematics

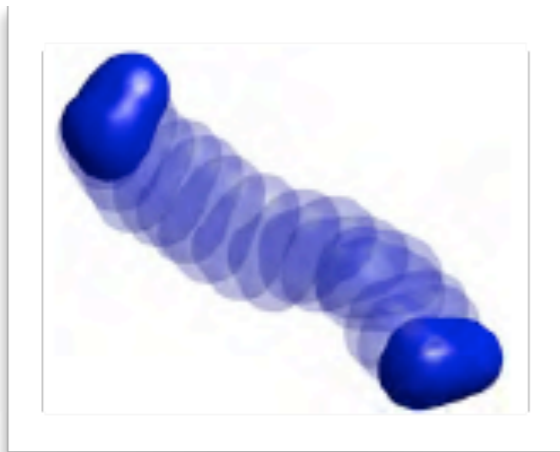


measuring
forces

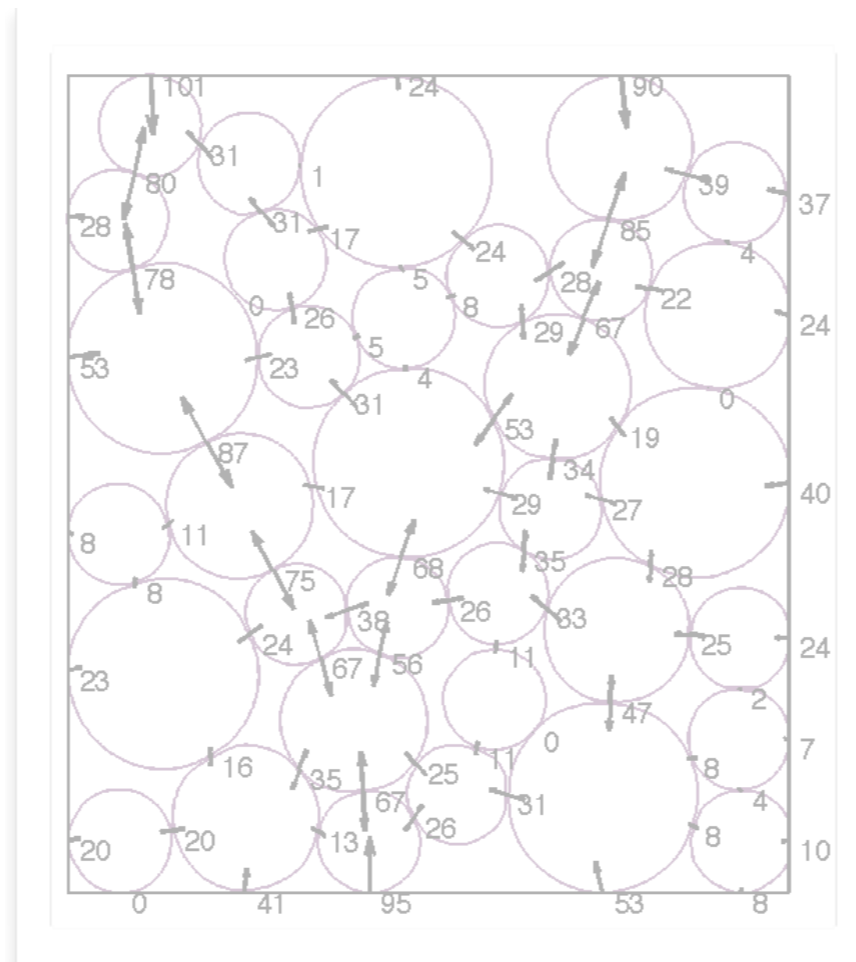


predicting
behavior

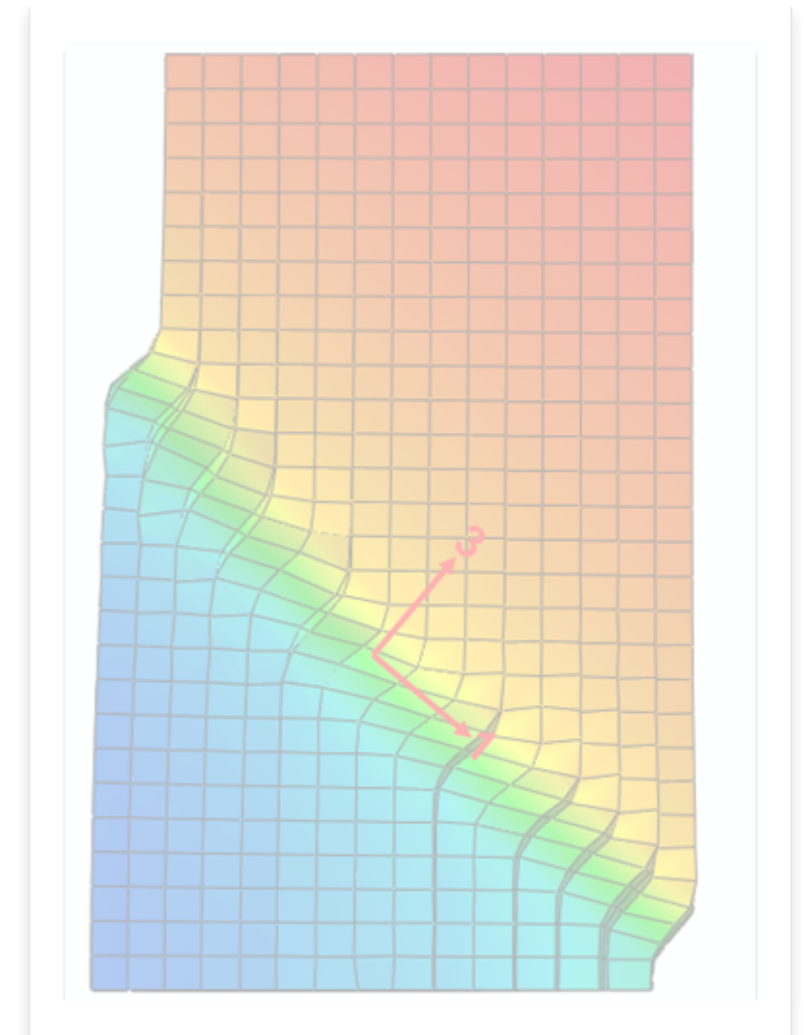
Today's menu: Avatar



measuring
kinematics



measuring
forces



predicting
behavior

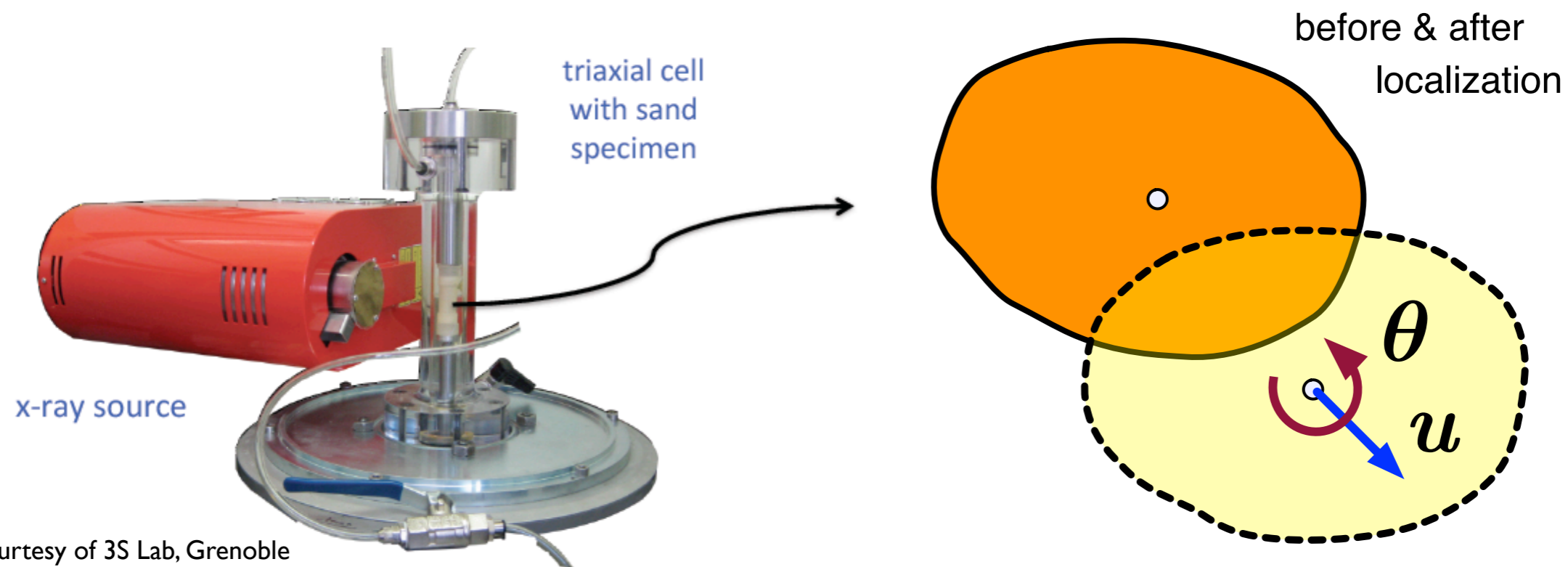
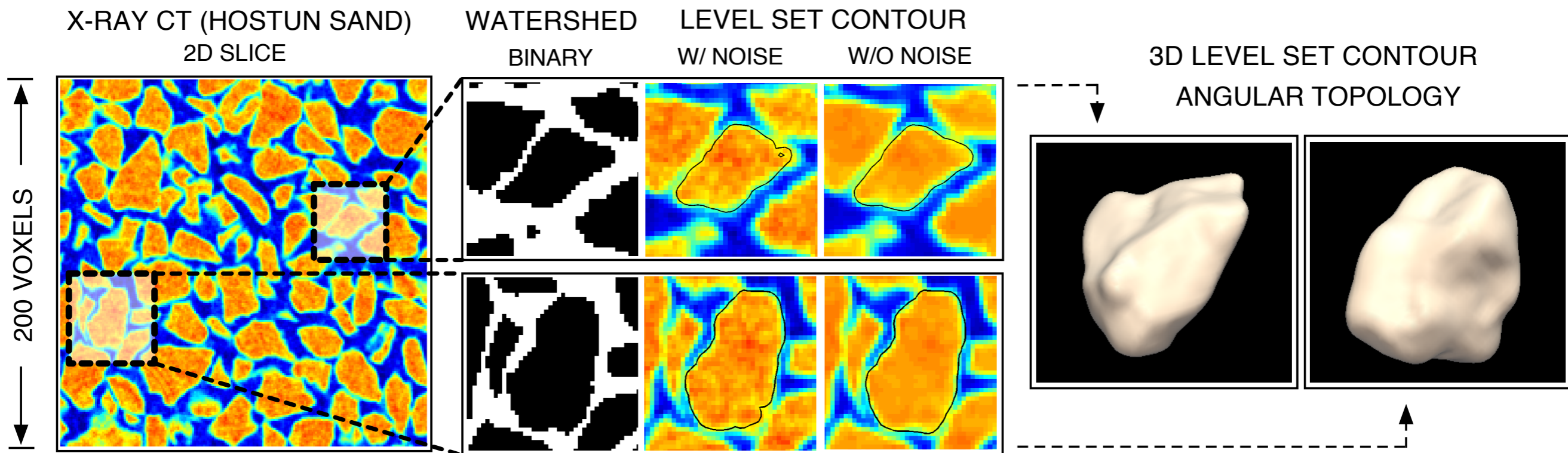


Image courtesy of 3S Lab, Grenoble

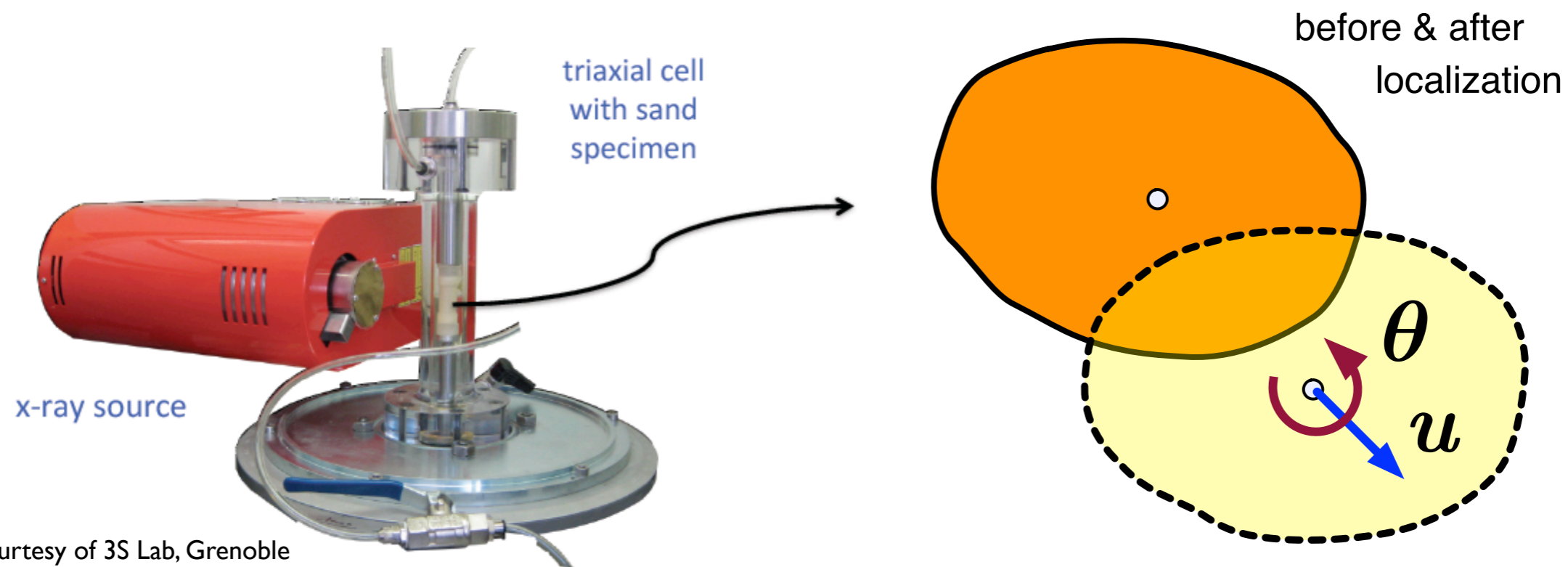
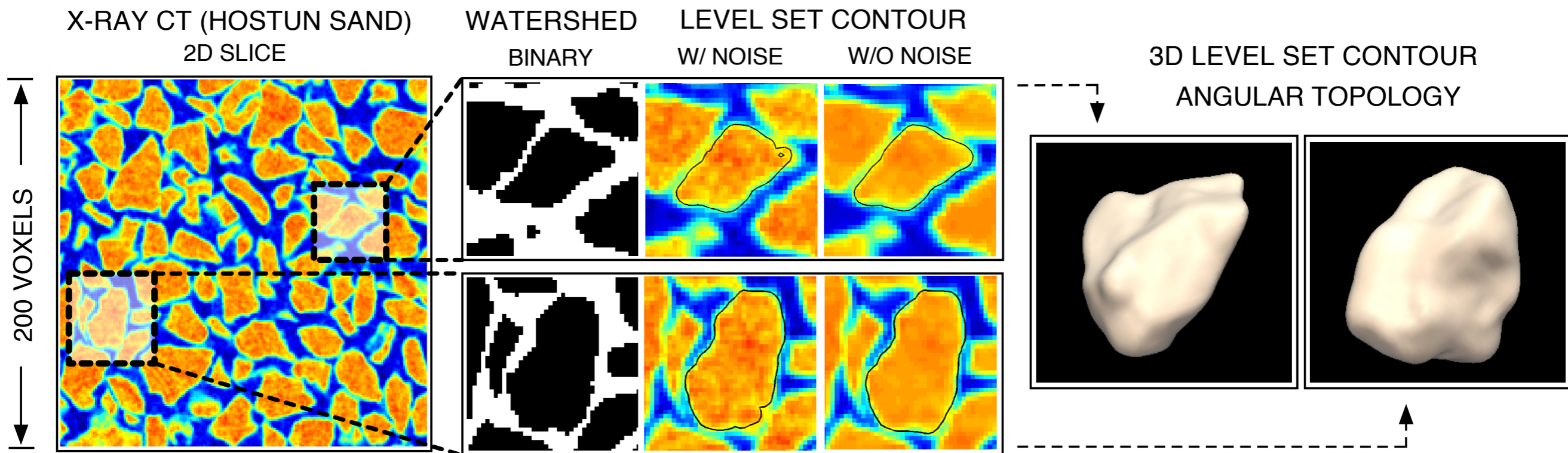
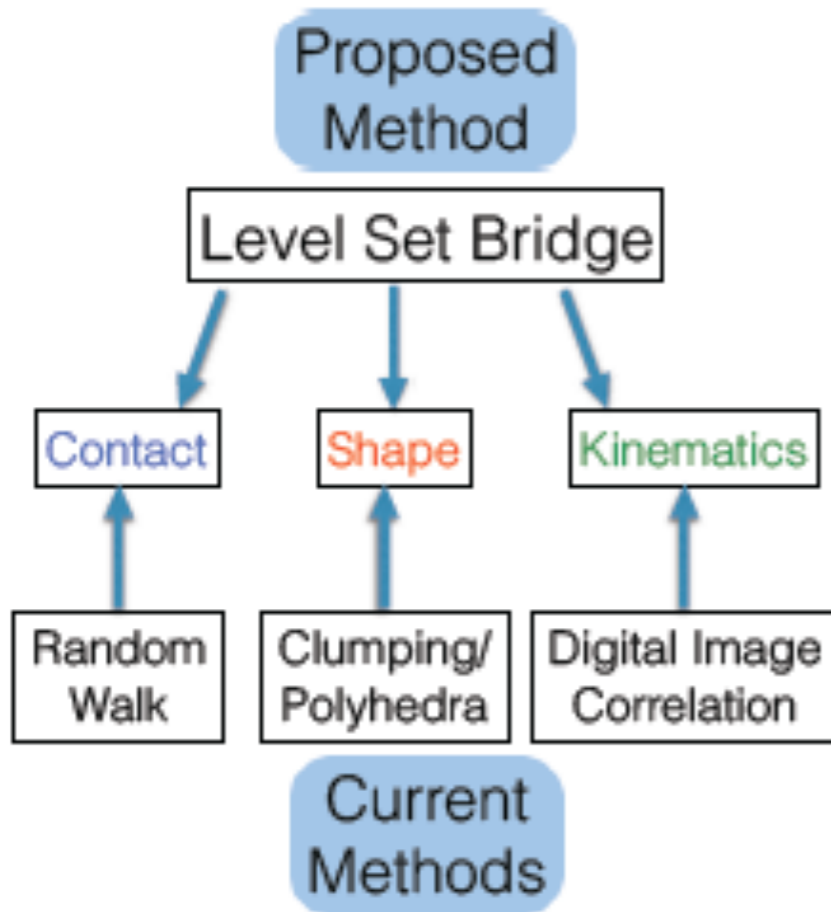


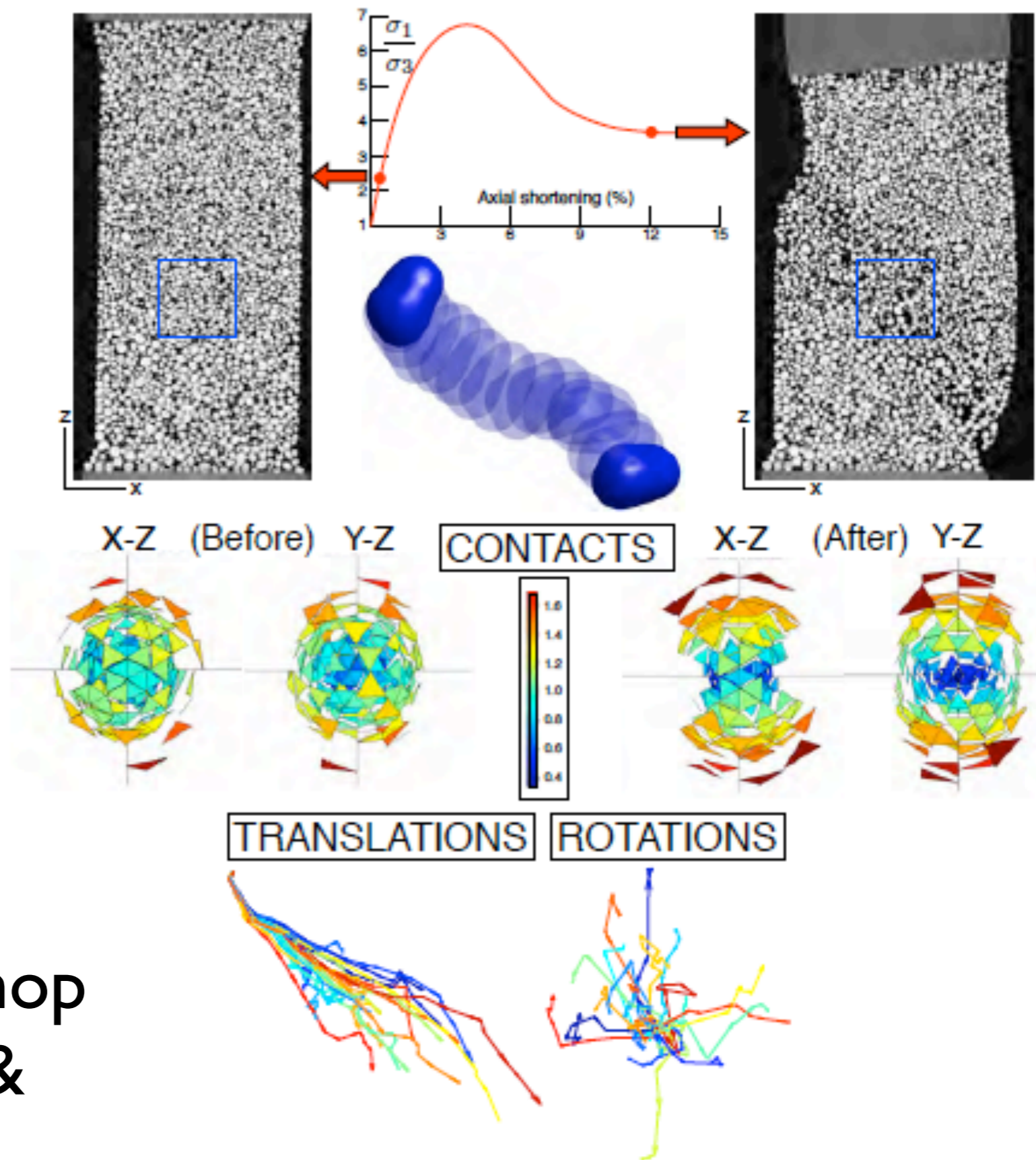
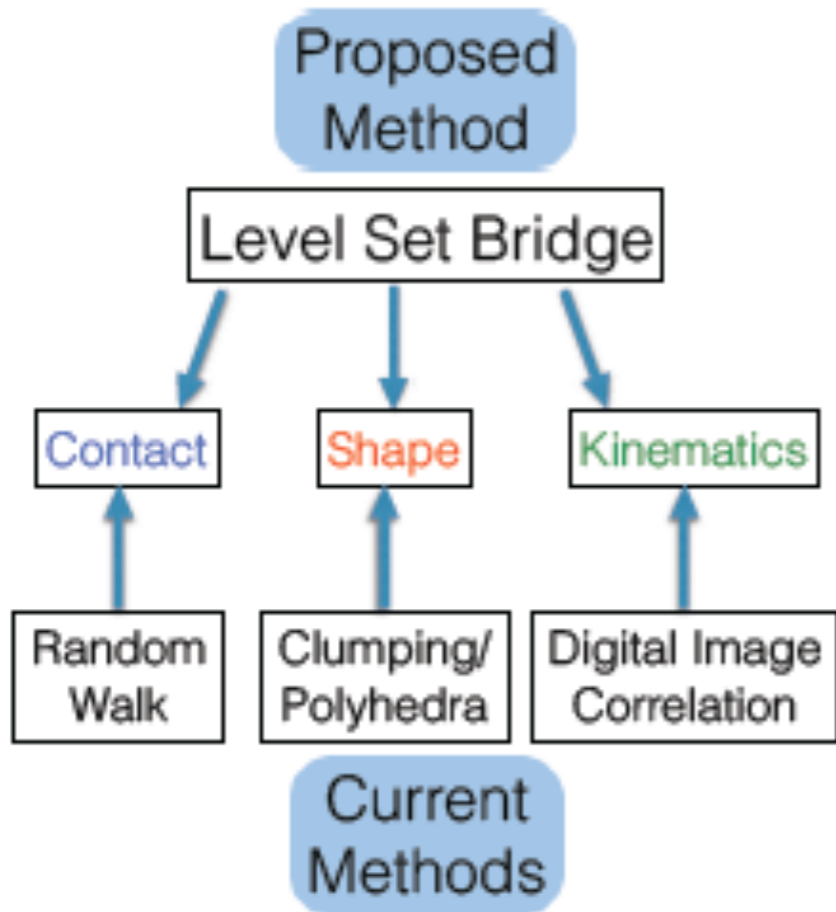
Image courtesy of 3S Lab, Grenoble

experimentally capture morphology & kinematics

Level-set: a one-stop shop
for characterization &
computations

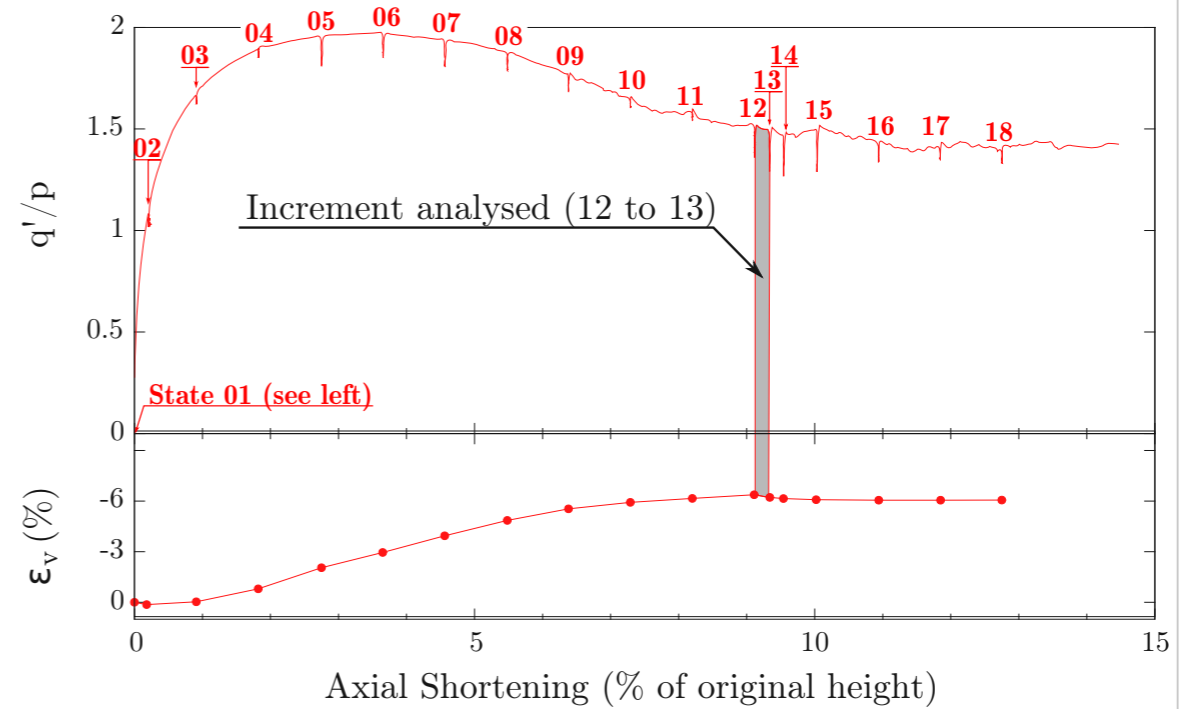
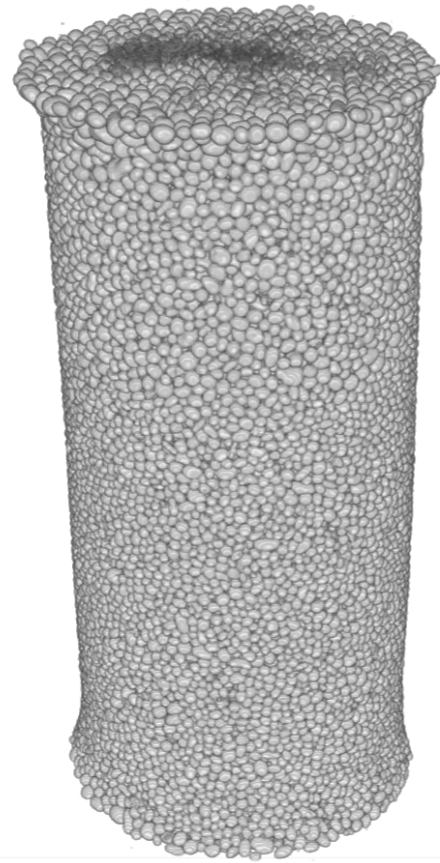


Level-set: a one-stop shop
for characterization &
computations

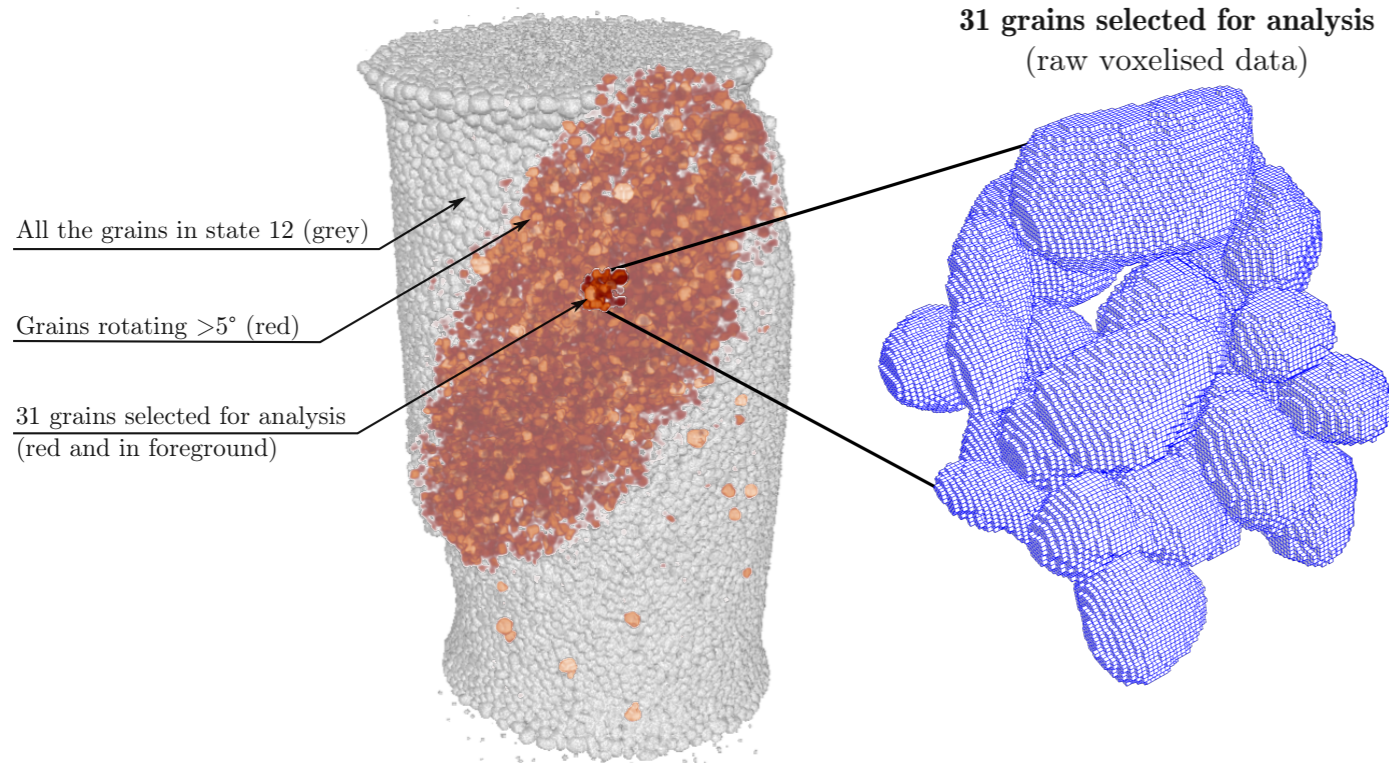


Level-set: a one-stop shop for characterization & computations

Macro-micro experimental data

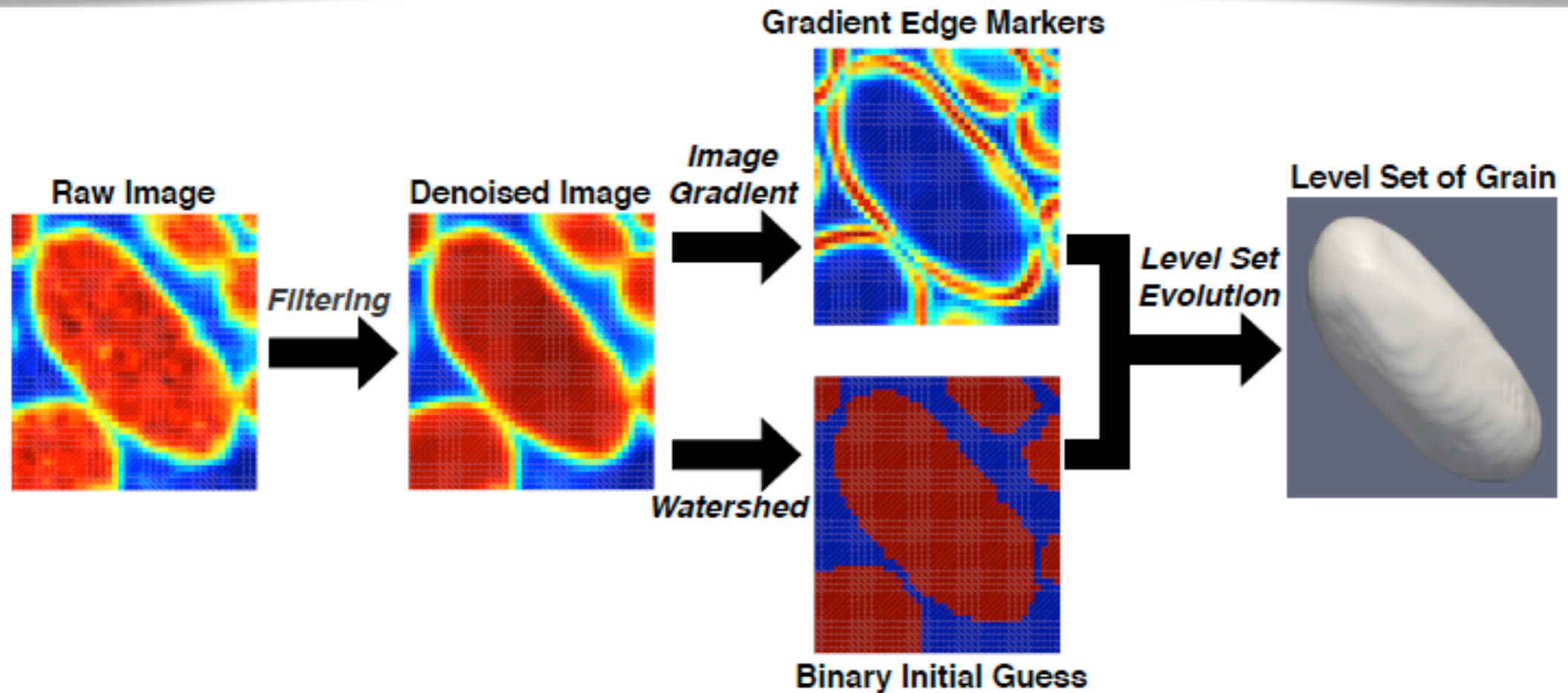
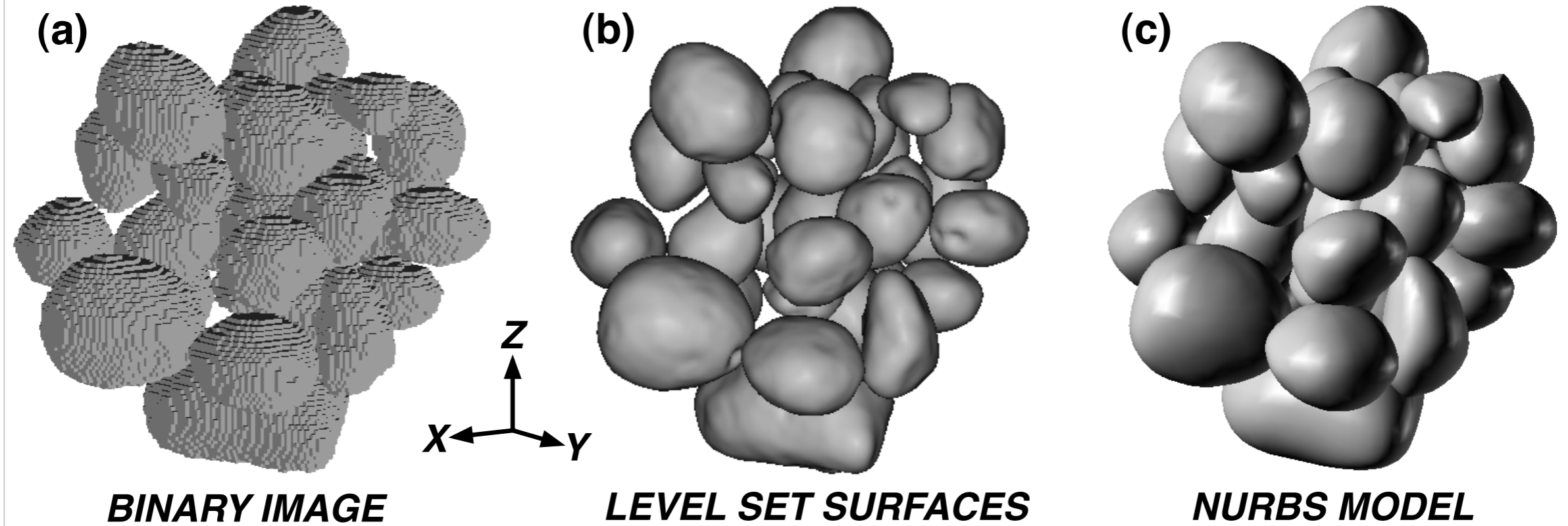


3D visualisation of sample in state 12
(9.11% axial shortening)



Macro-micro experimental data @ failure

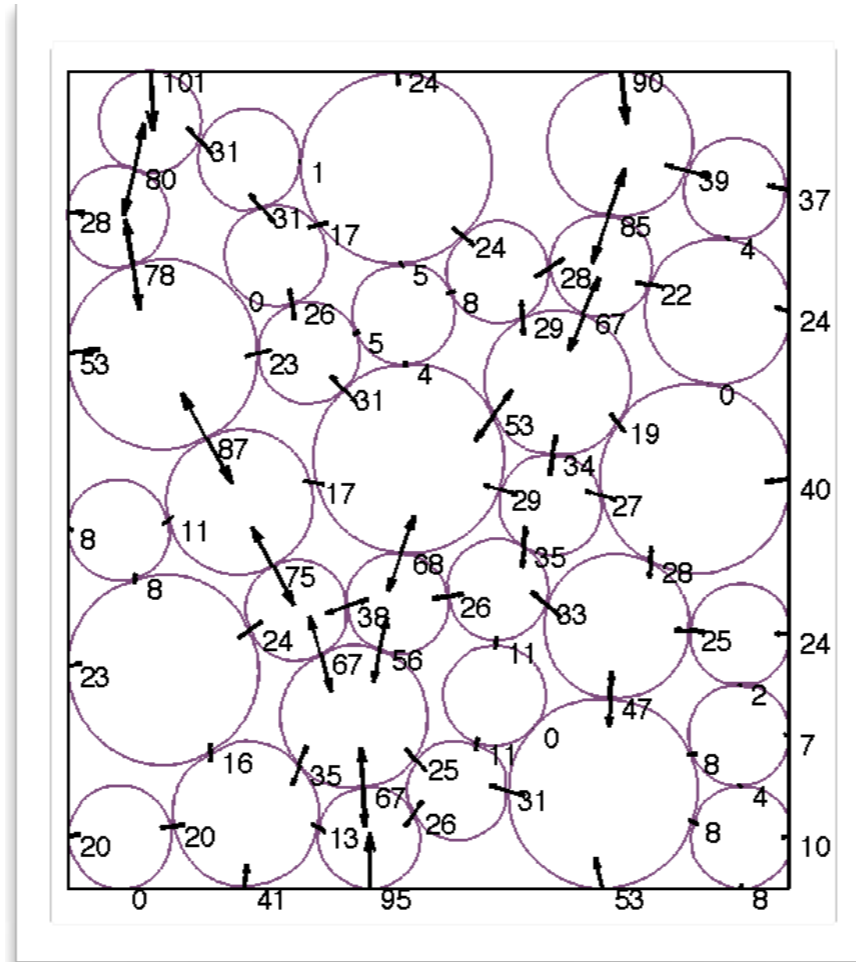
Construct computational model of real 3D particles



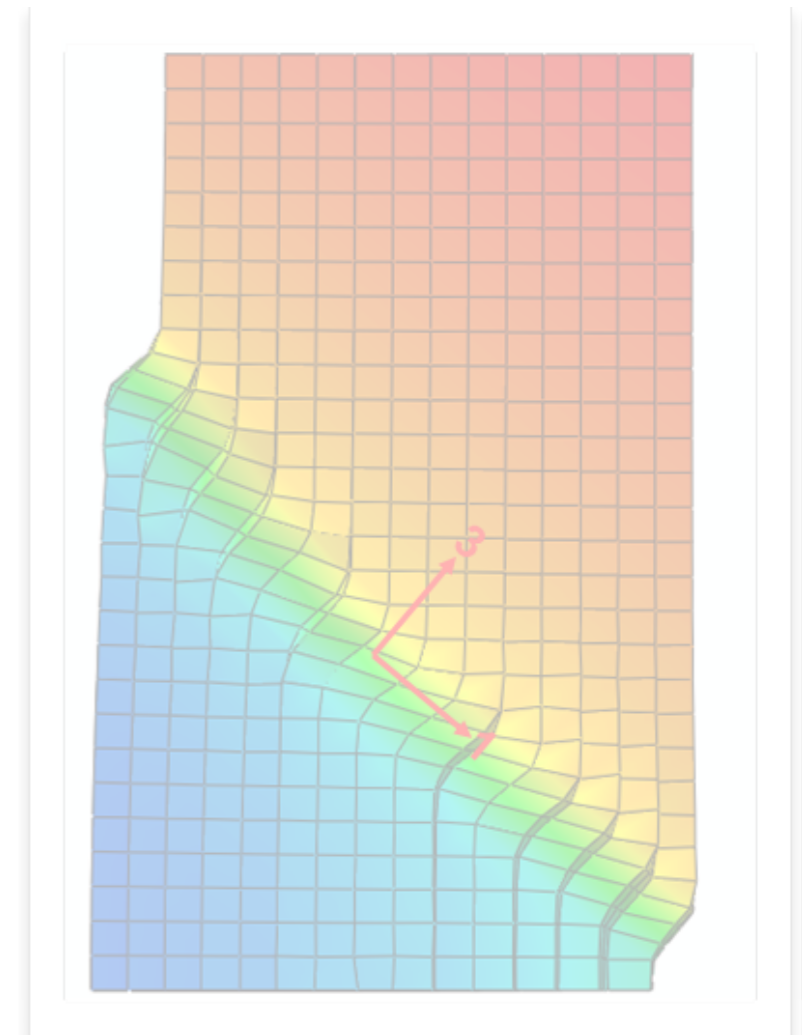
Today's menu: Avatar



measuring
kinematics



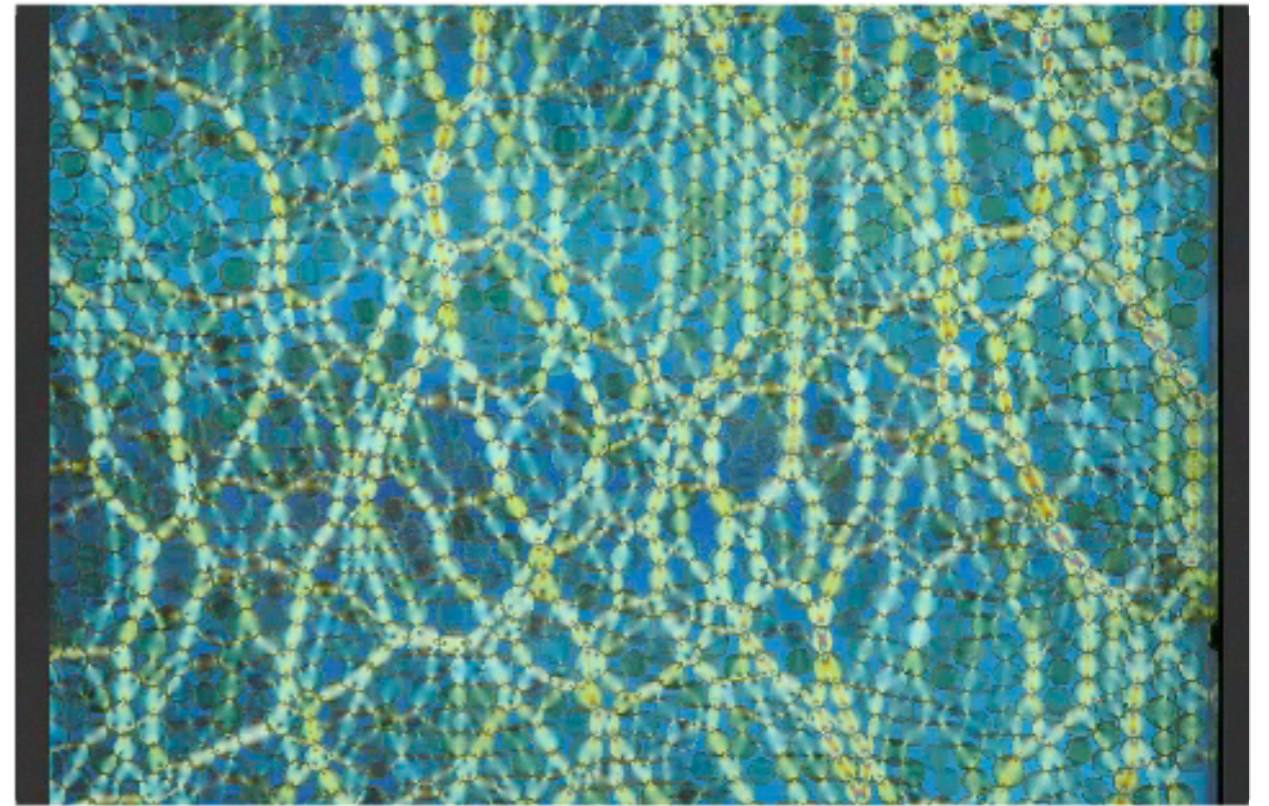
measuring
forces



predicting
behavior

Current workhorse: Photoelasticity

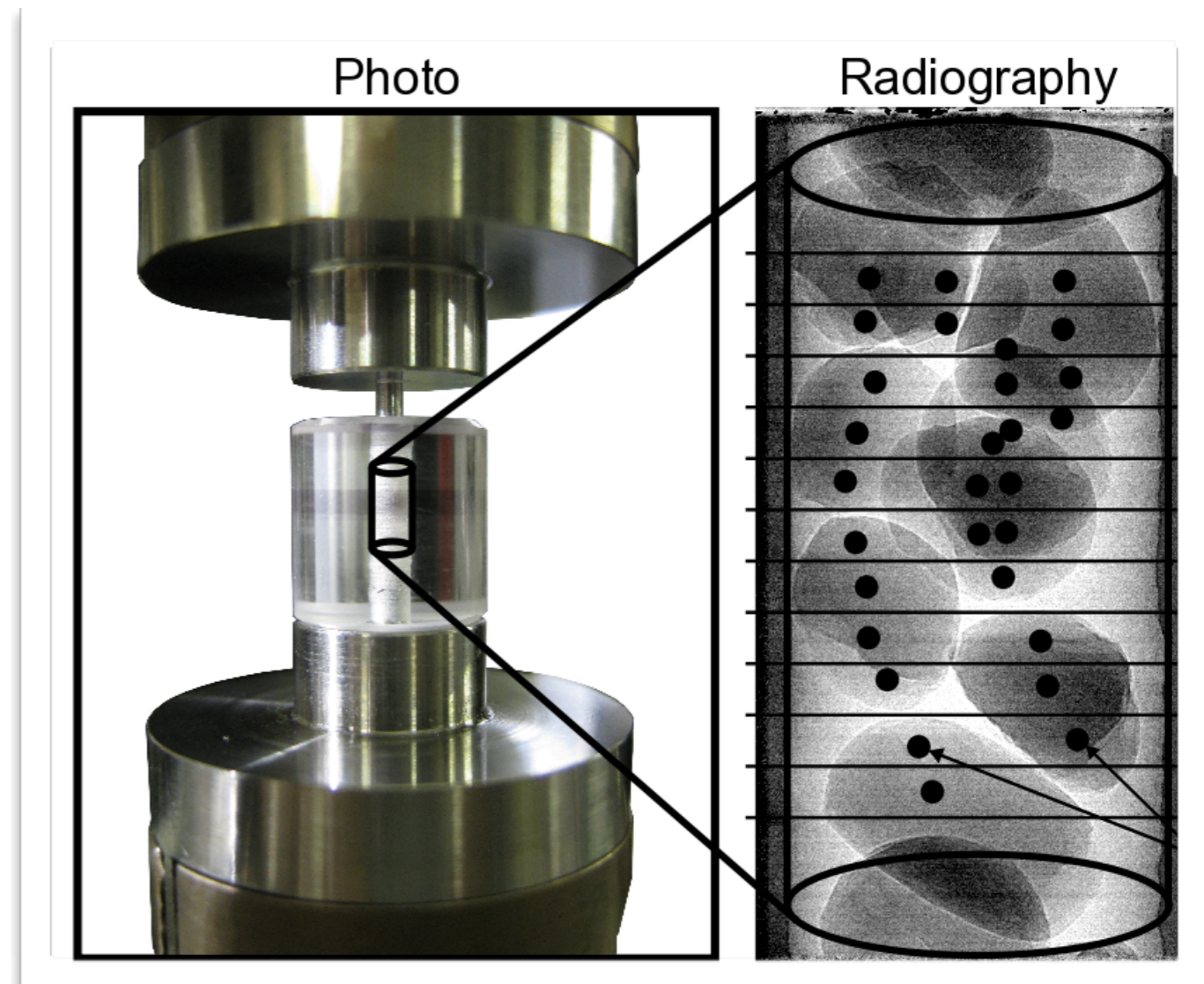
- Great in 2D
- Great insight into force-chain evolution
- Cannot provide accurate quantitative values of contact force
- Cannot work in opaque materials (e.g., sand)



Source- Jie Zhang/Duke University

Can contact forces be measured?

- 3DXRCT & 3DXRD: grain topology, kinematics & average grain strains
- Fundamental question: how to use information (constitutive modeling)?
- Missing link: grain contact forces Vs. stress

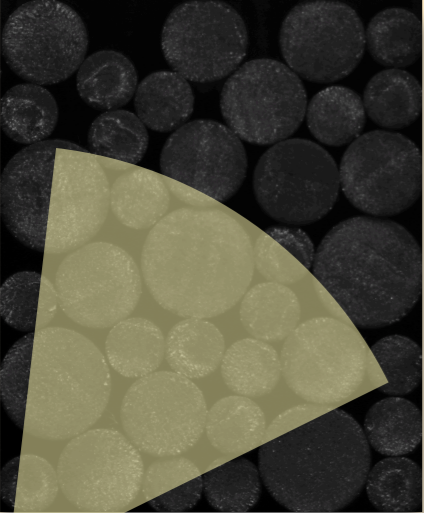


EXPERIMENTAL IMAGING

STRAIN FIELDS AND FABRIC

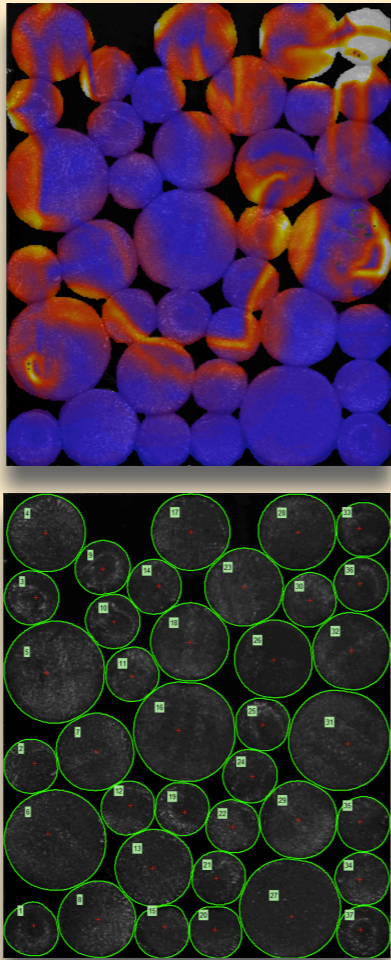
MATHEMATICAL FRAMEWORK

INTER-PARTICLE FORCES



Red arrows indicate the flow of information: from the top and bottom into the image, and from the left and right sides towards the image.

IMAGE SOURCE

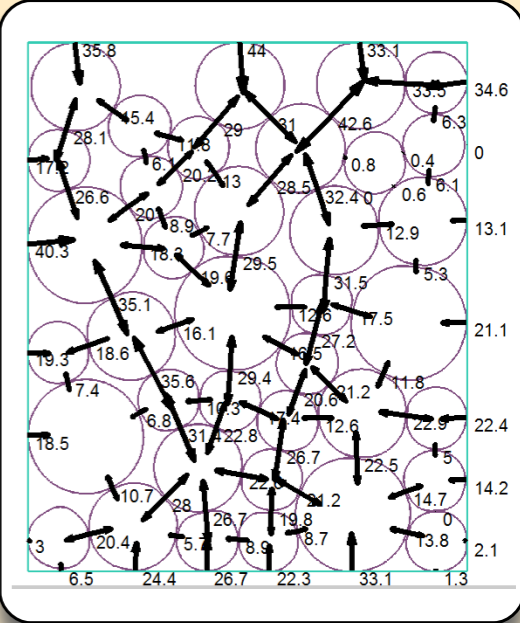


$$\bar{\sigma} = \mathbb{C} : \bar{\epsilon}$$

$$\sum_{\alpha=1}^{N_c^p} \mathbf{f}^\alpha = \mathbf{0}$$

$$\sum_{\alpha=1}^{N_c^p} \mathbf{x}^\alpha \times \mathbf{f}^\alpha = \mathbf{0}$$

$$\sum_{\alpha=1}^{N_c^p} \text{sym}(\mathbf{f}^\alpha \otimes \mathbf{x}^\alpha) = \Omega_p \bar{\sigma}_p$$

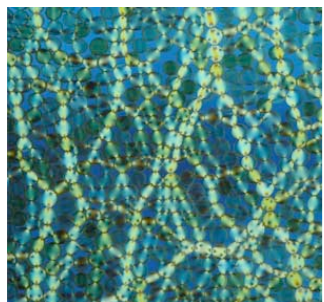
$$\mathbf{f}_n \geq 0 \quad |\mathbf{f}_t| \leq \mu \mathbf{f}_n$$


HI-RES PHOTOGRAPHY, X-RAY

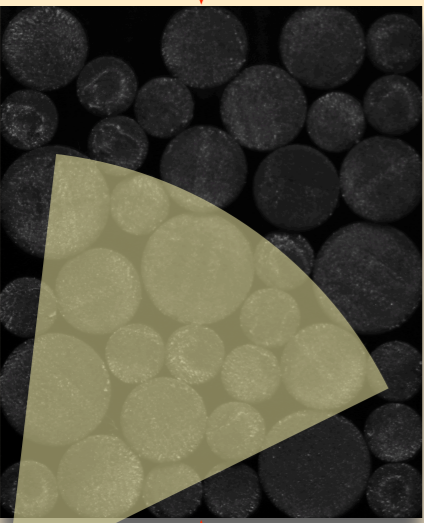
IMAGE CORRELATION, LEVEL-SETS

NUMERICAL SOLUTION TO INVERSE PROBLEM

THEORETICAL DEVELOPMENT

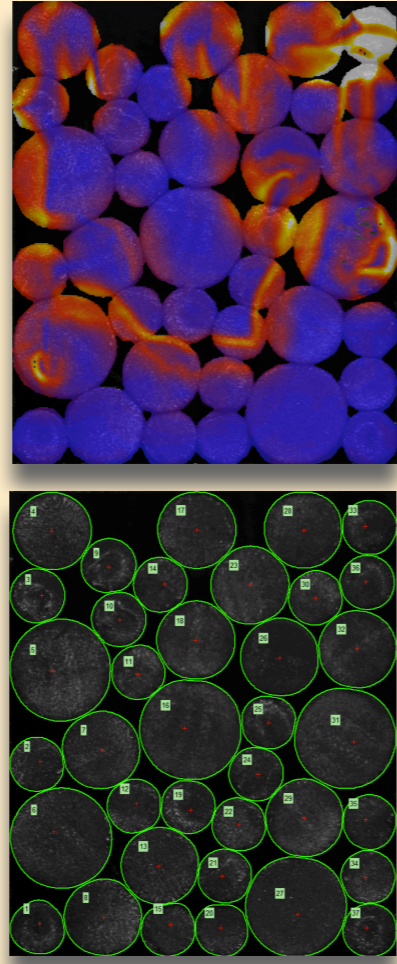


EXPERIMENTAL IMAGING → **STRAIN FIELDS AND FABRIC** → **MATHEMATICAL FRAMEWORK** → **INTER-PARTICLE FORCES**



Red arrows indicate the flow of information: from the top and bottom into the image, and from the image to the left and right.

IMAGE SOURCE

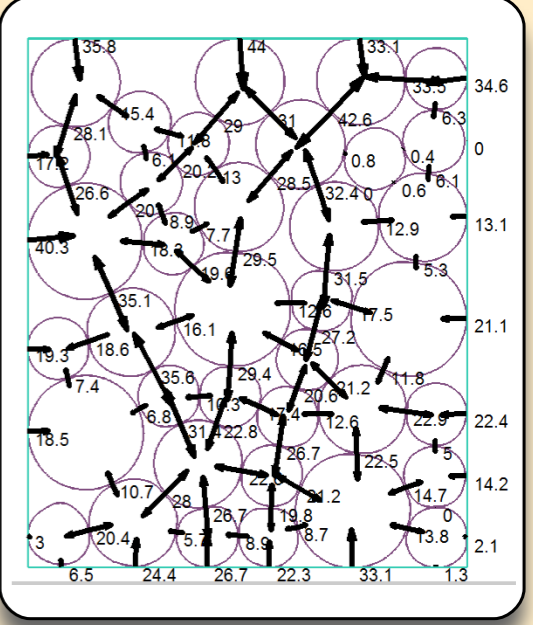


$$\bar{\sigma} = \mathbb{C} : \bar{\epsilon}$$

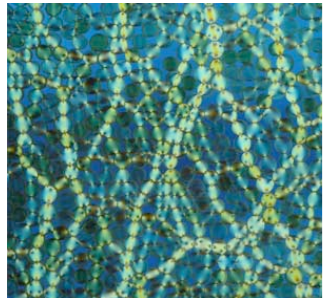
$$\sum_{\alpha=1}^{N_p} \mathbf{f}^\alpha = \mathbf{0}$$

$$\sum_{\alpha=1}^{N_p} \mathbf{x}^\alpha \times \mathbf{f}^\alpha = \mathbf{0}$$

$$\sum_{\alpha=1}^{N_p} \text{sym}(\mathbf{f}^\alpha \otimes \mathbf{x}^\alpha) = \Omega_p \bar{\sigma}_p$$

$$\mathbf{f}_n \geq 0 \quad |\mathbf{f}_t| \leq \mu \mathbf{f}_n$$


HI-RES PHOTOGRAPHY, X-RAY → **IMAGE CORRELATION, LEVEL-SETS** → **NUMERICAL SOLUTION TO INVERSE PROBLEM** → **THEORETICAL DEVELOPMENT**

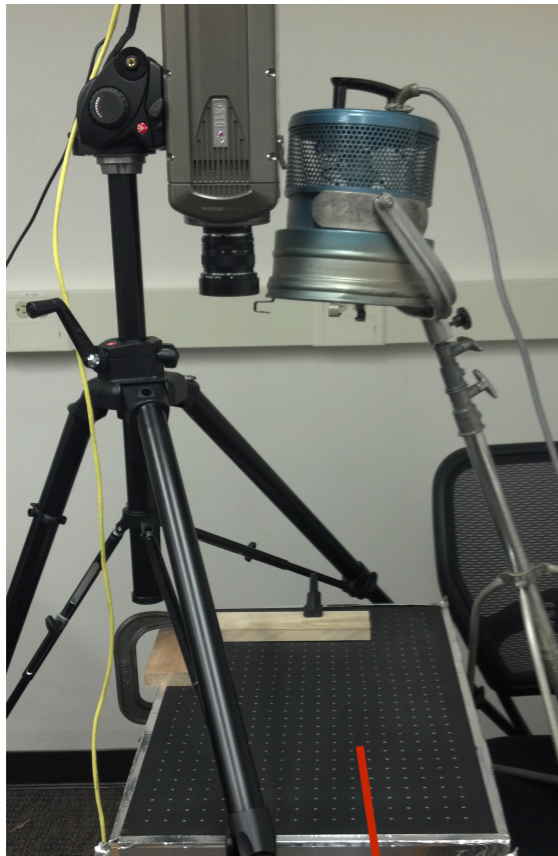


experimentally capture inter-particle **forces**

Dynamic Validation of Method

Dynamic Validation of Method

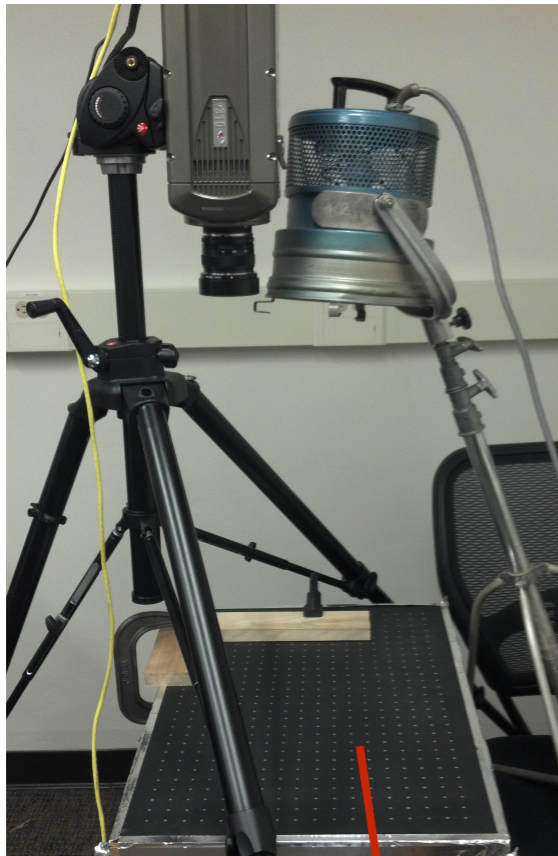
Phantom v310 high-speed camera



Frictionless “air hockey” table
(only forces are inter-particle)

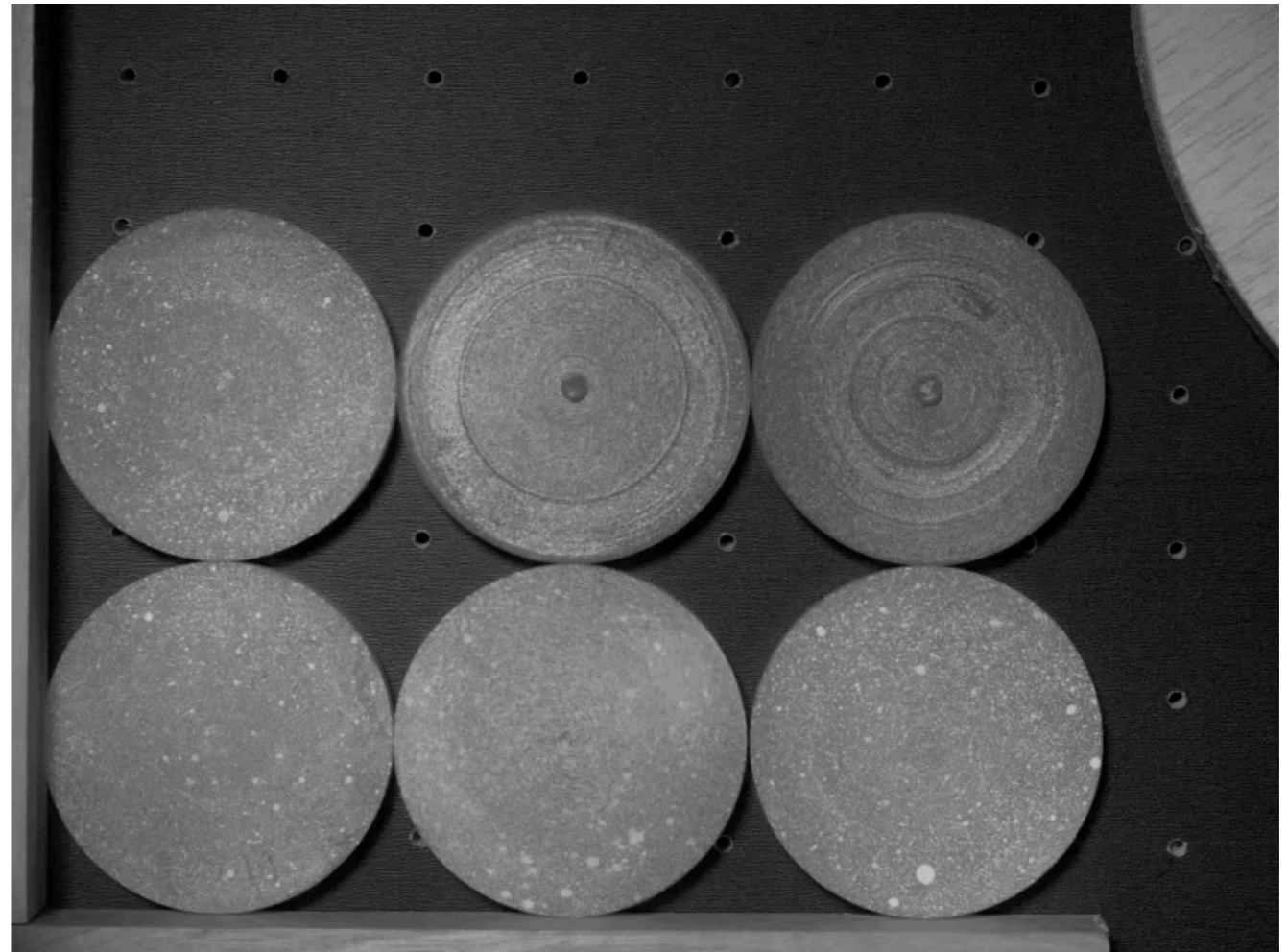
Dynamic Validation of Method

Phantom v310 high-speed camera



Frictionless “air hockey” table
(only forces are inter-particle)

Rubber “grains” and rigid impactor



(1/500 real time)

$$v_{0x} = -1.14 \text{ m/s} \quad v_{0y} = -0.66 \text{ m/s}$$

More unknowns than momentum equations

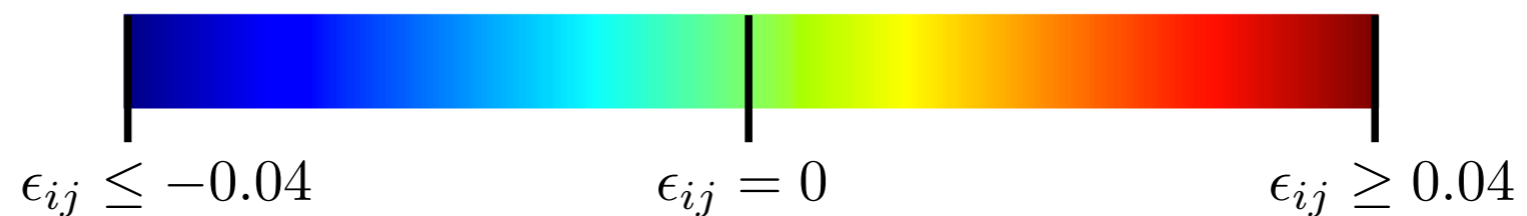
Dynamic Validation of Method

Digital Image Correlation (Vic2d): ϵ_{xy}

FEM Simulation (Abaqus/Explicit): ϵ_{xy}

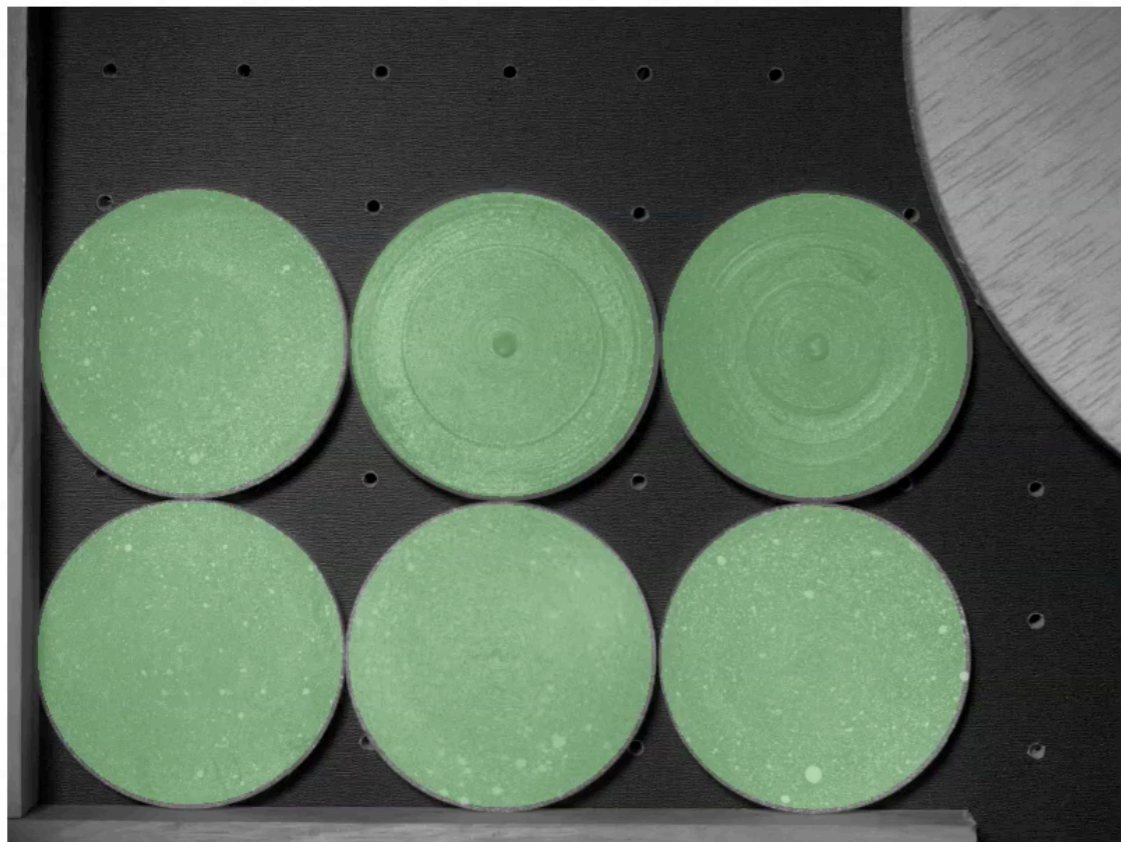
(1/500 real time)

(1/500 real time)



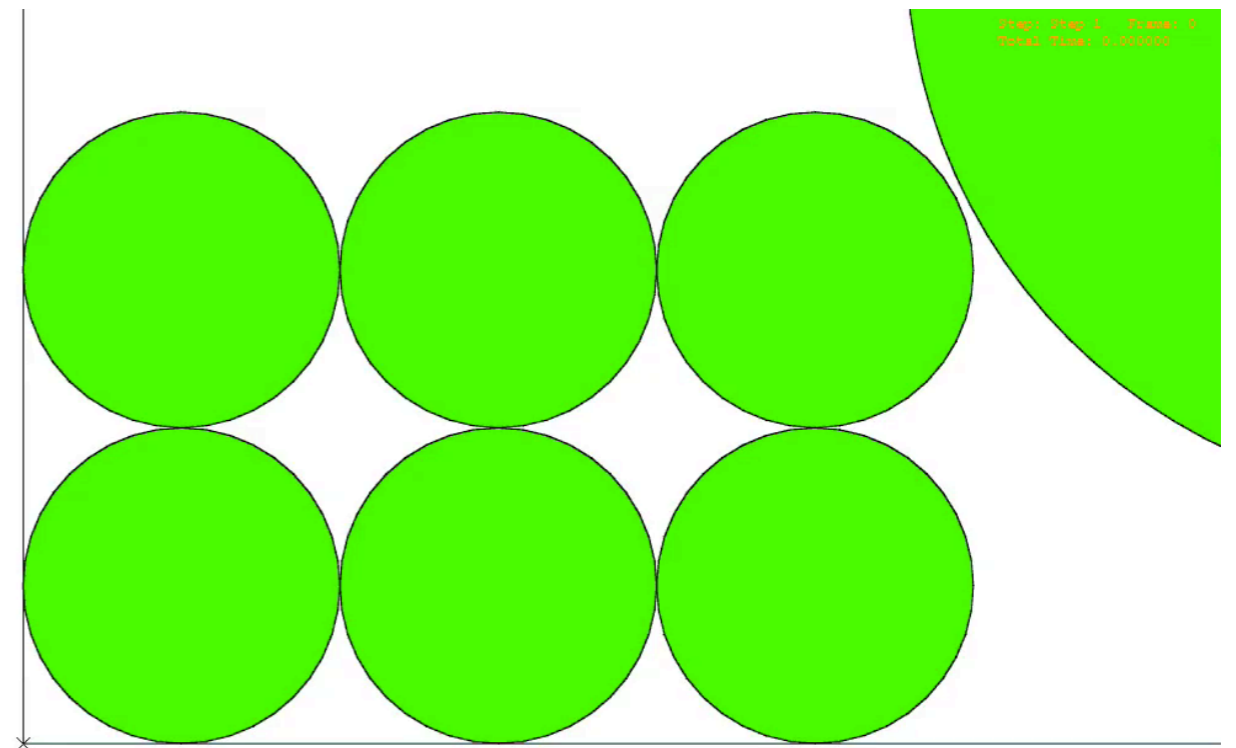
Dynamic Validation of Method

Digital Image Correlation (Vic2d): ϵ_{xy}

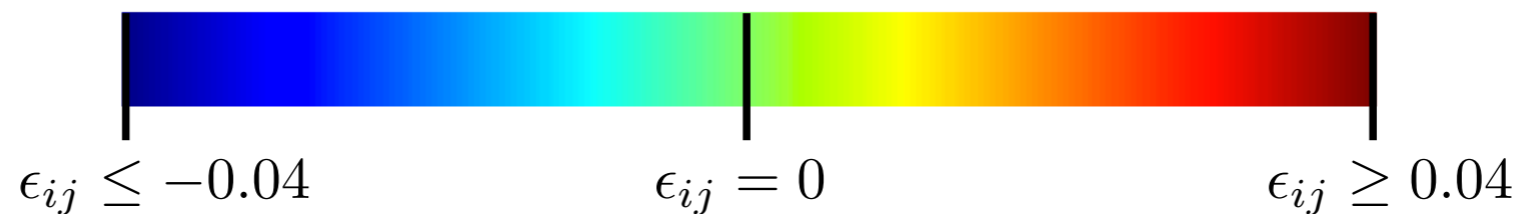


(1/500 real time)

FEM Simulation (Abaqus/Explicit): ϵ_{xy}



(1/500 real time)

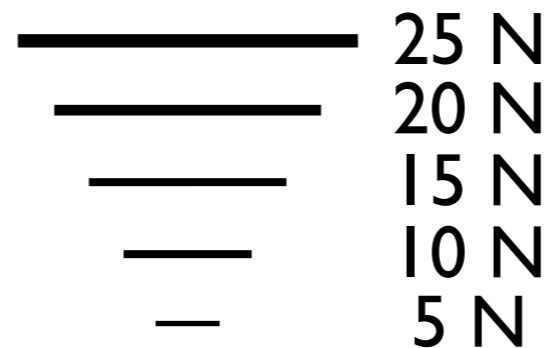


Dynamic Validation of Method

Inverse problem

FEM Simulation

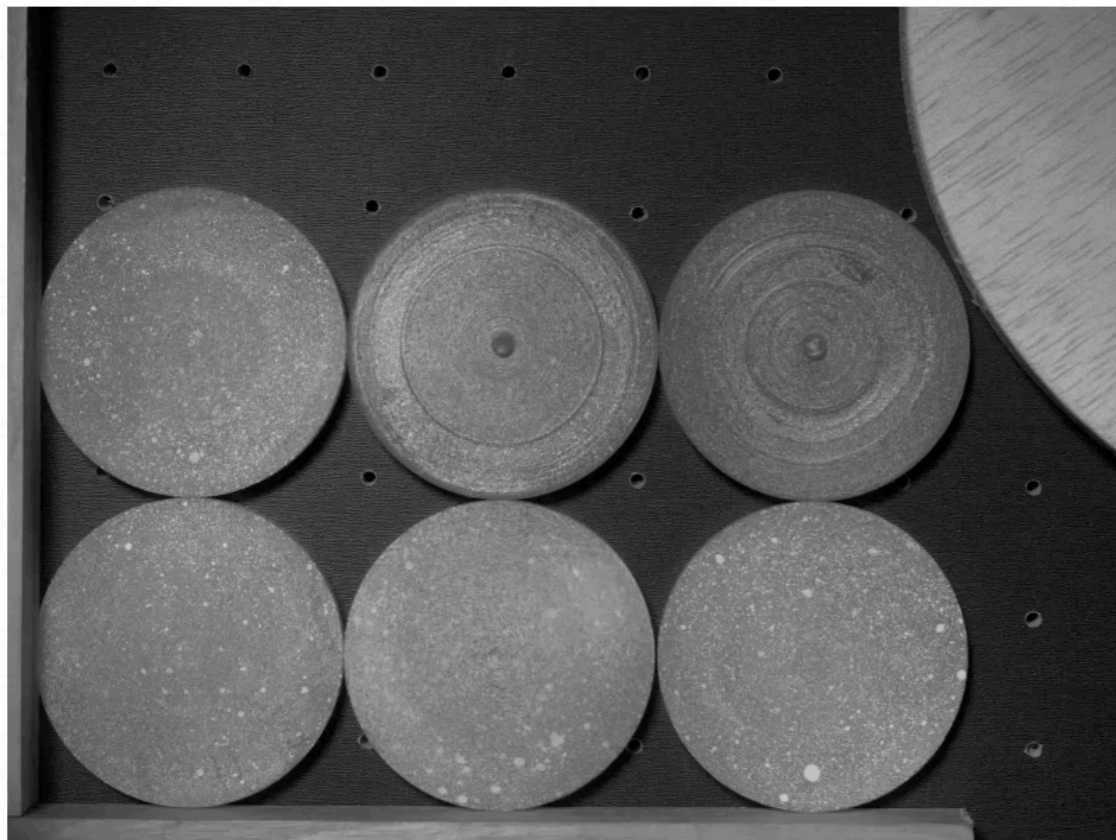
(1/500 real time)



(1/500 real time)

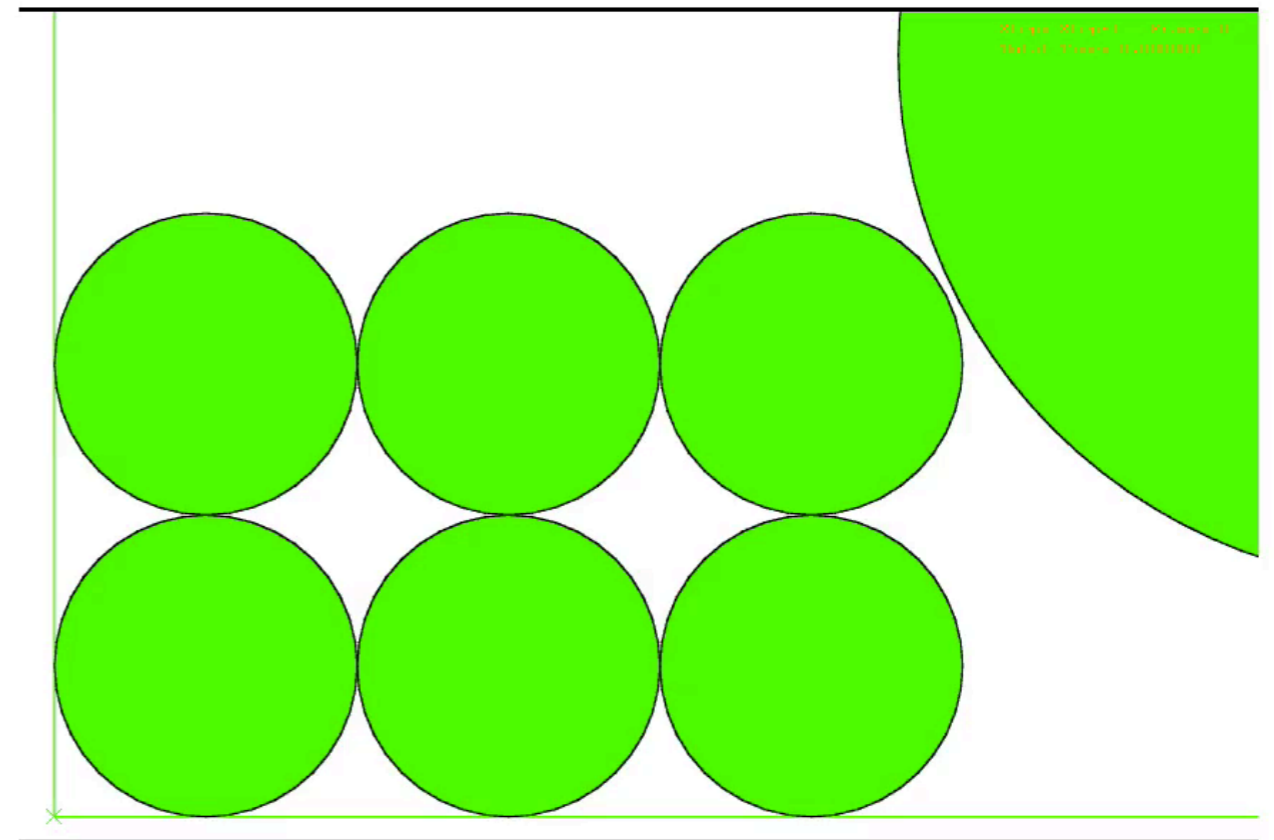
Dynamic Validation of Method

Inverse problem

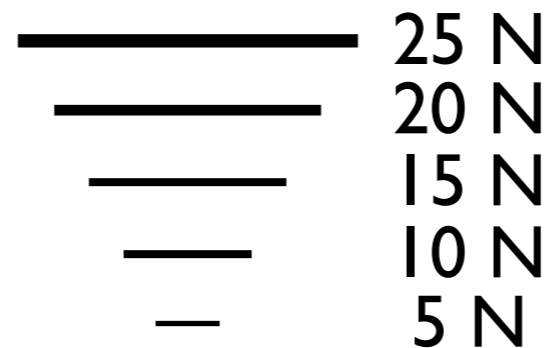


(1/500 real time)

FEM Simulation

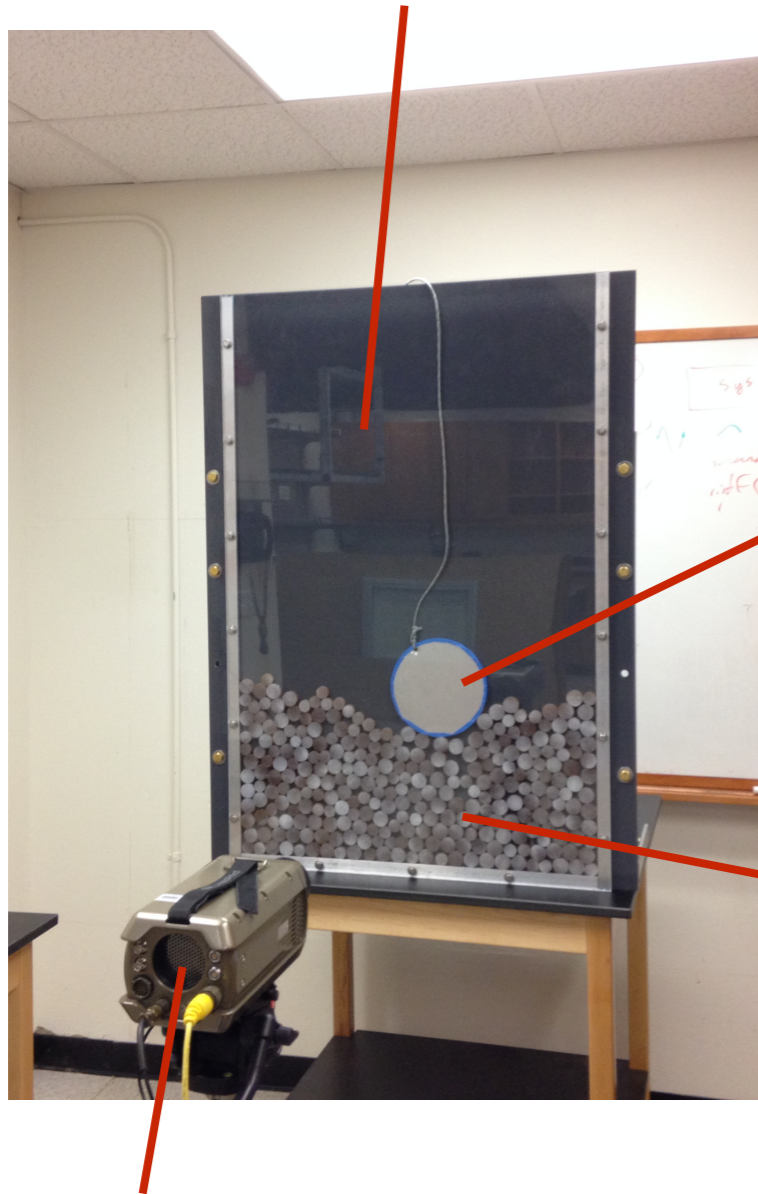


(1/500 real time)



Application: Penetration

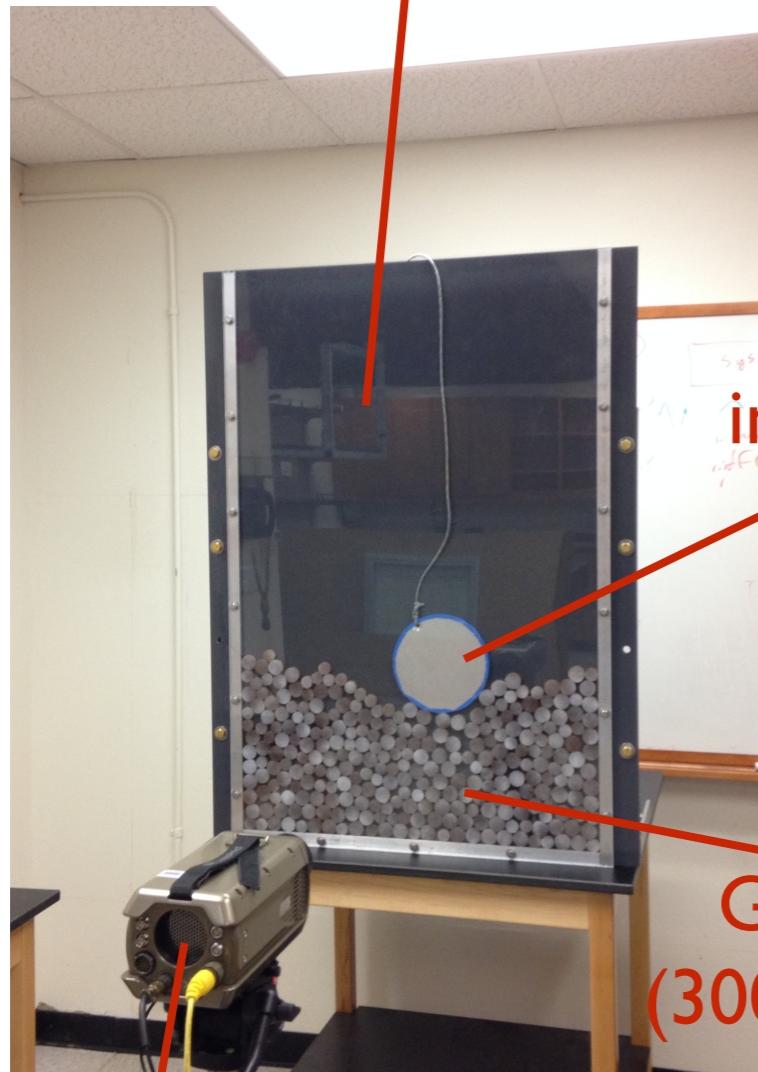
Experiment ($v_0=3\text{m/s}$)



(1/450 real time)

Application: Penetration

PVC & Plexiglass

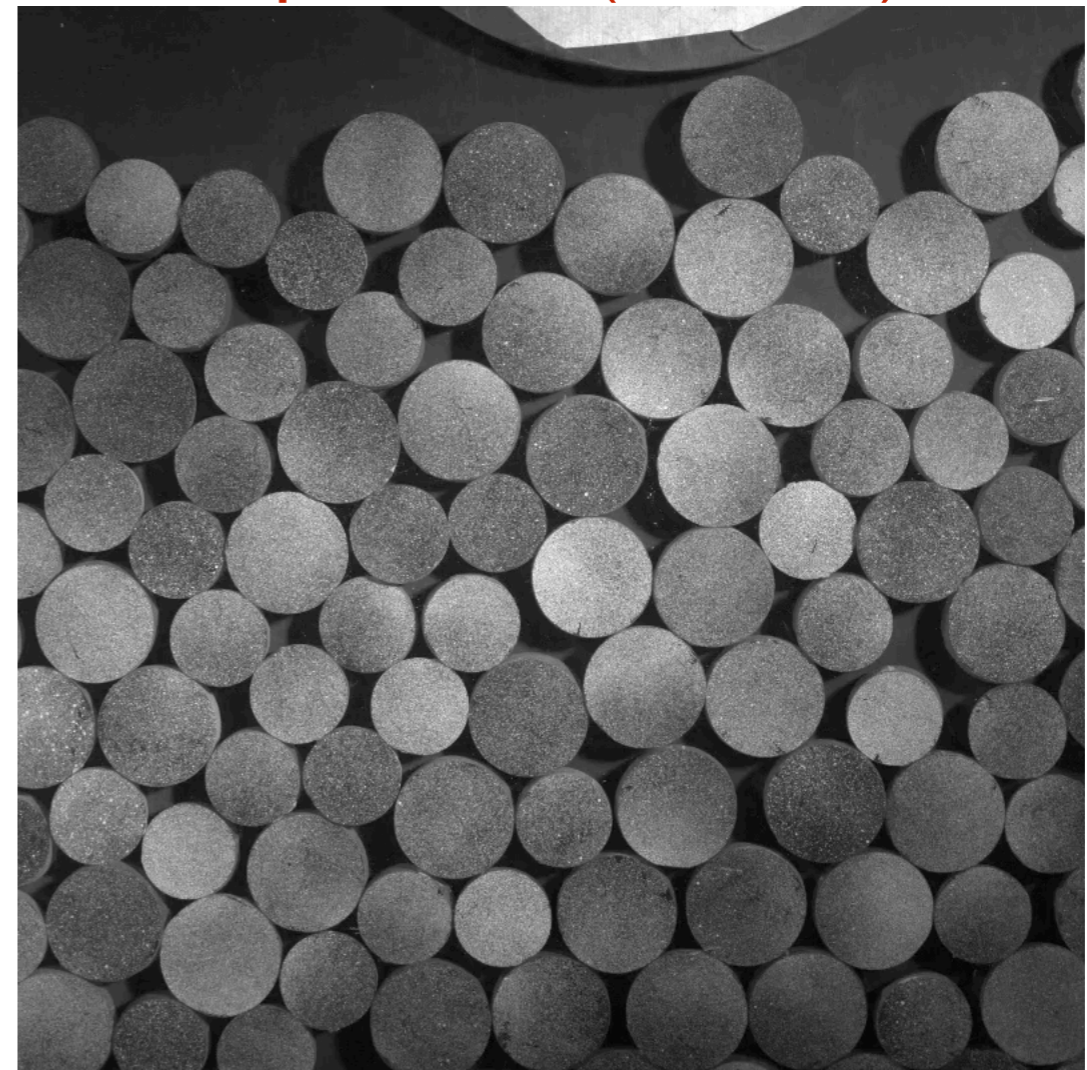


Steel intruder

Grains
(300 - 600)

Phantom v310 high-speed camera

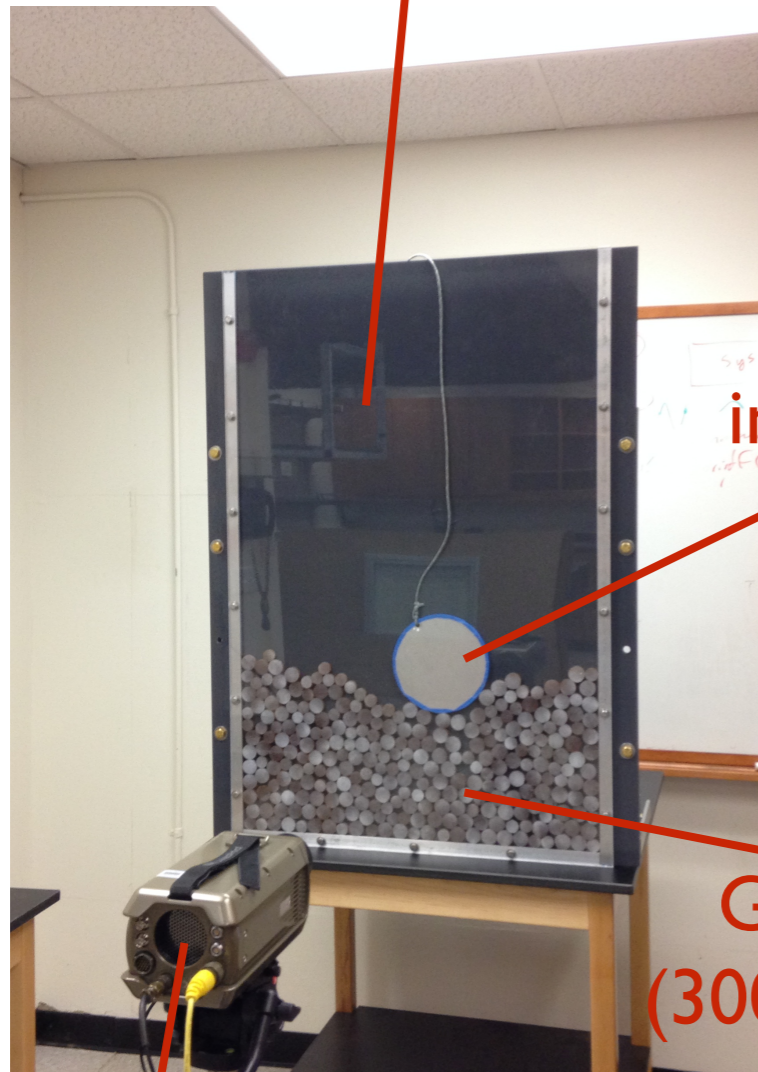
Experiment ($v_0=3\text{m/s}$)



(1/450 real time)

Application: Penetration

PVC & Plexiglass

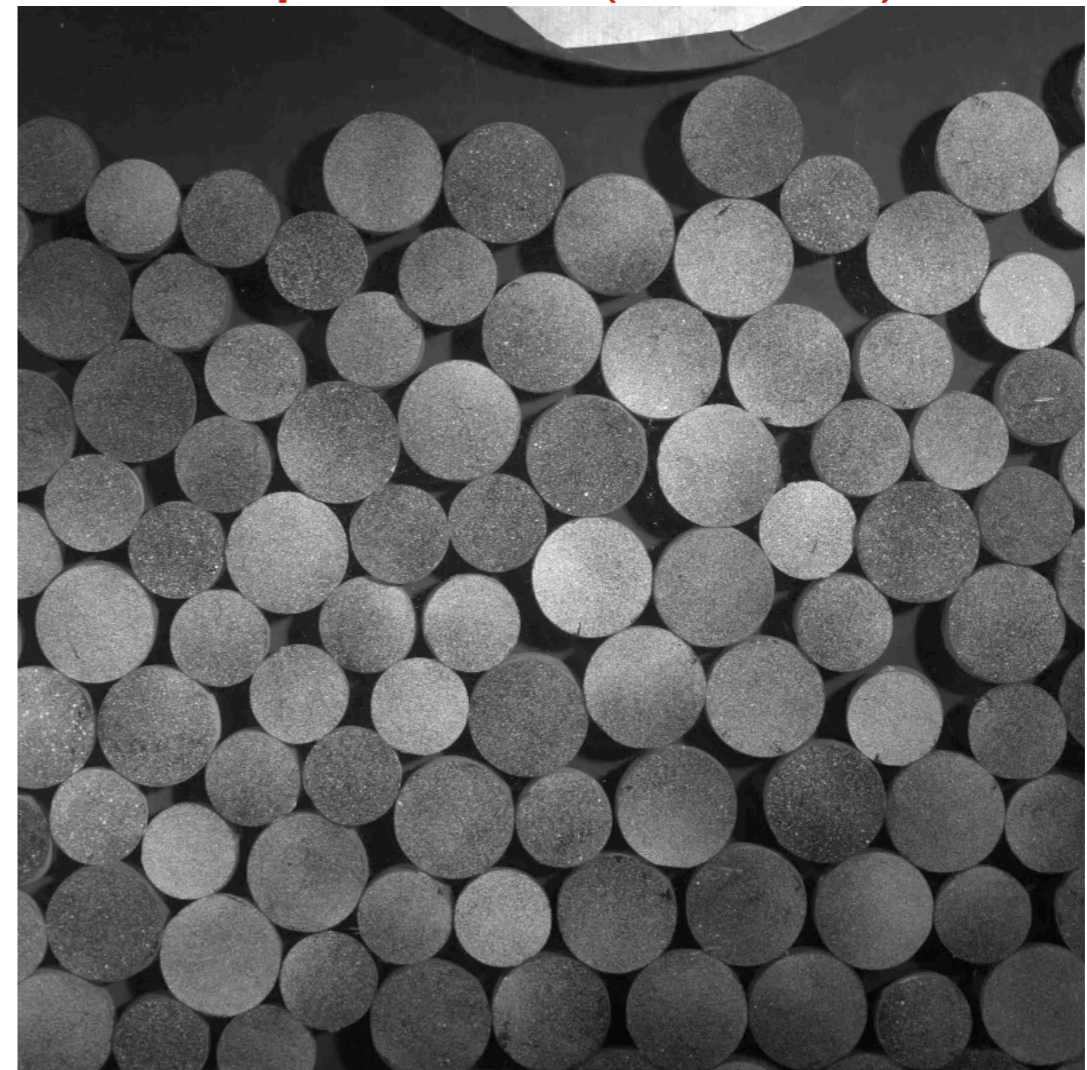


Steel intruder

Grains
(300 - 600)

Phantom v310 high-speed camera

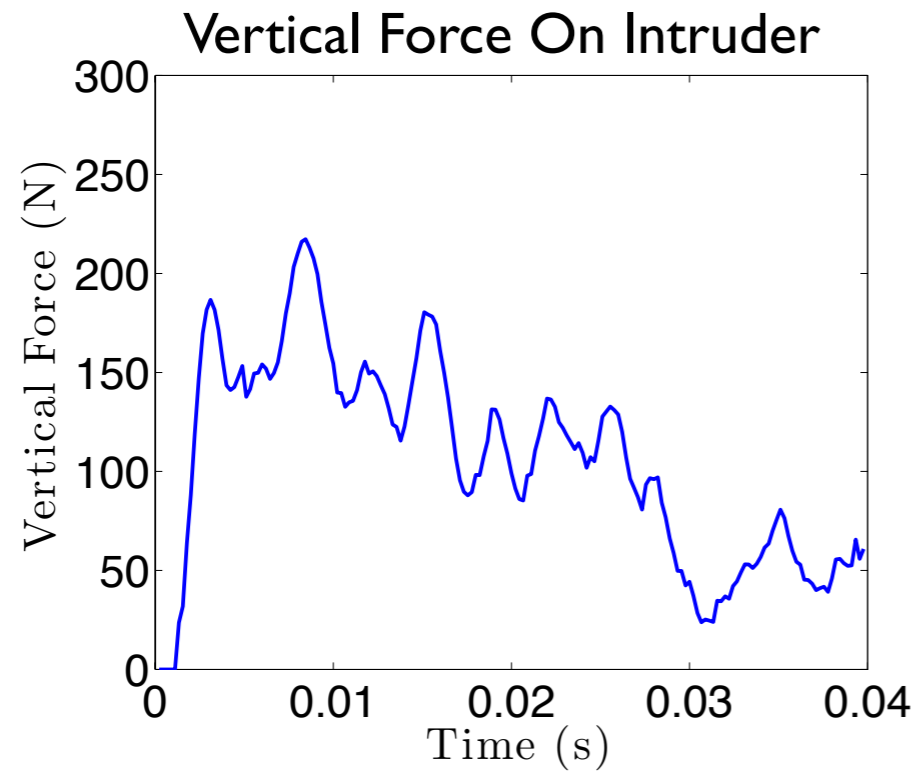
Experiment ($v_0=3\text{m/s}$)



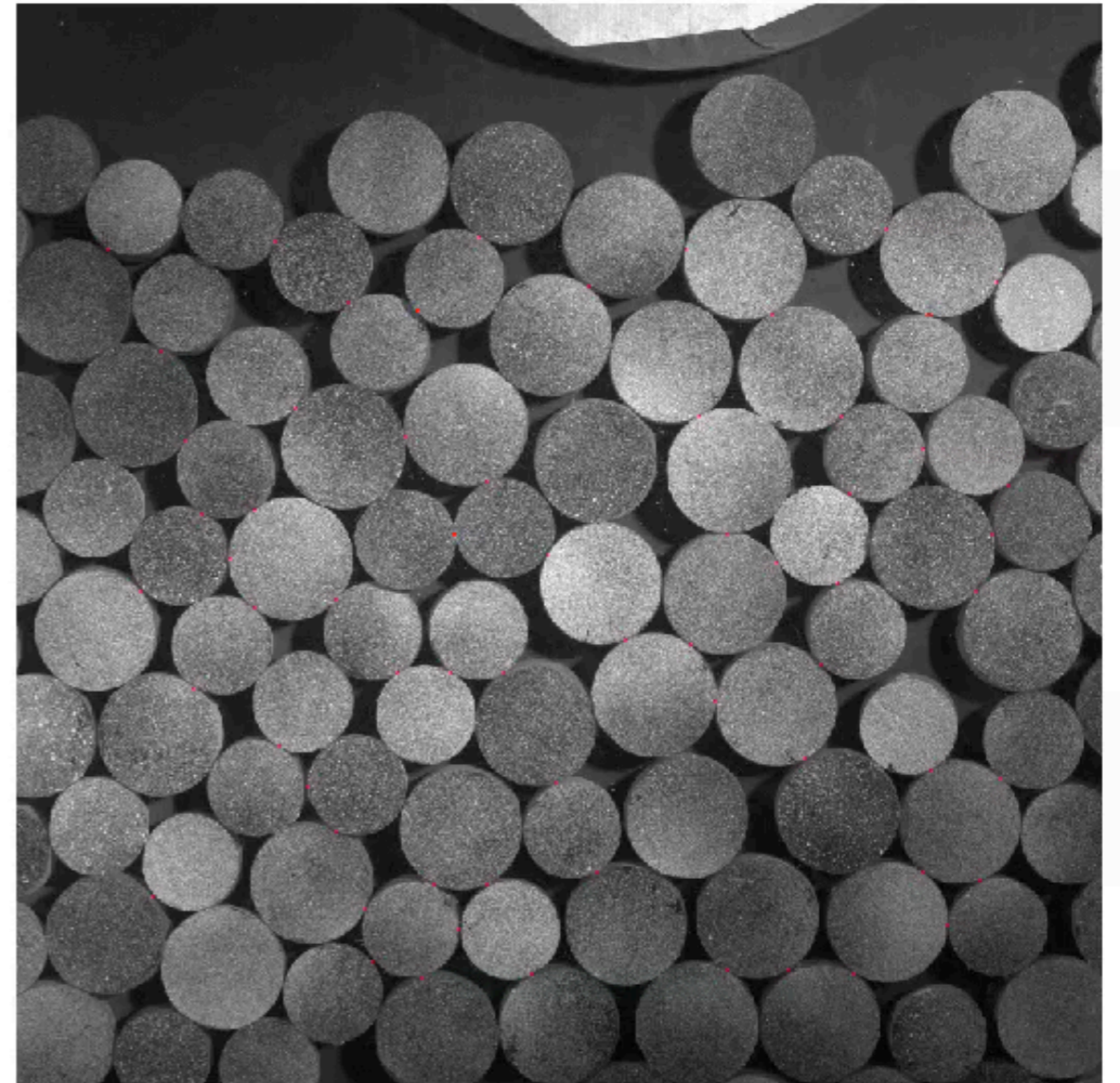
(1/450 real time)

Application: Penetration

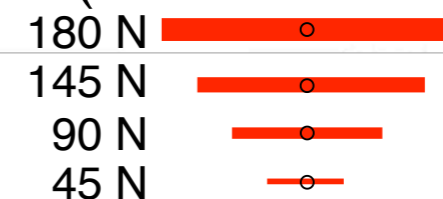
Application: Penetration



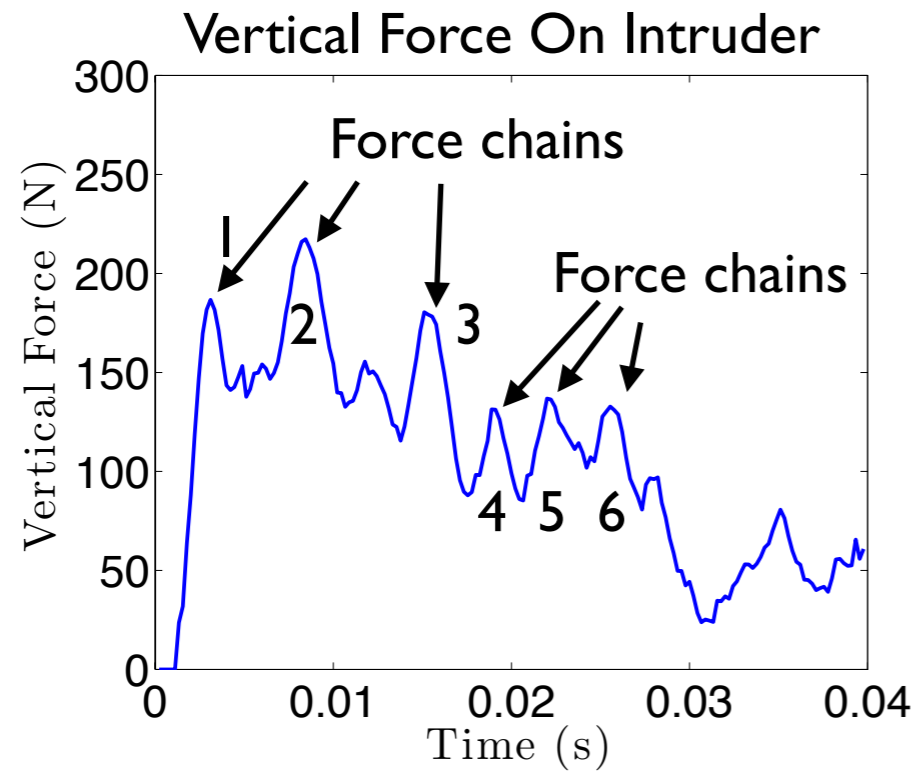
Inverse problem



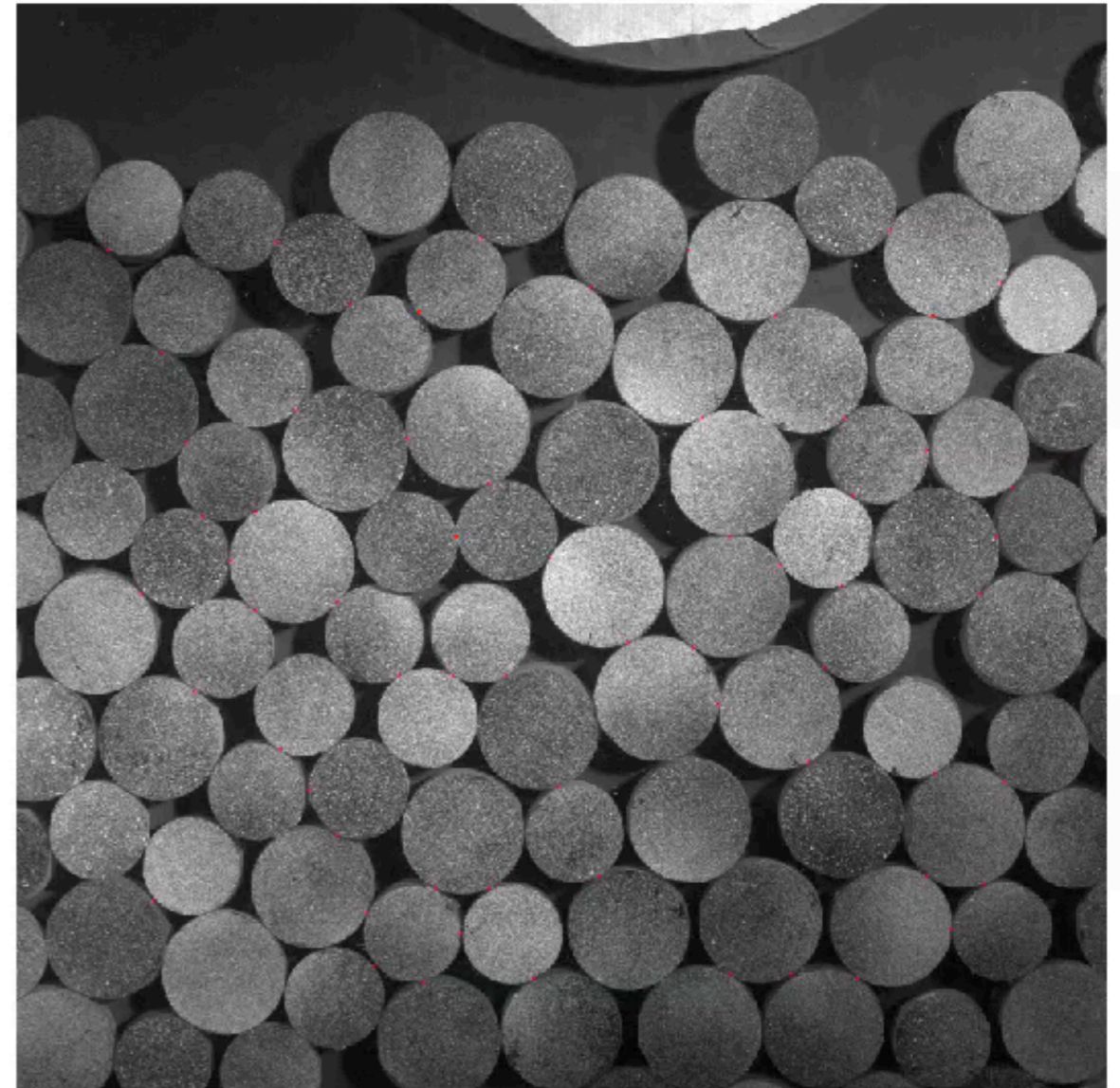
(1/450 real time)



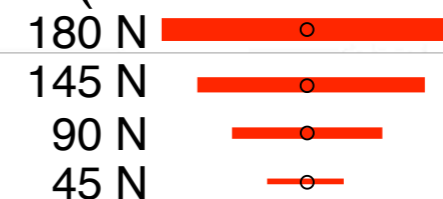
Application: Penetration



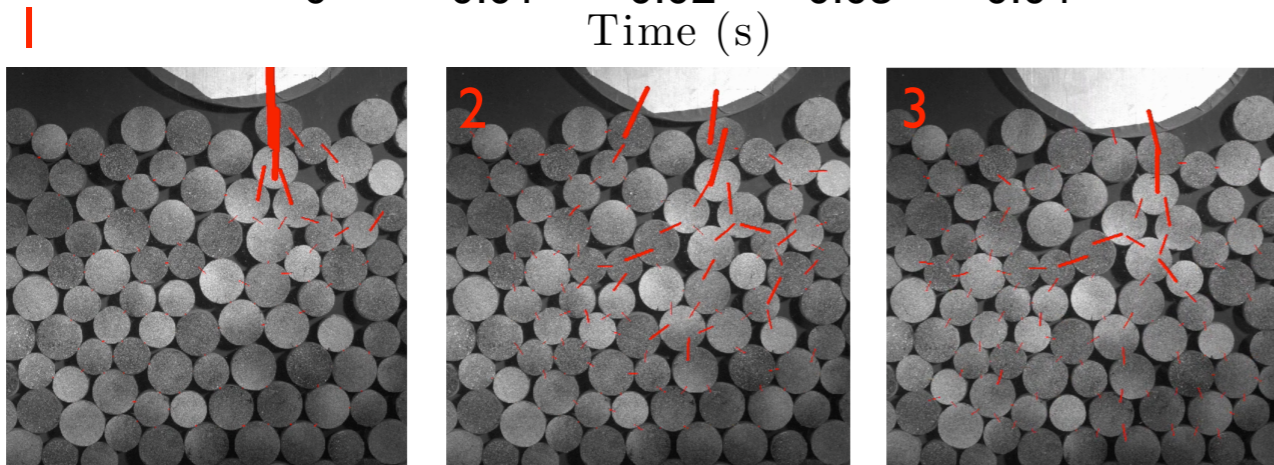
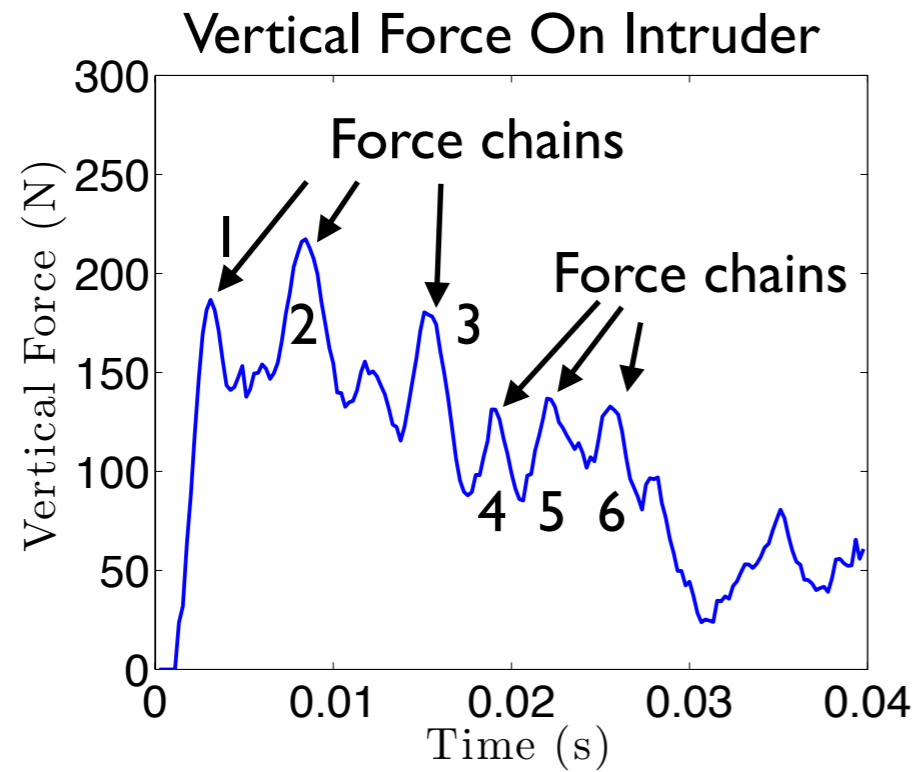
Inverse problem



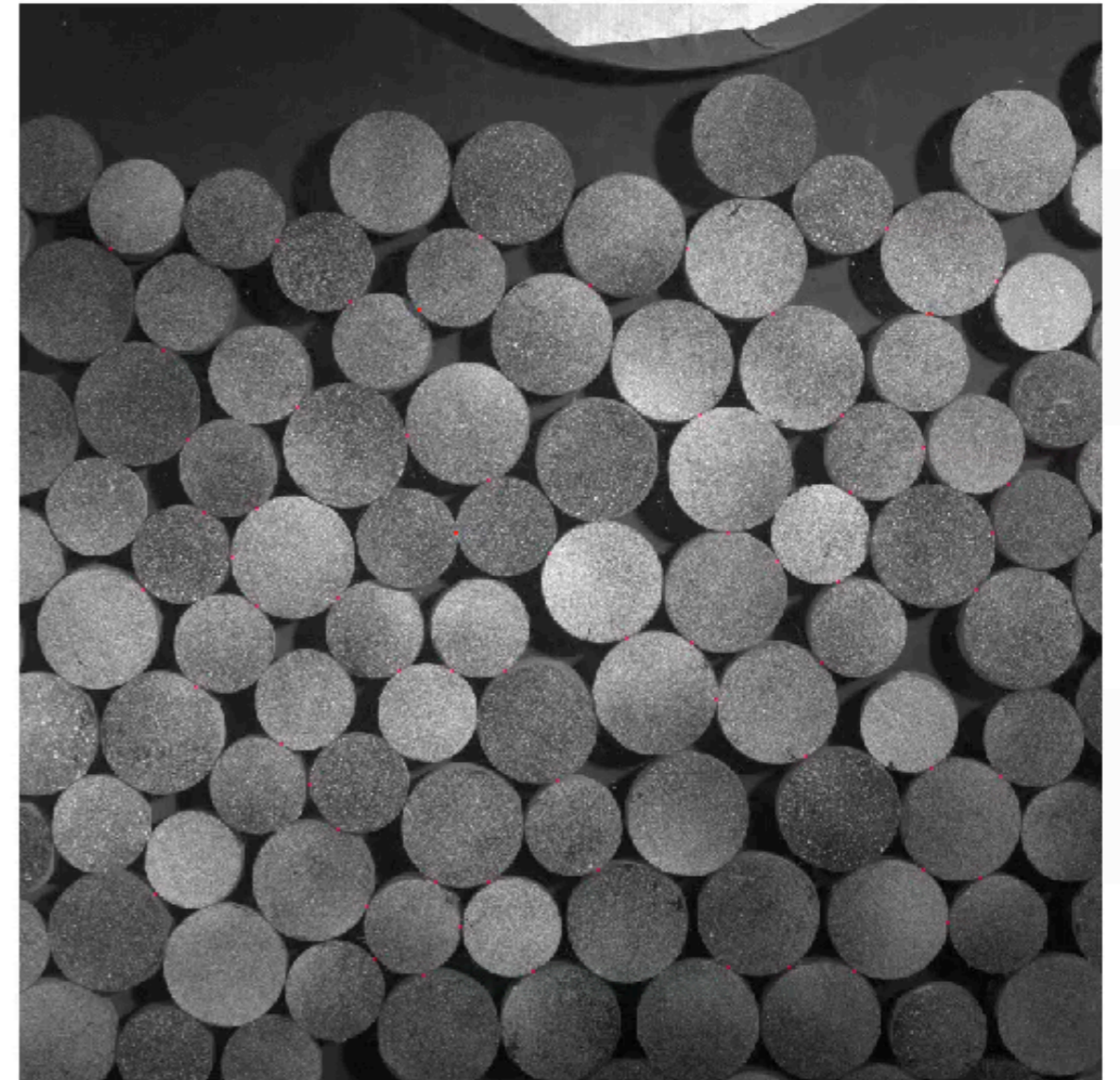
(1/450 real time)



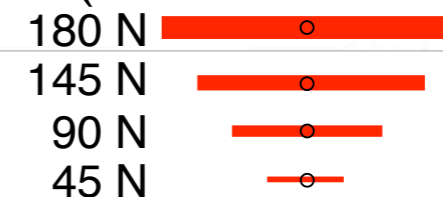
Application: Penetration



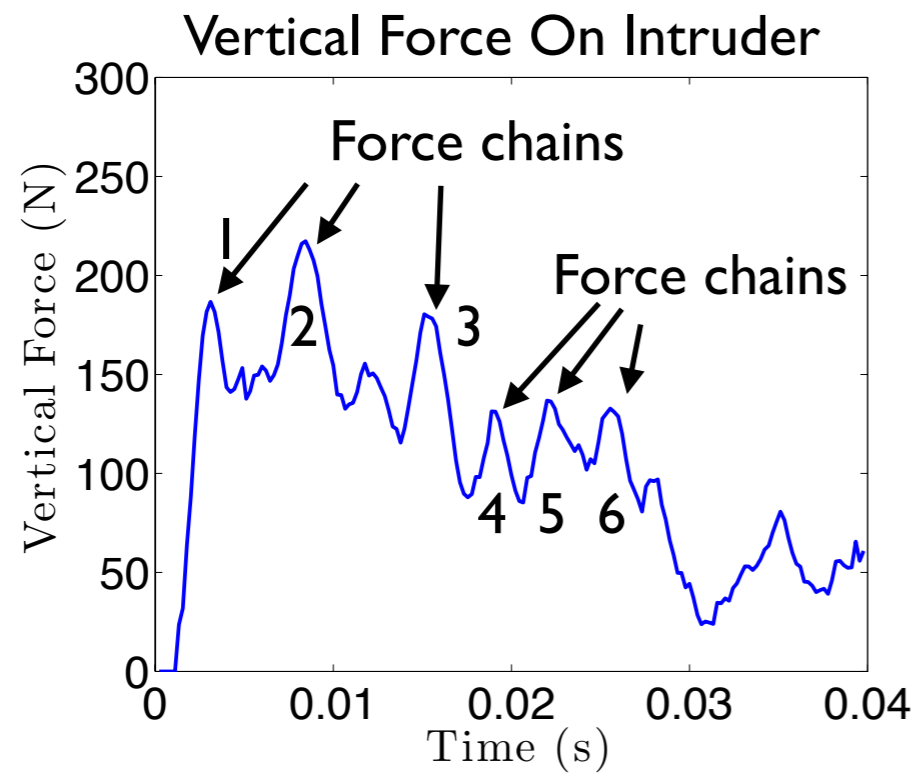
Inverse problem



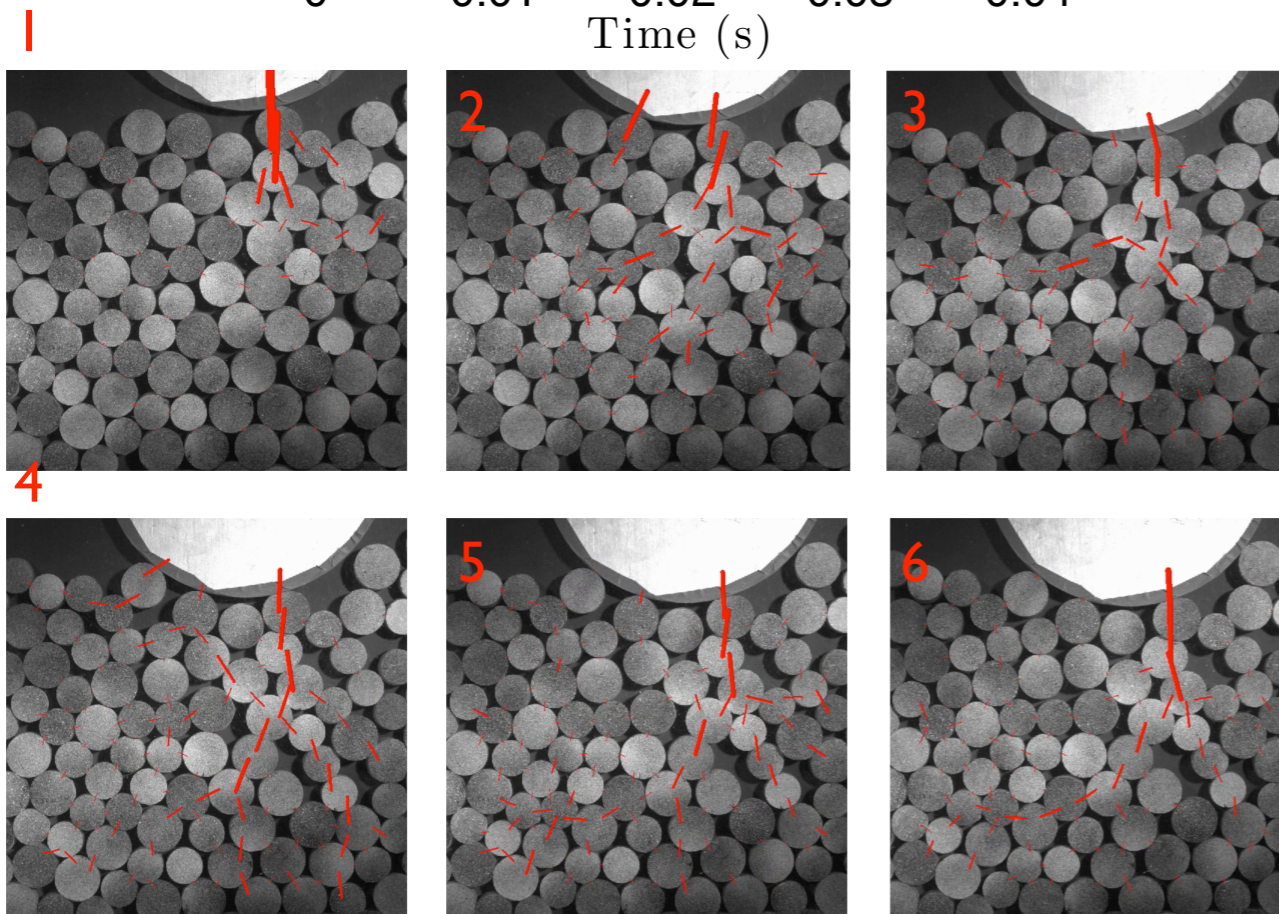
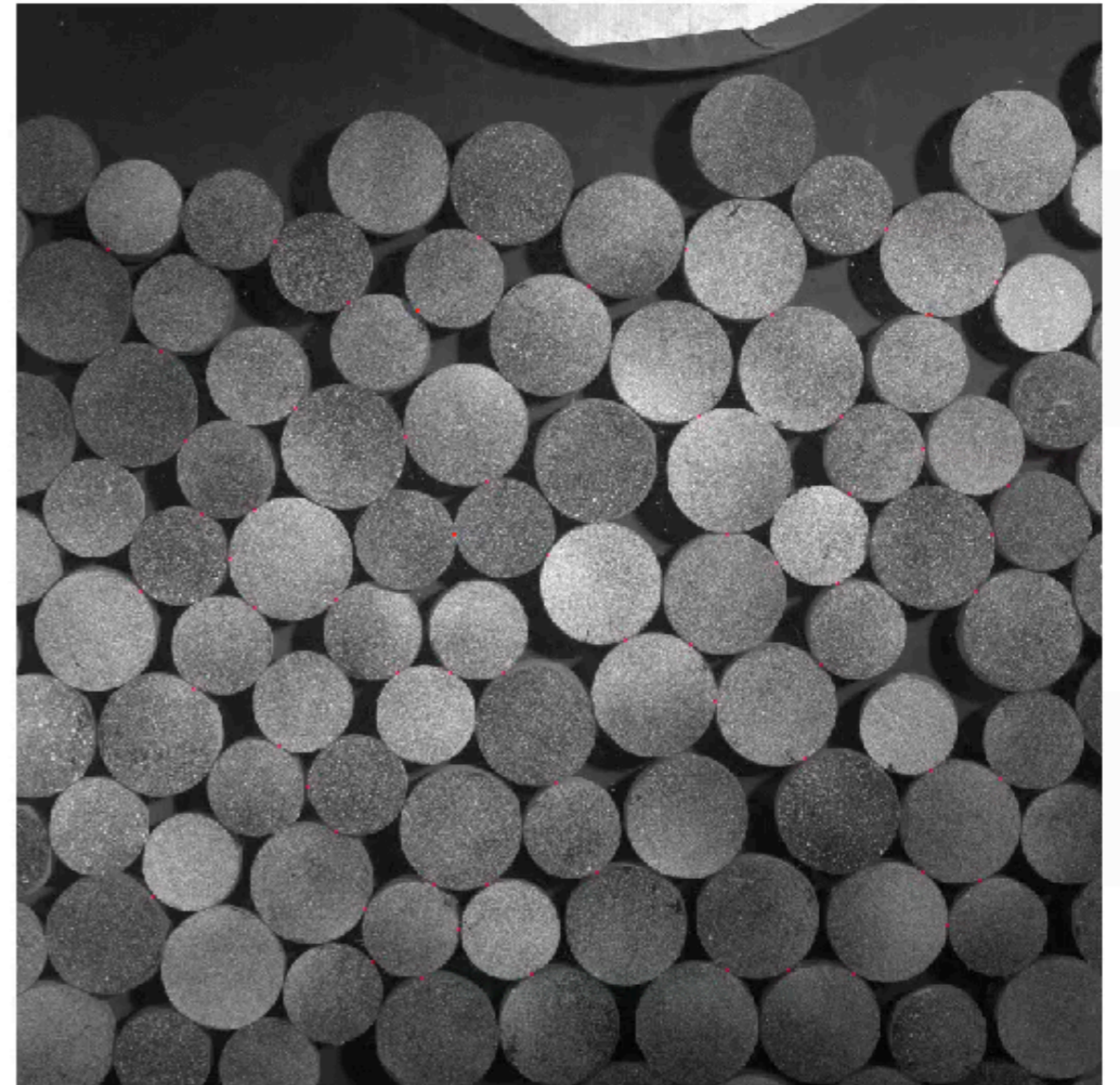
(1/450 real time)



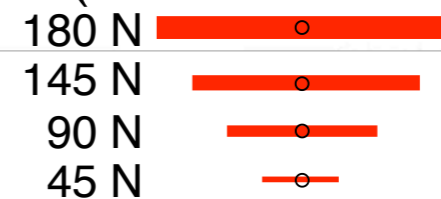
Application: Penetration



Inverse problem



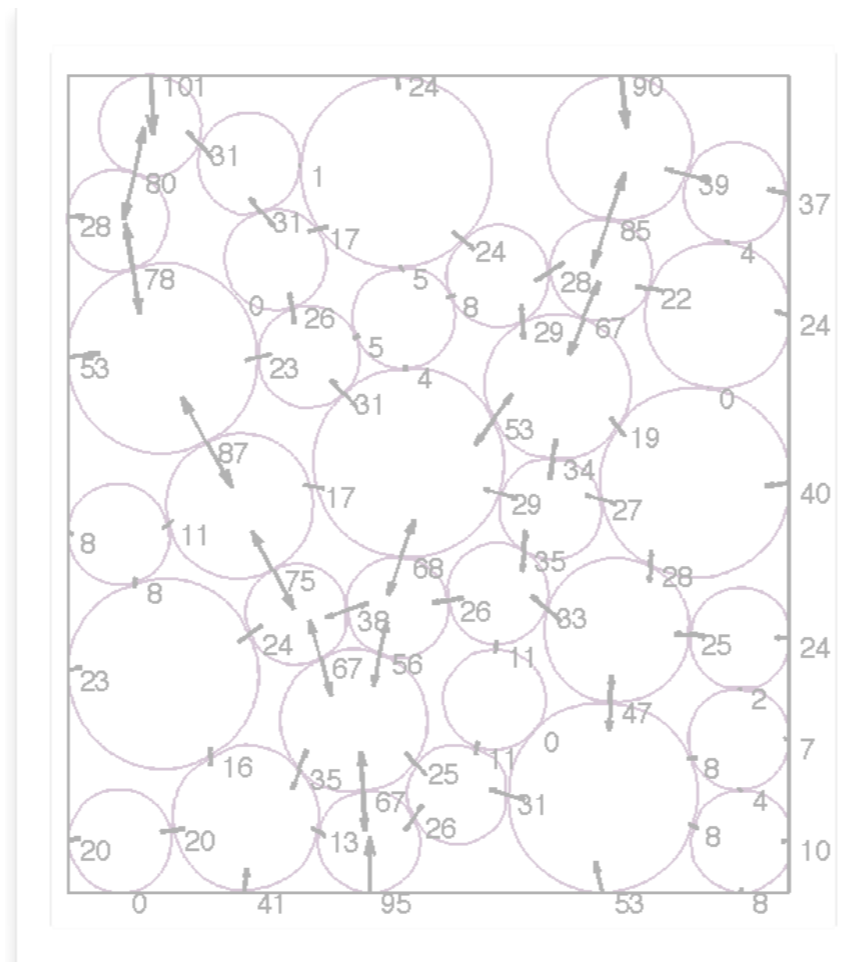
(1/450 real time)



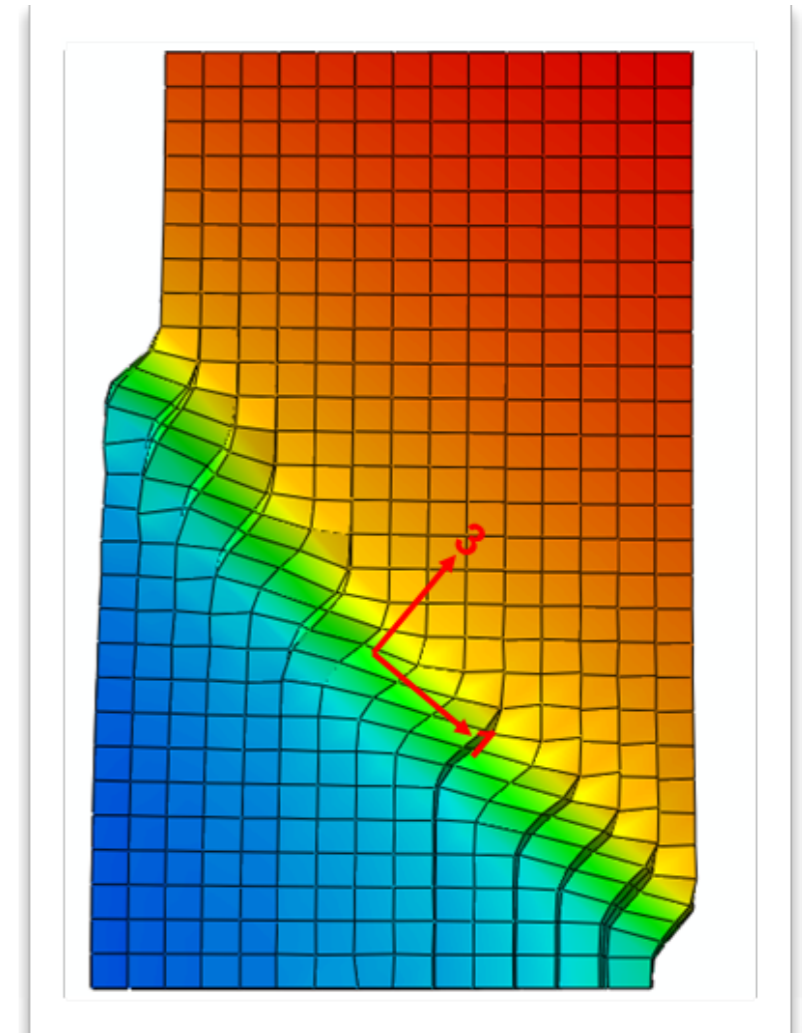
Today's menu: Avatar



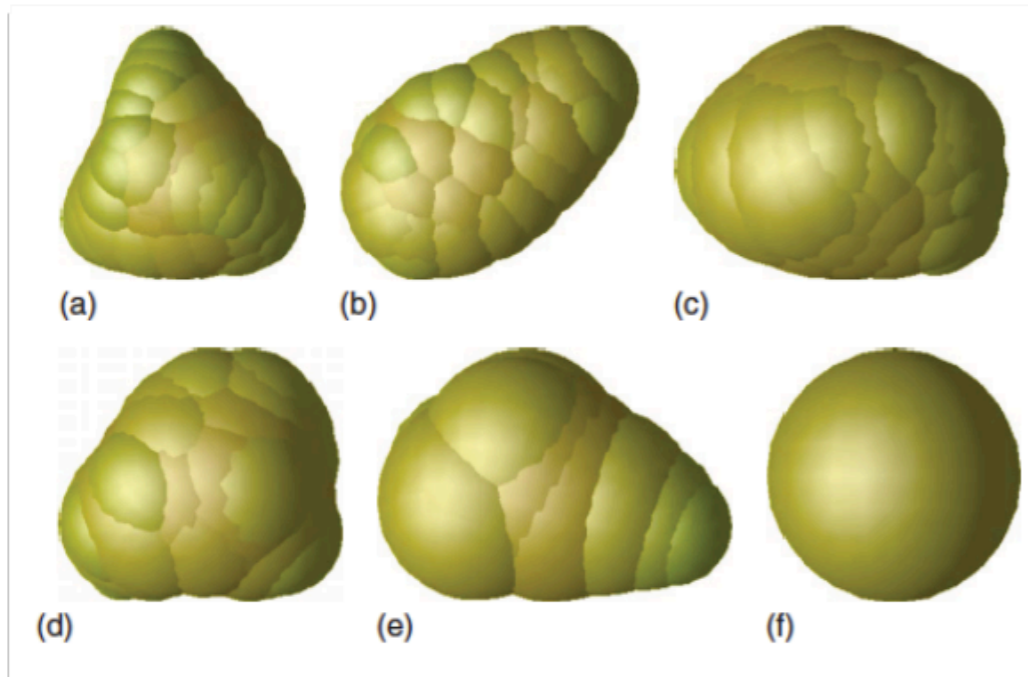
measuring
kinematics



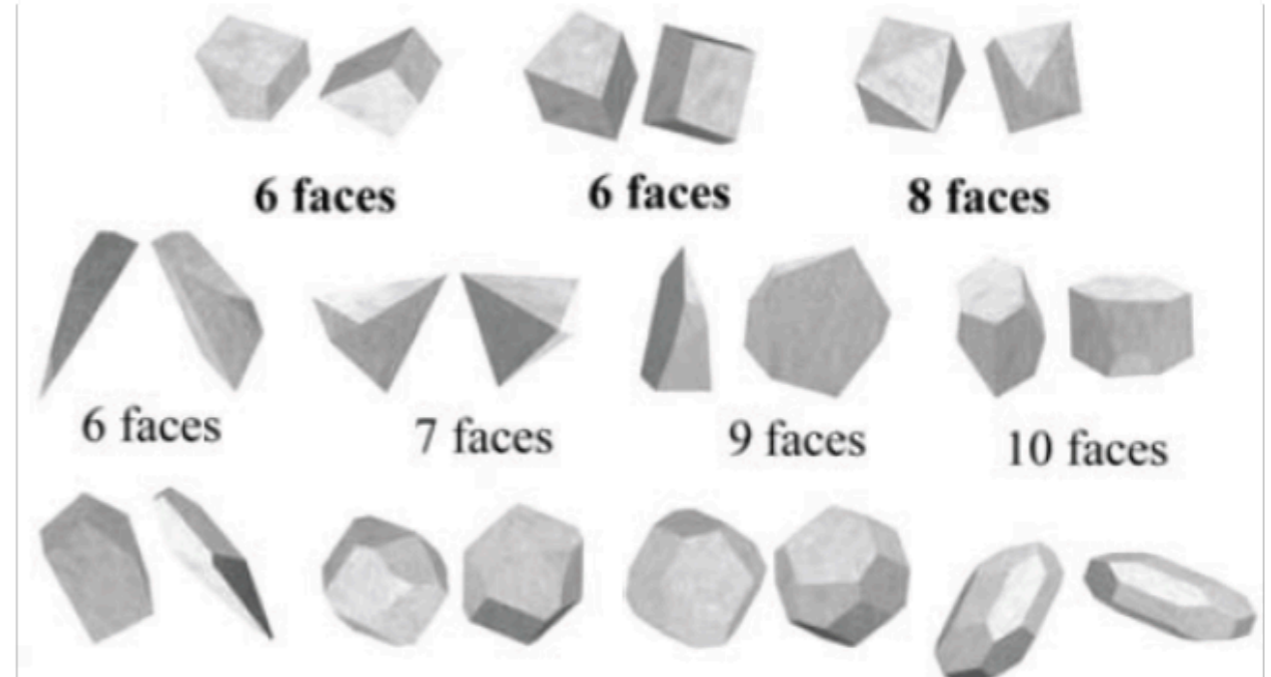
measuring
forces



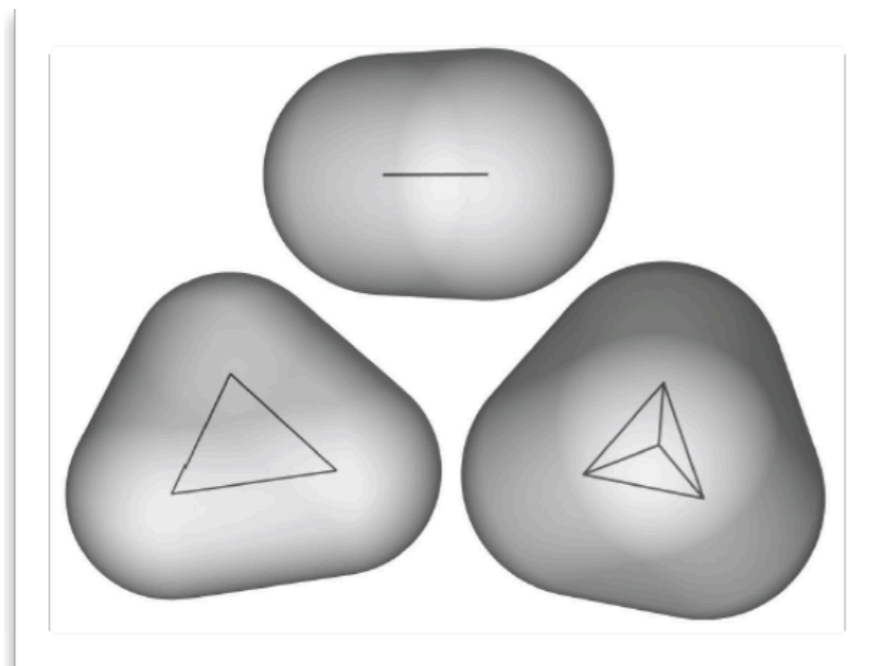
predicting
behavior



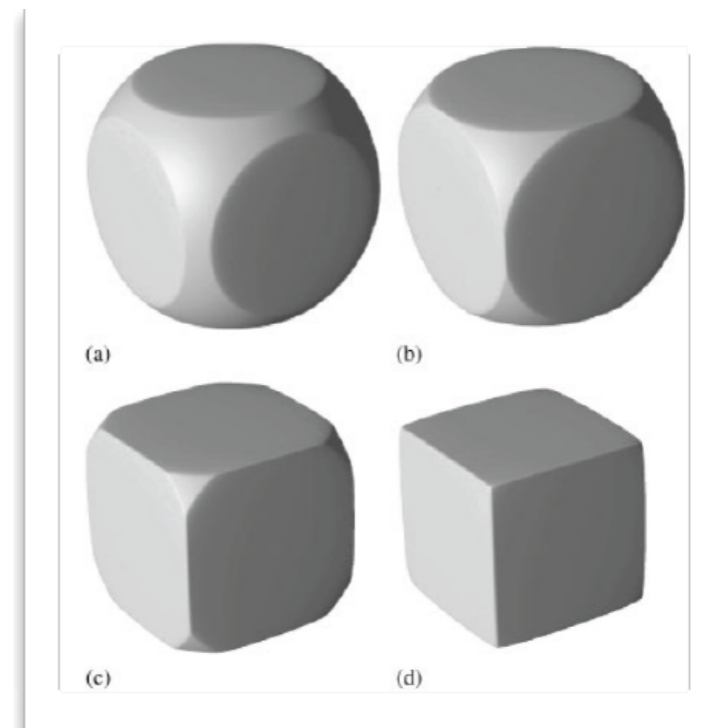
Clustering (using spheres)



Polyhedra



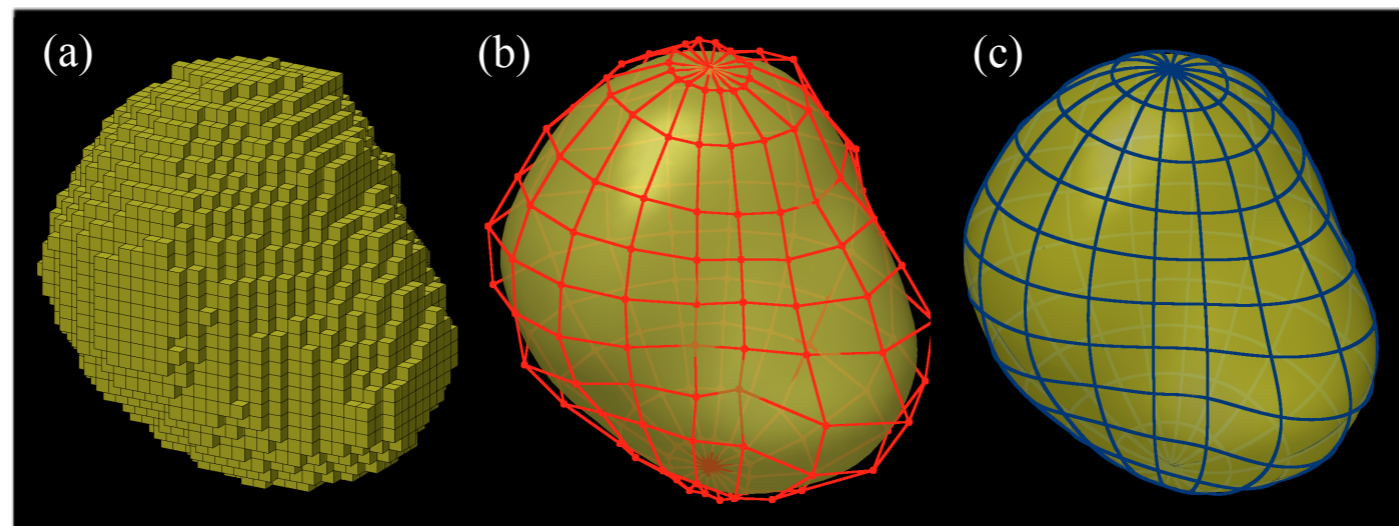
Spheropolyhedra



Potential Particles

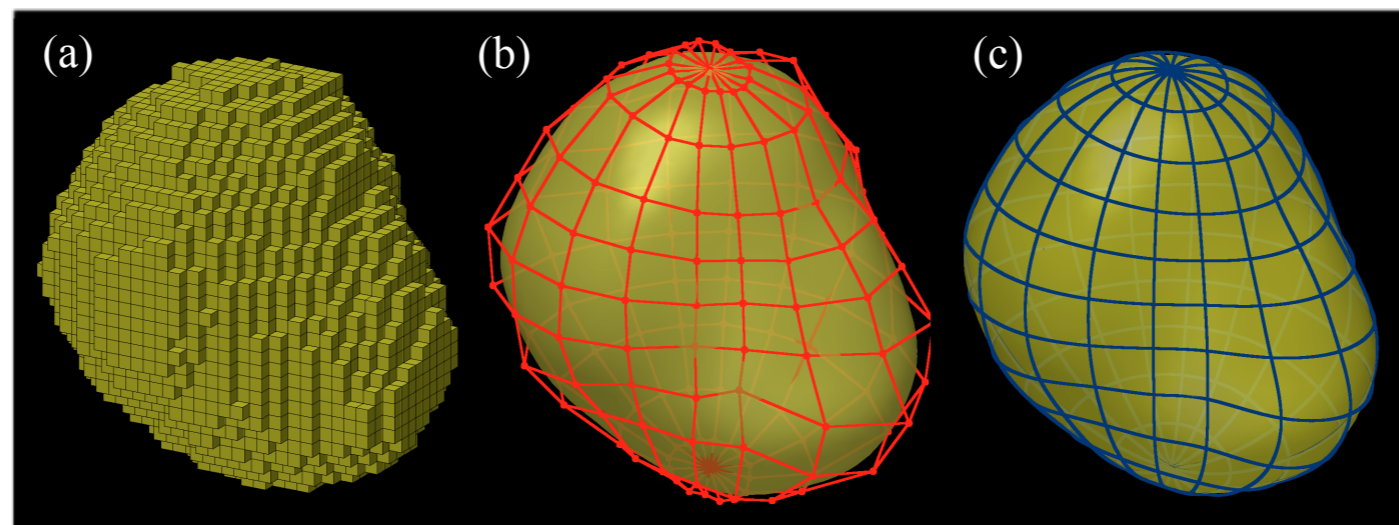
Granular Element Method

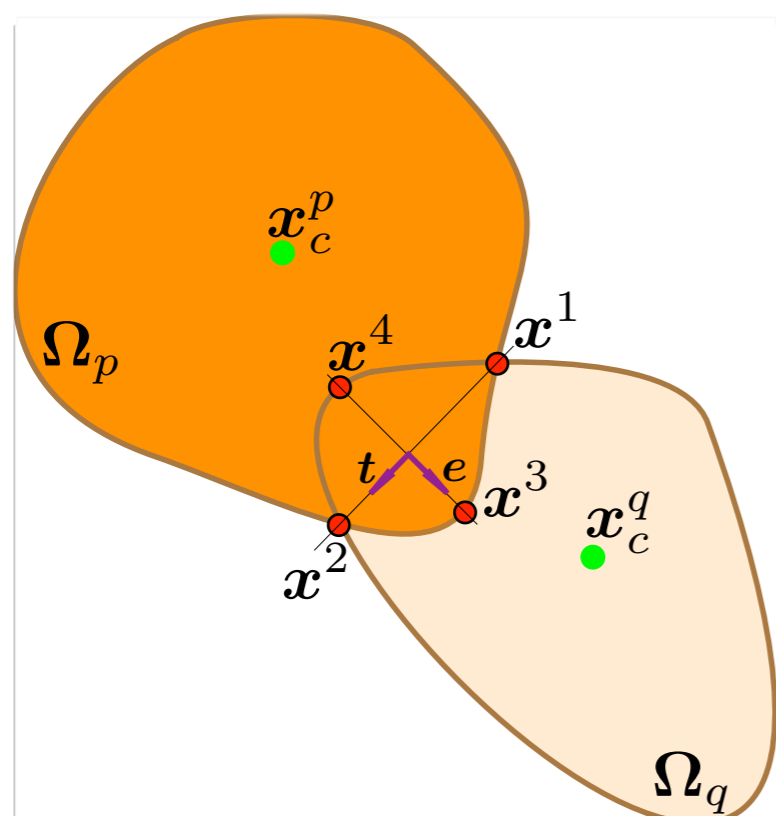
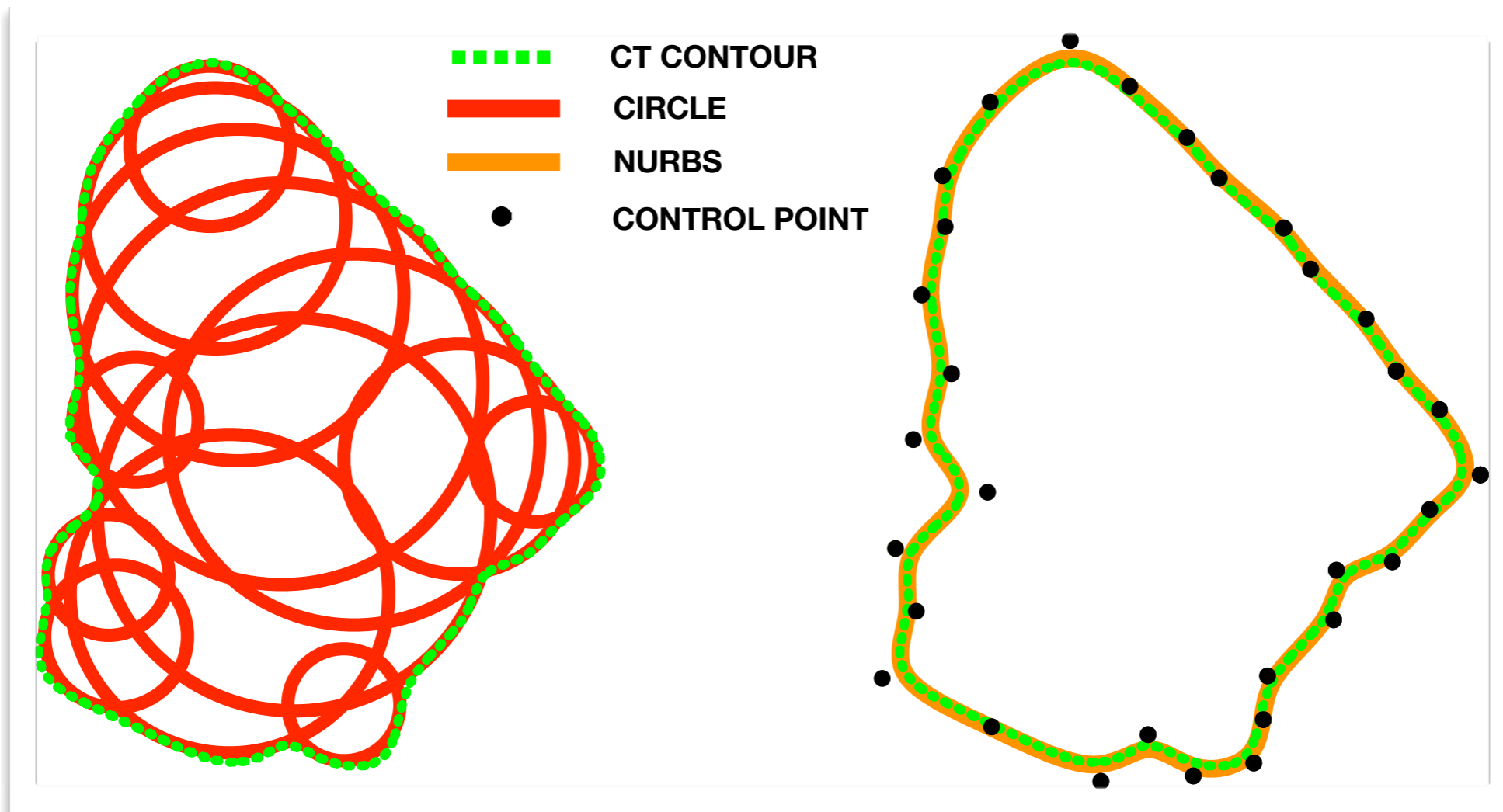
- A new discrete element method that has the ability to represent complicated grain geometries
- Uses parametric curves and surfaces
- Brings free-form computer-aided graphics design technology to full force for the realistic simulation of granular materials



Features of GEM

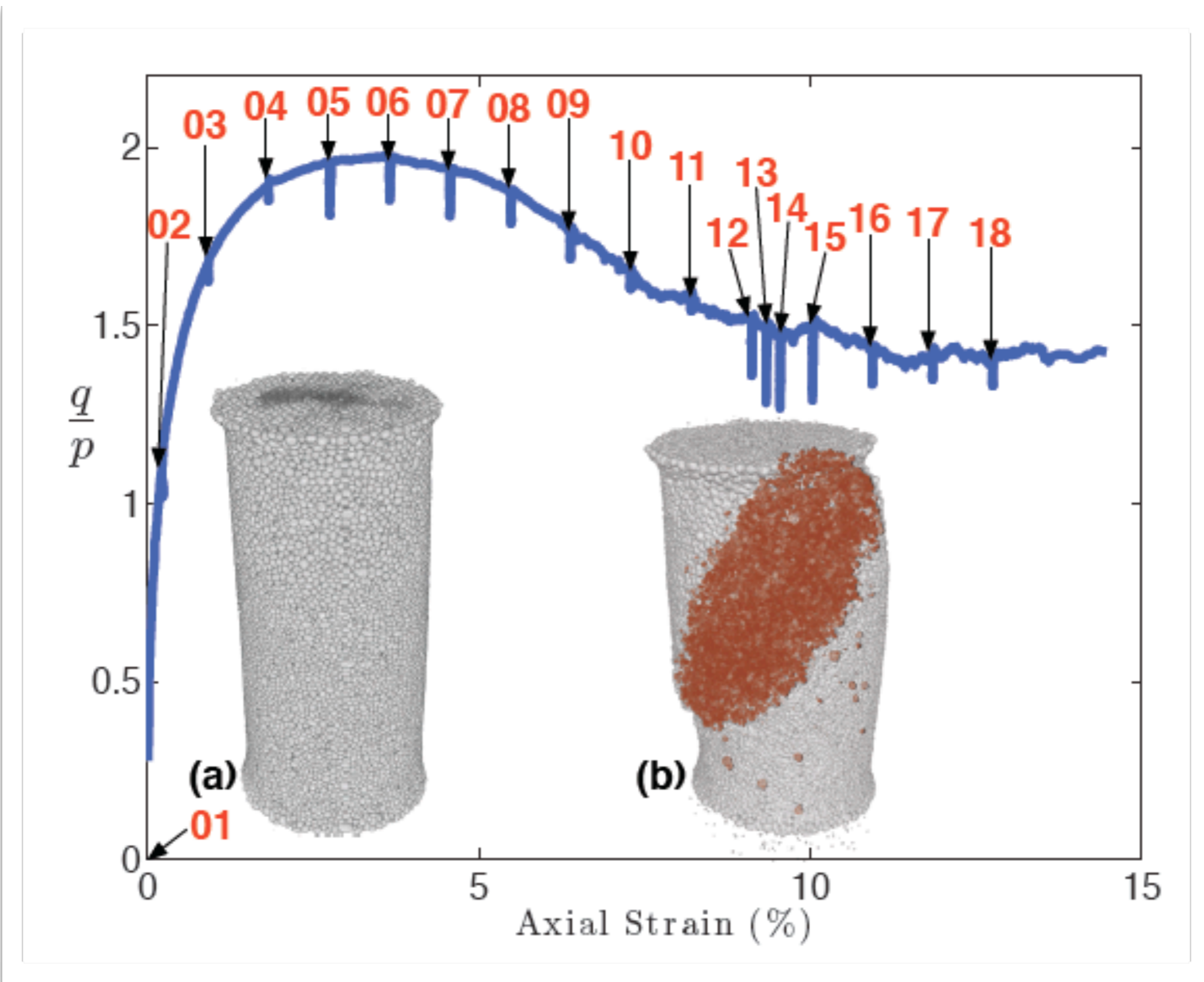
- Captures particle morphology: sphericity & roundness
- Can seamlessly go from binary images (XRCT) to model
- Can perform calculations with real shapes
- Accurately predicts macroscopic response
- Retains the simplicity of conventional DEM



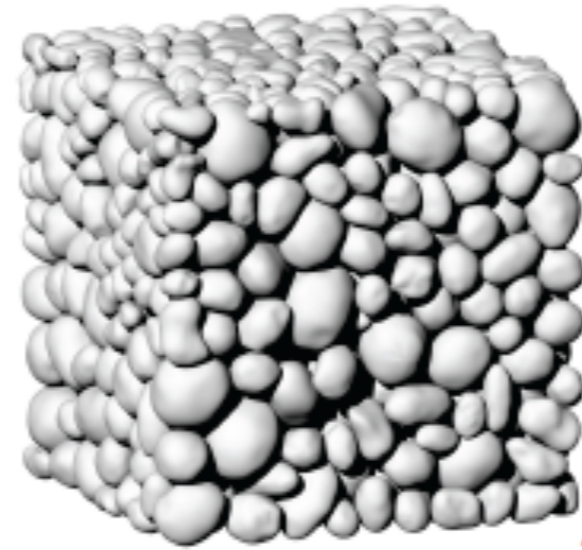
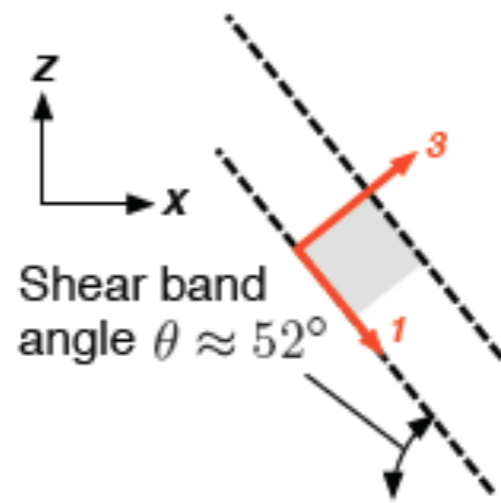
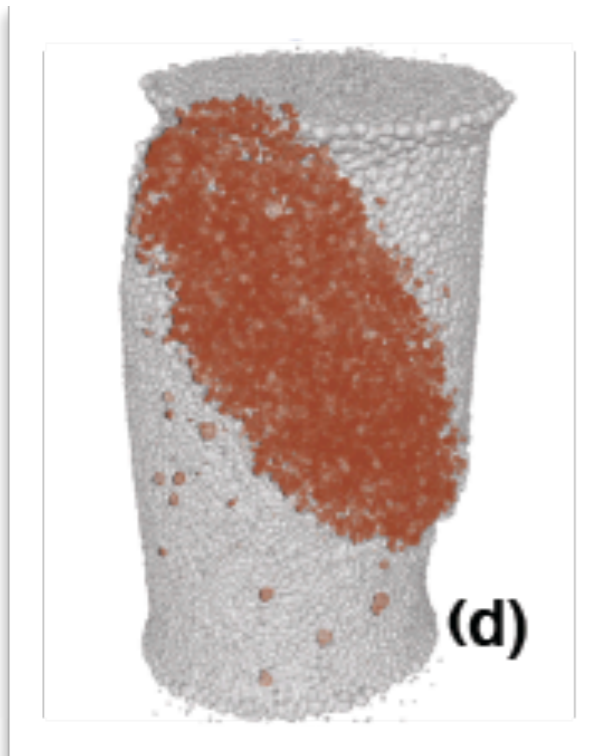


$$\begin{aligned}
 m a_i + C v_i &= F_i \\
 I \alpha + \bar{C} \omega &= M
 \end{aligned}$$

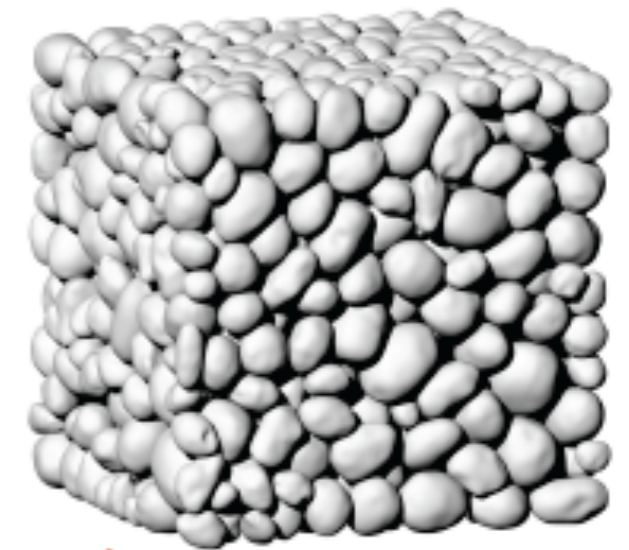
forces and moments depend
on particle morphology



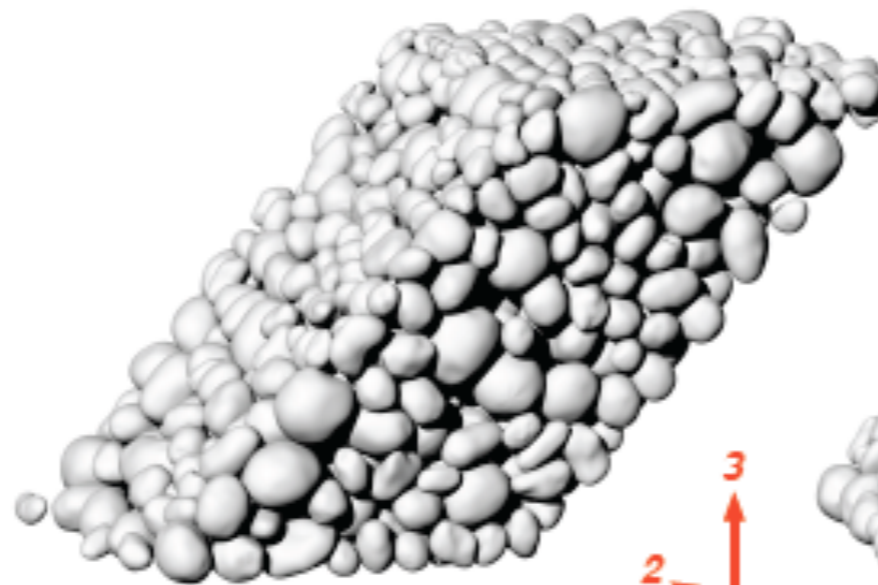
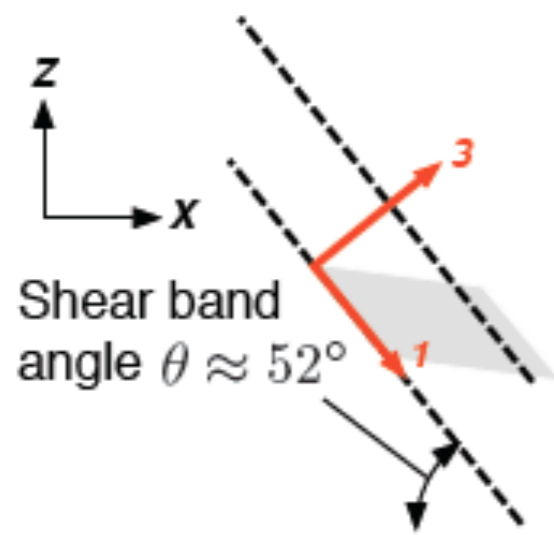
Experimental data: stress-strain (macro) & grain kinematics (micro)



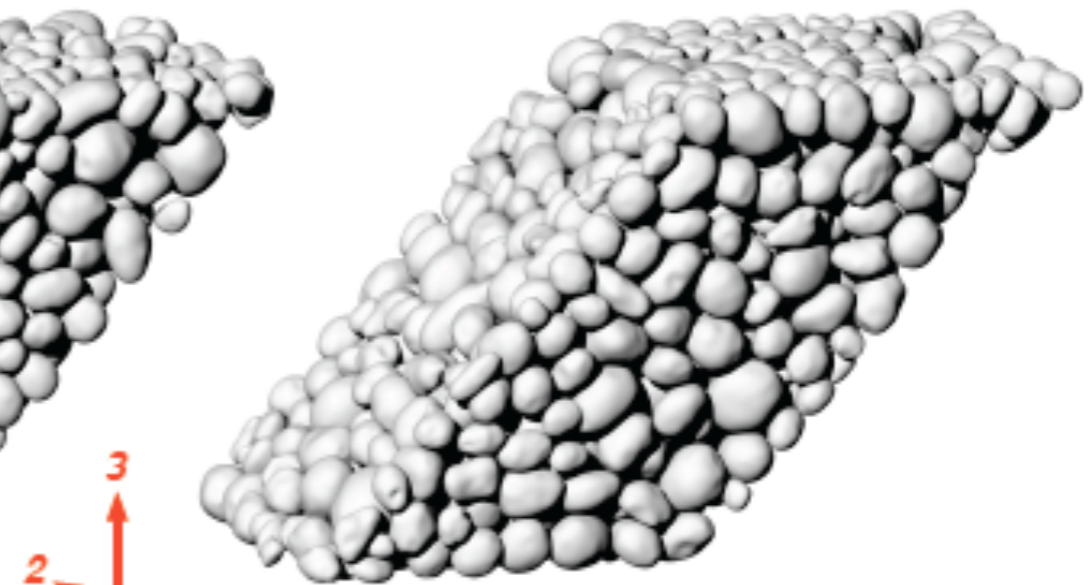
GEM Unit Cell 1



GEM Unit Cell 2

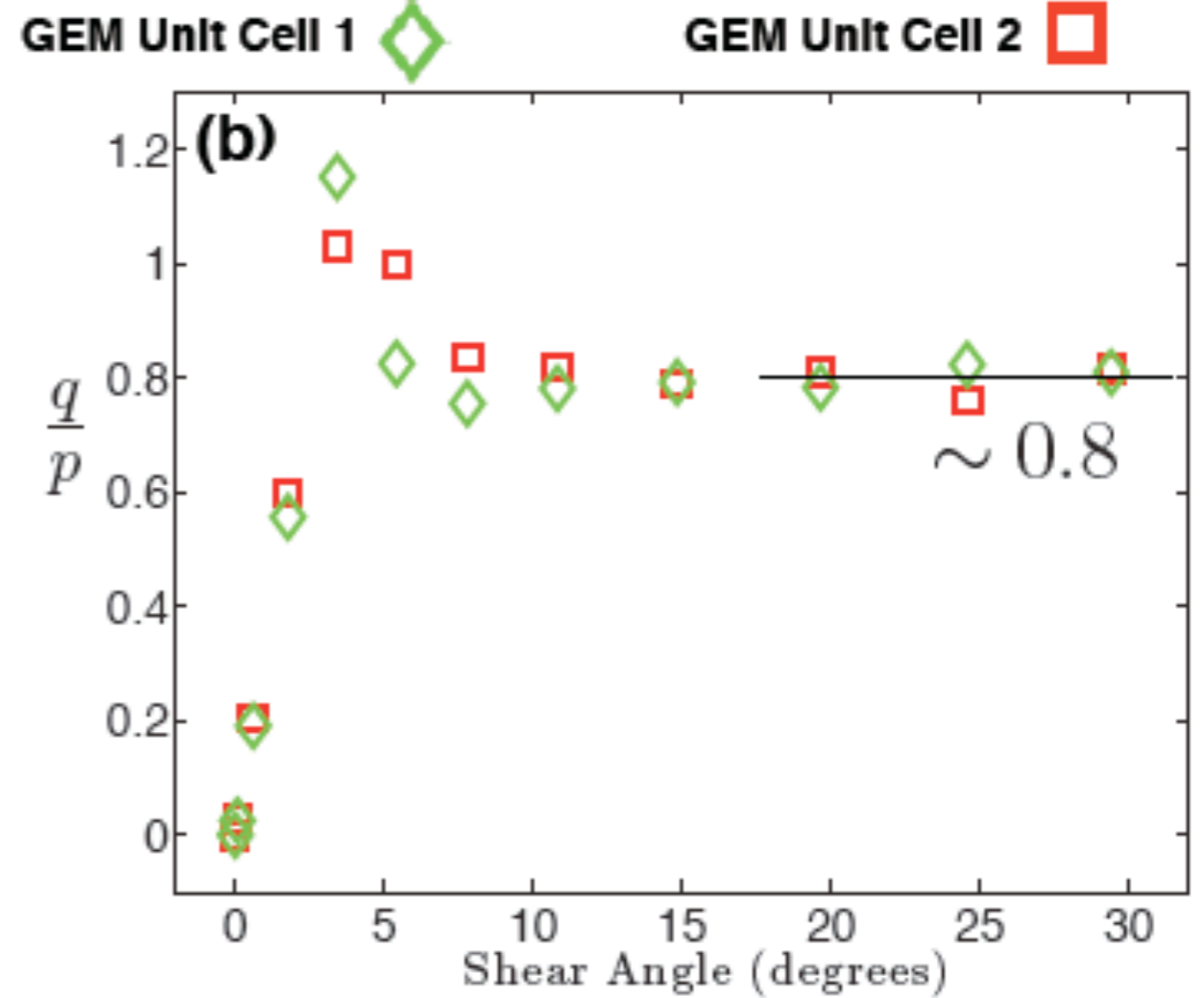
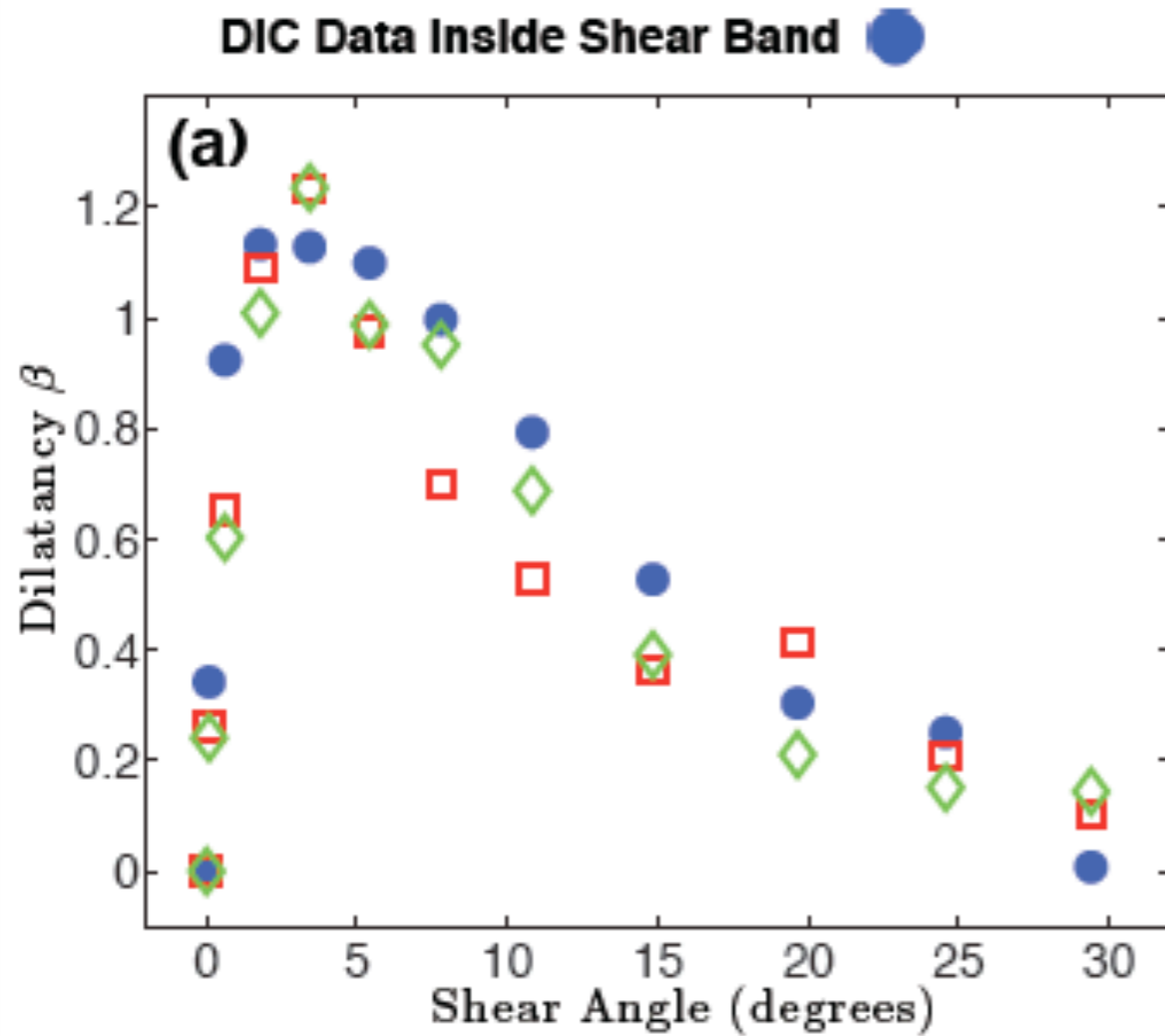


GEM Unit Cell 1



GEM Unit Cell 2

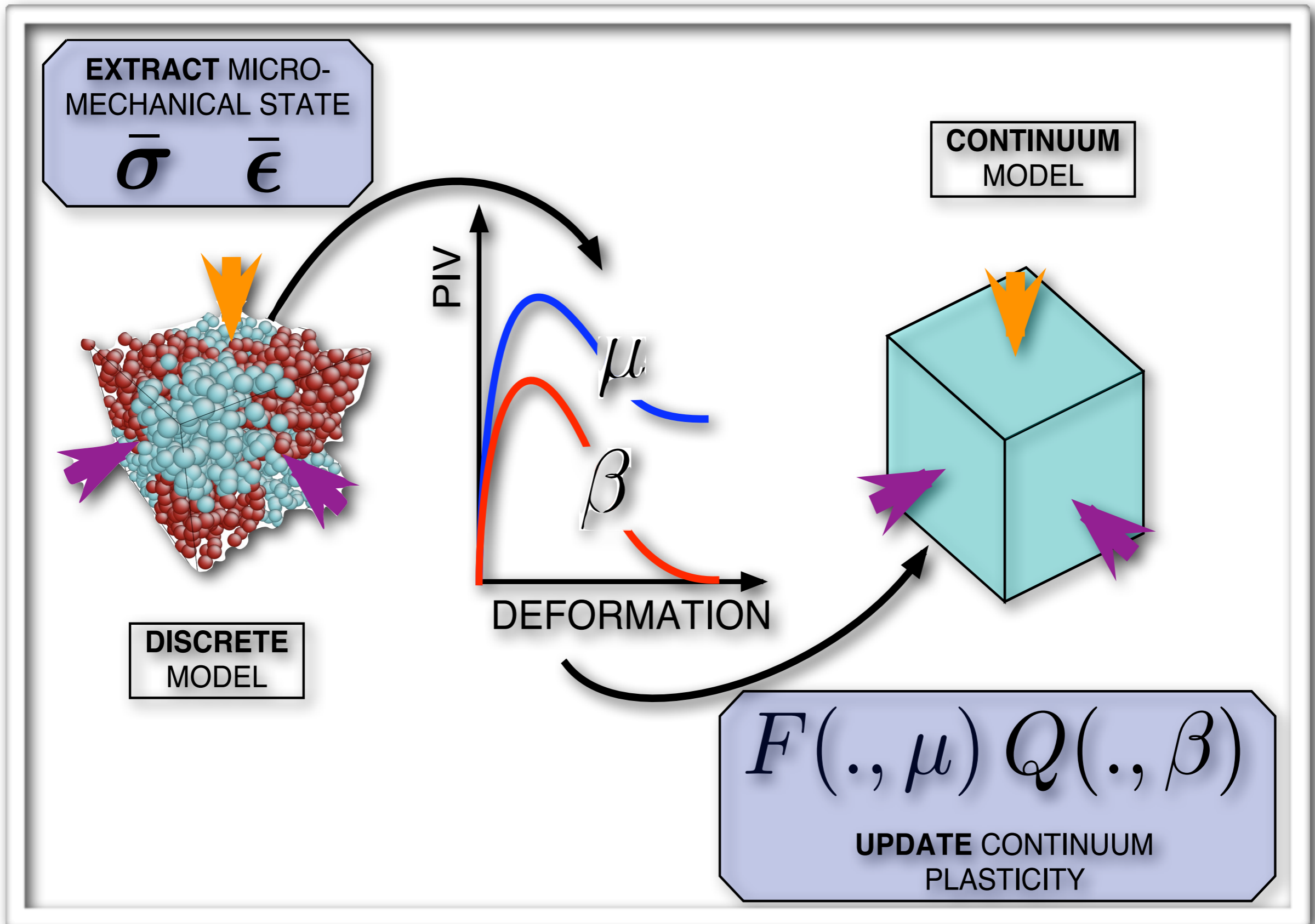
Simple shear numerical experiments



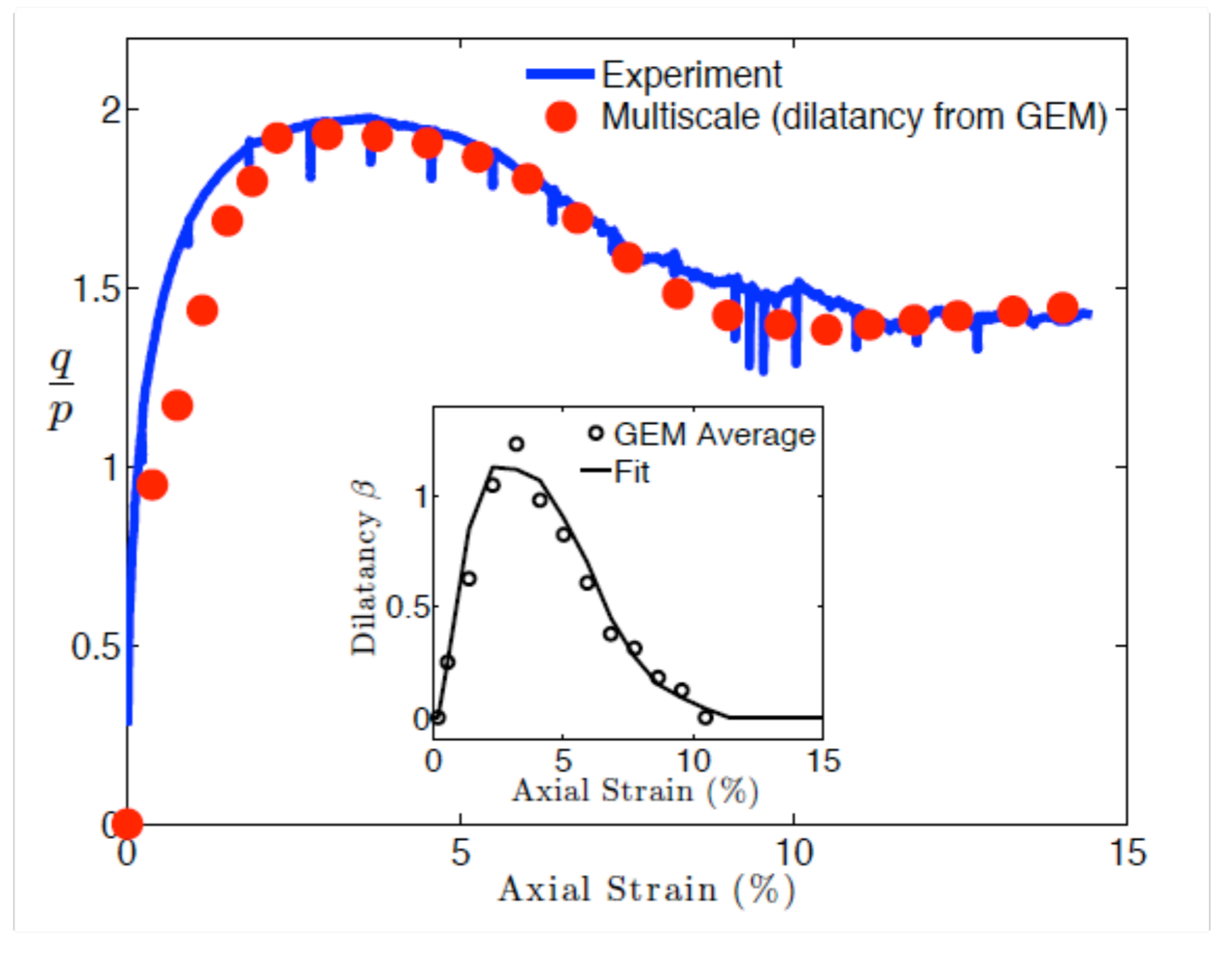
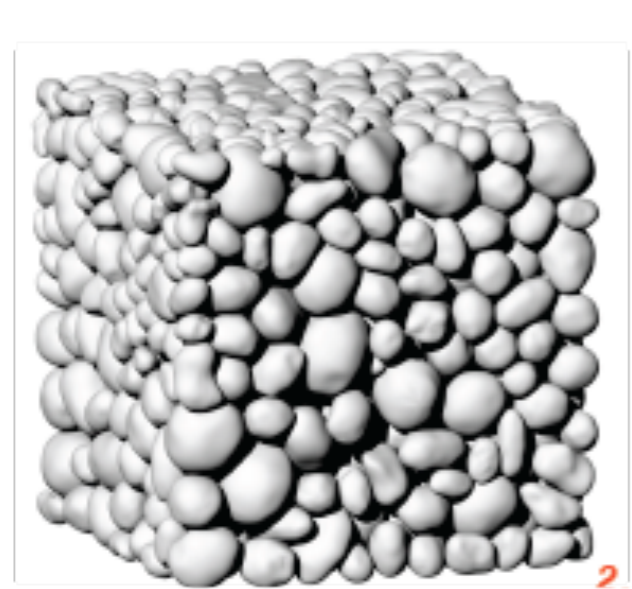
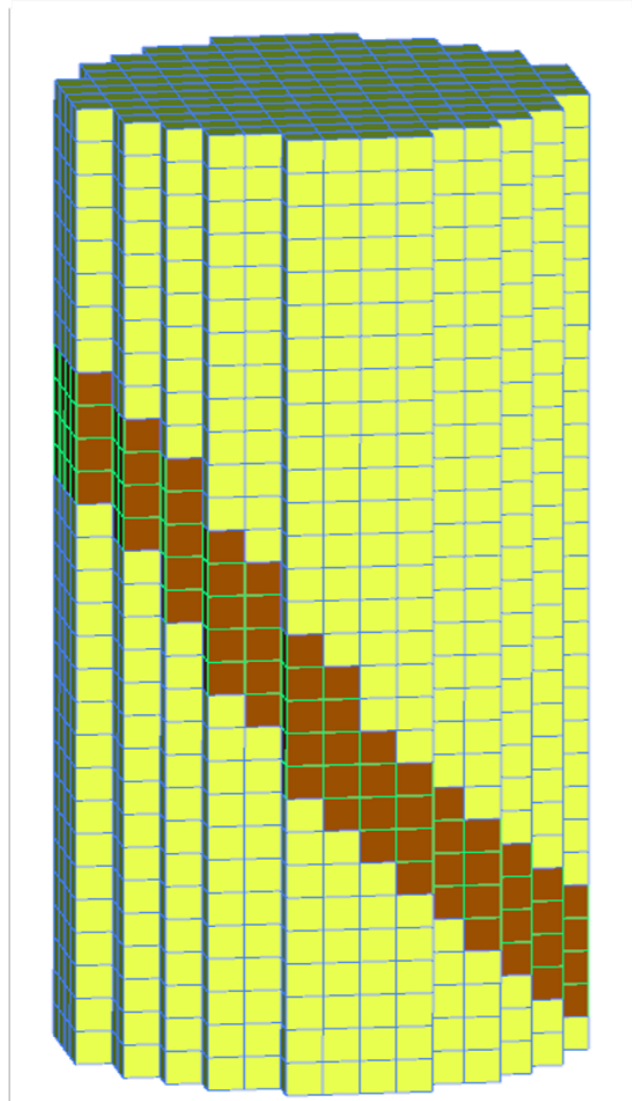
$$F(p, q, \mu) = q + \mu p = 0$$

$$Q(p, q, \beta) = q + \beta p - \bar{c} = 0$$

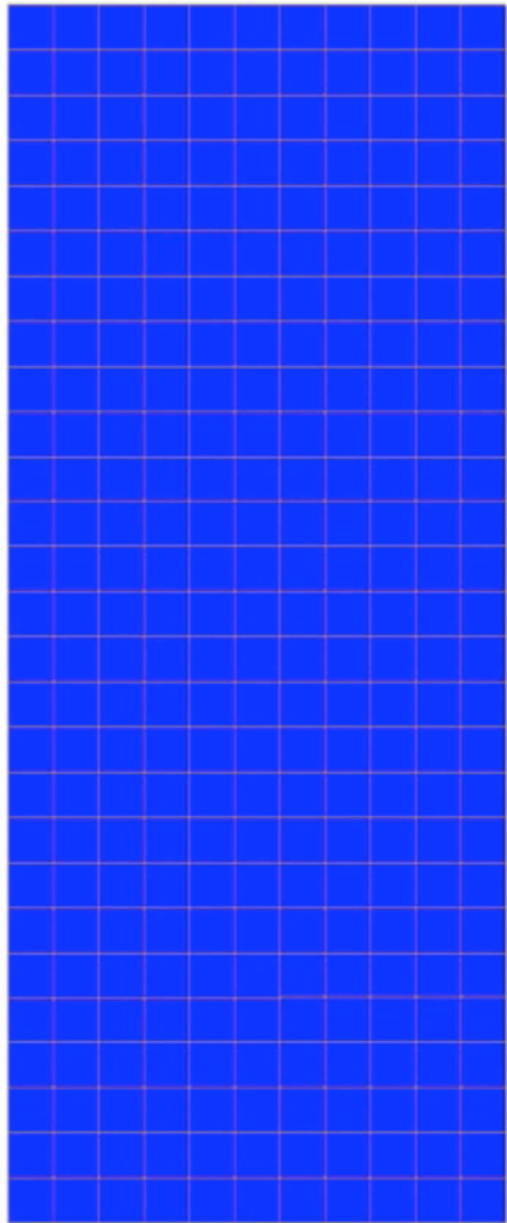
Computation of plastic parameters from DEM (micro) model



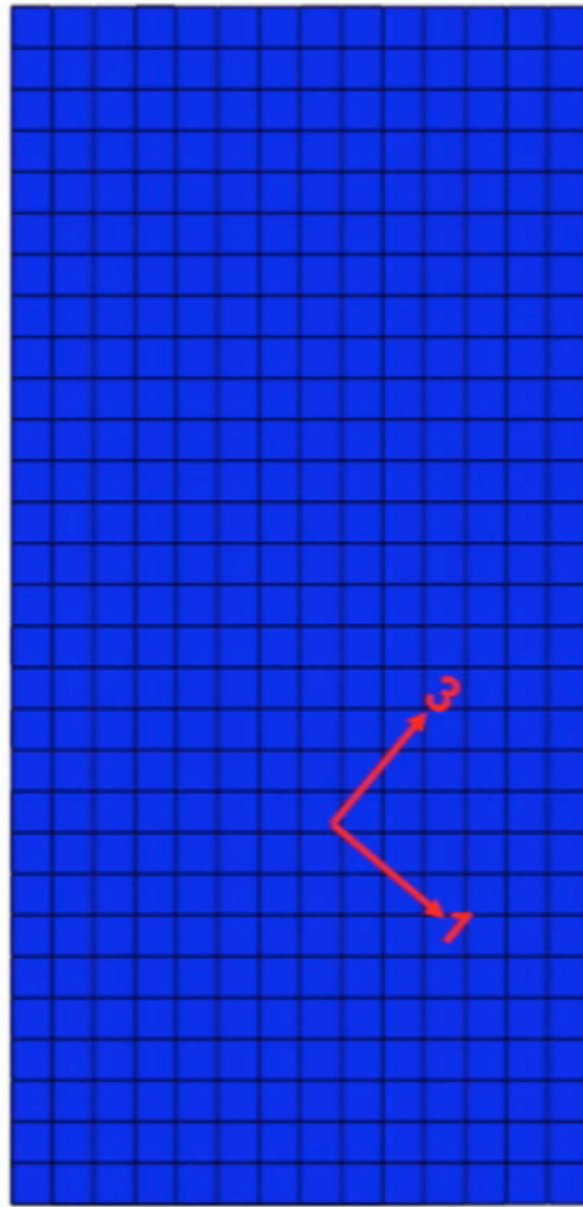
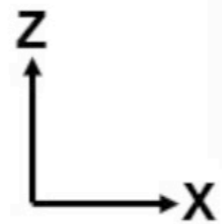
Hierarchical multiscale scheme



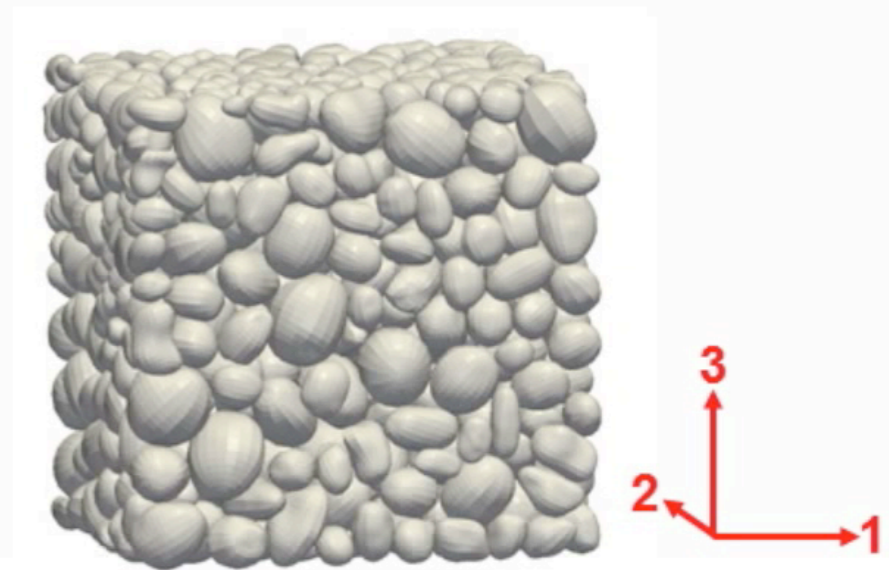
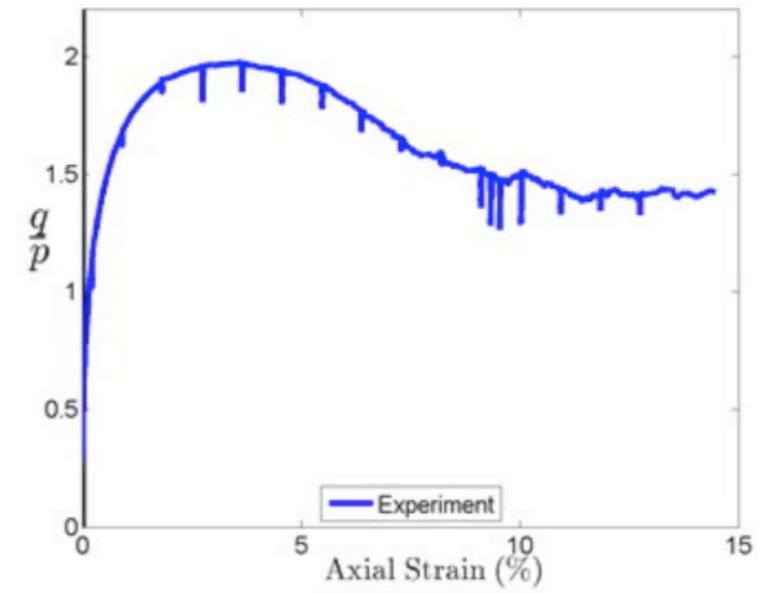
Main multiscale results



DIC



MULTISCALE

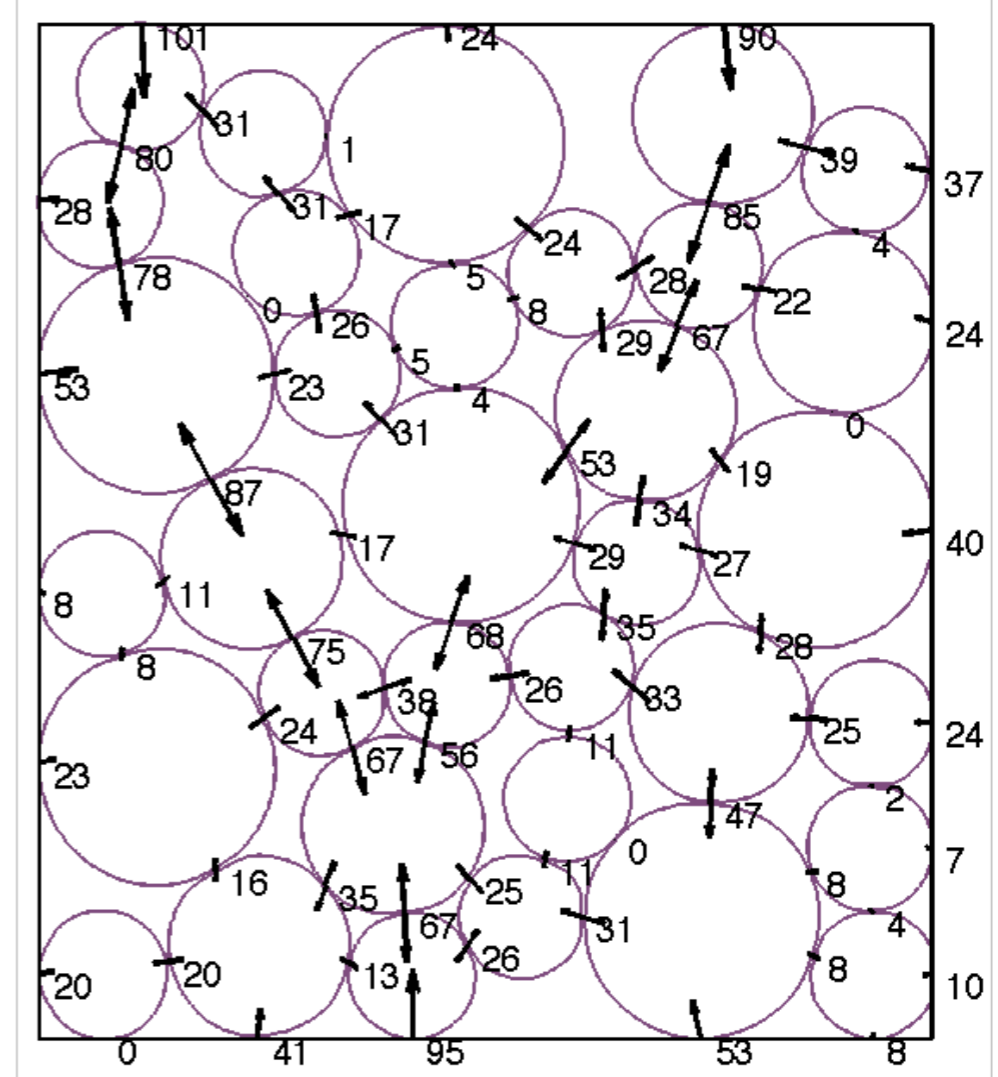
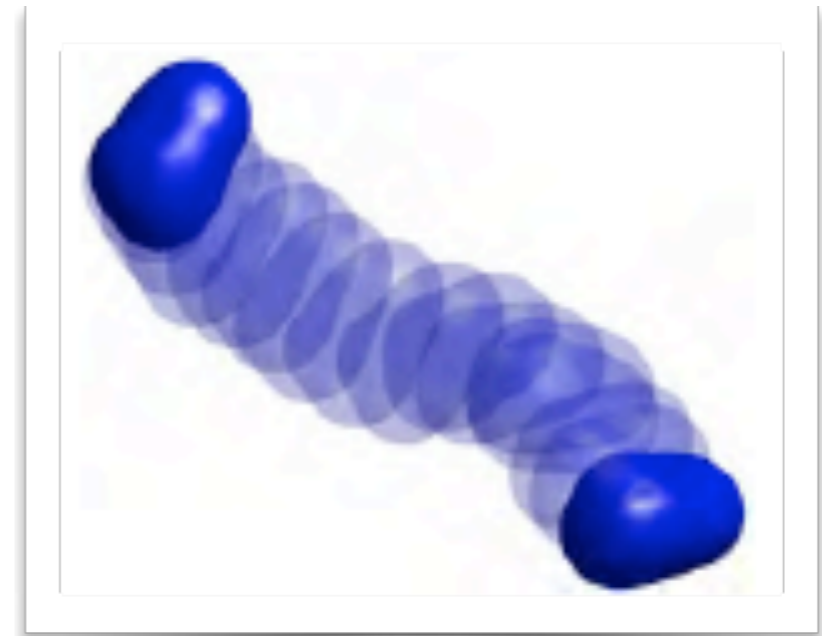


GEM UNIT CELL

Main multiscale results

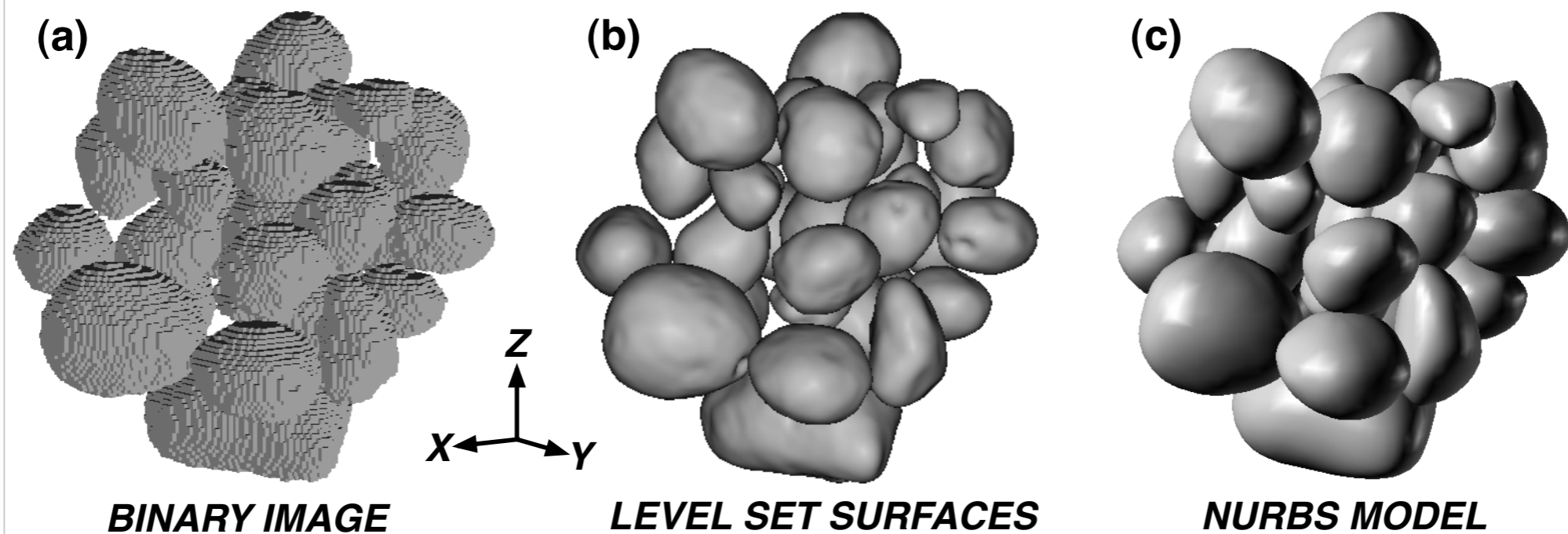
Closure 1/3

- We can now measure & compute granular BEHAVIOR: kinematics+forces



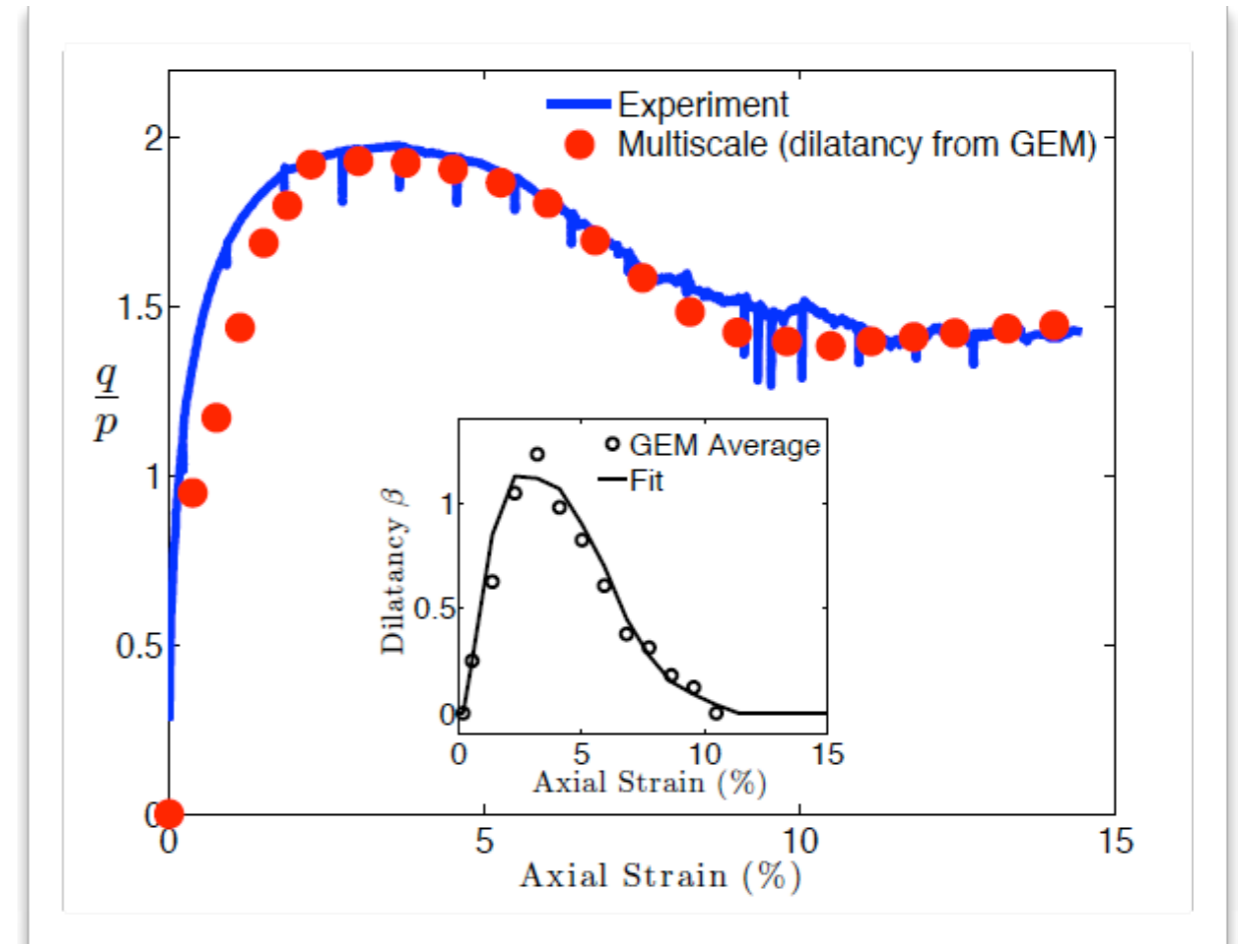
Closure 2/3

- Coupling between imaging & computational power is making progress real



Closure 3/3

- First time EVER a multiscale model has captured accurately macro behavior of REAL granular materials!



geomechanics.caltech.edu

@jandrade79